

AC Servo System

1S Series



Optimized installation and setup Increased machine productivity Global availability and global conformance



State of the art servo technology applied to general purpose

Improved machine design. Increased machine productivity

Designed to meet the machine requirements, the 1S servo technology optimizes the full cycle, through the machine design, installation and commissioning tasks and finally to the maintenance once in production. In addition to the traditional motion solution, the 1S servo offers high resolution multi-turn encoder without battery backup, safety network built-in and improved loop control allowing accurate and higher machine productivity.

Optimized installation and commissioning tasks

Cabinet size reduction:

· Compact servo drive with same height throughout the whole power range



Servo features

- · Power range from 100 W to 3 kW -100/200/400V
- · 23 bit high resolution encoder
- Battery-free absolute multi-turn encoder
- · Improved loop control for low overshoot and quick settling time
- · Safety function built-in:
 - · Hardwired Safe Torque Off: EN ISO 13849-1(Cat.3 PLe), EN61508(SIL3), EN62061(SIL3), EN61800-5-2(STO)
 - · Safety over EtherCAT(FSoE): EN ISO 13849-1(Cat.3 PLd), EN61508(SIL2), EN62061(SIL2), EN61800-5-2(STO)



- · Pluggable connectors in all connectors for easy pre-wiring and system maintenance
- · Direct wiring of I/O signals. No need for terminal block units



Embedded relay for direct motor brake control





50% setup time reduction*



Servo sizing

- Servo sizing tool for the entire machine
- Graphical environment of the kinematic chain
- Electronic CAM import from Sysmac Studio



System configuration

- NJ project auto-builder from servo sizing file
- Quick setup wizard for key parameters
- Parameters transfer in less than 400 ms



Gain tuning & test run



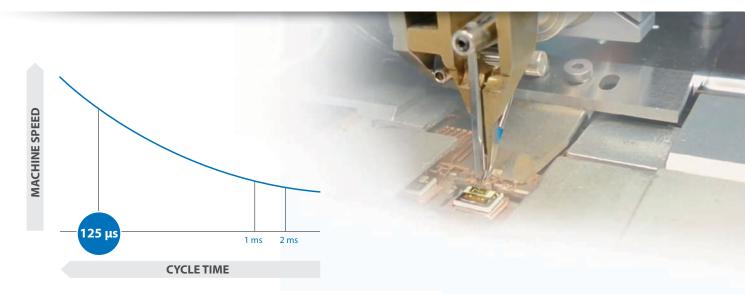
- "Best effort" feature for quick stabilization time
- · Easy tuning with intelligent gain search in less than 2 minutes
- · Wizard for tuning, test run & monitoring
- Advanced tuning simulation to reduce testing effort and prevent machine damage

Save 40% *

Save 60% *

Save 50% *

Totally integrated, totally in control



HIGHER PRODUCTIVITY

125 µs system cycle

- · Faster machine speed keeping same
- · Accurate profile generation in the controller
- · The 23 bit high resolution encoder in combination with the improved loop control provide an accurate following profile



INTEGRATED SAFETY

Safety control via EtherCAT

- · Simplified safety installation
- · Reduction of safety devices
- · Safety function built-in: Fail Safe over EtherCAT (FSoE) Safe Torque Off
- · Safety approval: EN ISO 13849-1(Cat.3 PLd), EN61508(SIL2), EN62061(SIL2), EN61800-5-2(STO)
- · Troubleshooter integrated with Sysmac Studio



TOTALLY IN CONTROL



Sysmac Studio

- · Simplified servo setup: Direct use of servo sizing calculation
- · Open standard IEC 61131-3 programming
- · Standard PLCopen Function Blocks for Motion and Safety



- · Sysmac Library for fast engineering and optimized machine availability
 - Application libraries
 - Optimized productivity
 - · Predictive maintenance
 - Reduced downtime





Sysmac Automation Platform

The integrated platform

Sysmac is an integrated automation platform dedicated to providing complete control and management of your automation plant. At the core of this platform, the Machine Controller series offers synchronous control of all machine devices and advanced functionality such as motion, robotics and database connectivity. This multidisciplinary concept allows you to simplify solution architecture, reduce programming and optimize productivity.

Controller

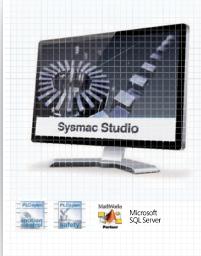
Motion

EtherNet/IP



Software

EtherCAT.



Sysmac Studio, the integrated software

- · One single tool for logic sequence, motion, safety, robotics, vision and HMI
- Fully compliant with open standard IEC 61131-3
- · PLCopen Function Blocks for Motion and Safety
- · Supports Ladder, Structured Text