

CFS50 Motor Feedback Systems

High performance in the proven mechanical design



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Product description

Motor feedback systems of the CFS50 product family are used worldwide in a large variety of applications and environ-

ments. Incremental signals with resolutions of up to 65,536 lines per revolution and commutation signals are available.

At a glance

- Output driver for incremental and commutation signals as per EIA 422
- Resolution of up to 65,536 lines per revolution
- Commutation signals up to 32 pole pairs
- Temperature range from -20 °C to +115 °C
- Various mechanical interfaces

Your benefit

- High level of flexibility due to mechanics already proven in other motor feedback systems
- Time-saving due to electrical zero
 adjustment
- High level of compatibility thanks to standard interface

CE

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Detailed technical data

Performance

Number of lines per revolution	1000, 1024, 2000, 2048, 4000, 4096, other number of lines on request	
Commutation signals	See diagram on page 8, other commutations on request	
Max. output frequency	800 kHz	
Measuring step	90° electric/number of lines	
Reference signal		
Number	1	
Position	90° electr., logic operation with A and B	

Interfaces

Output driver	TTL/RS422
Output signal sequence	See pulse time diagram on page 8
Signal tolerance tx1 tx4 max. at 300 kHz	1.5 x ¼ T

Electrical data

Supply voltage	5 V ± 10 %
Max. operating current	60 mA (without load)

Mechanical data

Dimensions	See dimensional drawing
Mass	0.1 kg
Moment of inertia to the motor	10 gcm ²
Operating speed	12 000 rpm ⁻¹
Working speed	6000 rpm ⁻¹
Max. angular acceleration	0.2 x 10 ⁵ 1/s ²
Operating torque	0.2 Ncm
Start-up torque	0.4 Ncm
Permissible shaft movement	
Static	Axial ± 0.75 mm Radial ± 0.5 mm
Dynamic	Axial ± 0.2 mm Radial ± 0.1 mm
Angular motion, perpendicular to the rotational axis	
Static	± 0.005 mm/mm
Dynamic	0.0025 mm/mm
Lifetime of ball learnings	3.6 x 10 ⁹ revolutions

Ambient data

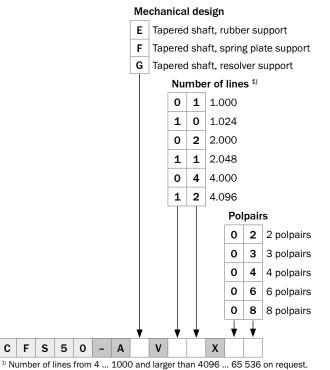
Working temperature range	-20 °C +115 °C
Storage temperature range (without packaging)	-40 °C +125 °C
Permissible relative air humidity ¹⁾	90 %
Resistance	
To shocks as per EN 60068-2-27	100 g/10 ms
To vibration as per EN 60068-2-6	20 g/10 2000 Hz
EMC ²⁾	As per EN 61000-6-2 and EN 61000-6-3
Protection class as per IEC 60529	IP 40

 $^{\mbox{\tiny 1)}}$ Condensation not permissible.

²⁾ EMC as per specified standards is ensured if the motor feedback system is fitted in a conductive housing connected to the central grounding point of the motor controller via cable shielding. The GND-(OV) connection of the supply voltage is also grounded there. If other shielding concepts are used, the user must perform his own tests.

Ordering information

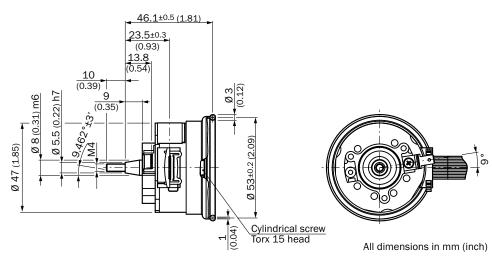
Ordering code



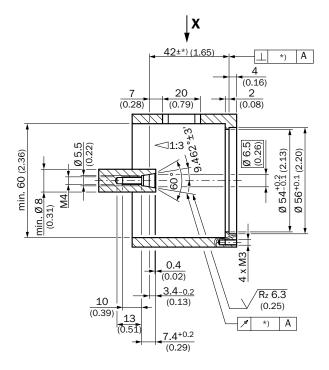
²⁾ Polpairs 5, 7 and from larger than 8 ... 32 on request.

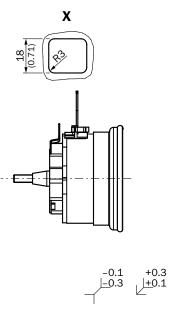
Dimensional drawings

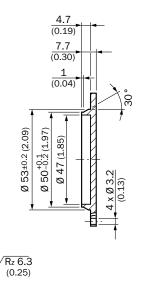
CFS50-AEVxxXx



Proposed customer fitting for CFS50-AEVxxXx



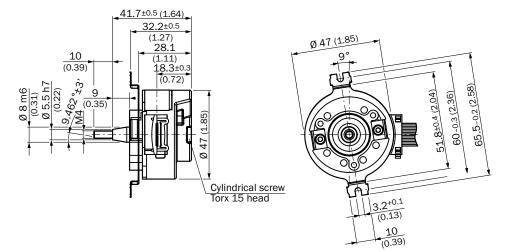




*) Size of tolerance reduce the allowed movement of the shaft, see data sheet.

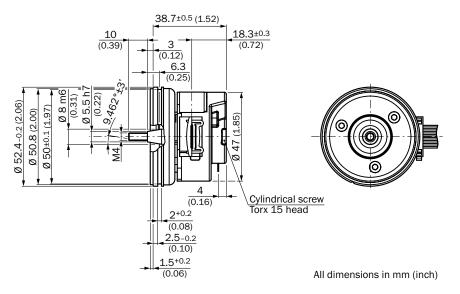
All dimensions in mm (inch)

CFS50-AFVxxXxx

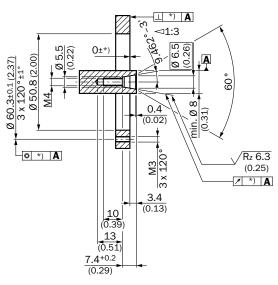


All dimensions in mm (inch)

CFS50-AGVxxXxx



Proposed customer fitting for CFS50-AGVxxXxx



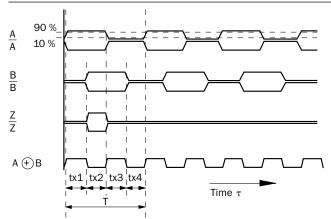
*) Size of tolerance reduce the allowed movement of the shaft, see data sheet.

All dimensions in mm (inch)

PIN and wire assignment

PIN	Color	Signal
1	Blue	Ground connection (GND)
2	Red	Supply voltage 5 V ± 10 $\%$ (U_s)
3	Yellow	Reference signal inverted (Z)
4	Purple	Reference signal (Z)
5	Brown	Increment signal inverted (Ā)
6	White	Increment signal (A)
7	Black	Increment signal inverted (B)
8	Pink	Increment signal (B)
9	White/Red	Commutation signal inverted (\overline{T})
10	White/Gray	Commutation signal (T)
11	White/Blue	Commutation signal inverted (\overline{S})
12	White/Yellow	Commutation signal (S)
13	White/Pink	Commutation signal inverted (R)
14	White/Green	Commutation signal (R)
15	Gray	Electronic setting of the commutation signals (SET0)

Incremental track



At constant rotational speed with regard to the input shaft and rotation in clockwise direction.

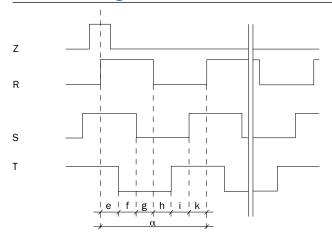
By connecting the two signals A and B, an output signal arises whose period durations tx1 ... tx4 have varying lengths.

The differences are determined:

- by the pulse/pause ratio tolerance of the individual channels
- by the tolerance in the 90 $^\circ$ phase shift between A and B
- by the frequency

The times $tx1 \dots tx4$ ideally have to amount to 1/4 of the particular period duration T. The typical output frequency of the encoder is defined so that the max. time tx is smaller than $1.5 \times T/4$.

Pulse time diagram



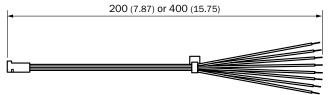
Polpairs	Number of poles	e, f, g, h, i, k	α
2	4	30°	180°
3	6	20°	120°
4	8	15°	90°
6	12	10°	60°
8	16	7.5°	45°

The angle information is related to a mechanical shaft rotation. Flank precision of the signals R, S, T ±1°.

Accessories

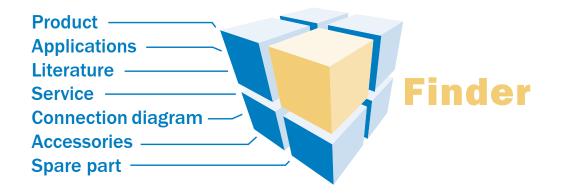
Plug connectors and cables

Description	Cable length	Model name	Part no.
Braid set, straight, 15-core, 15 x 0.24 mm ²	200 mm	DOL-OJ15-GOM2XBA	2051662
	400 mm	DOL-OJ15-GOM4XBA	2061864



All dimensions in mm (inch)

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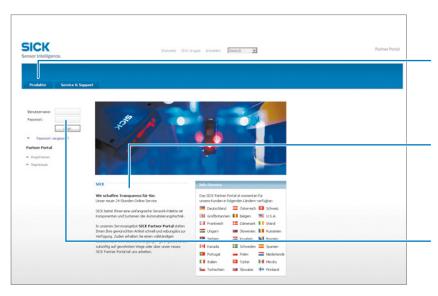
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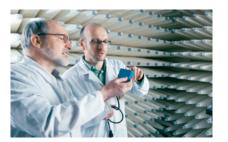
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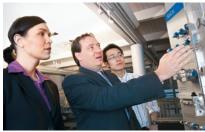
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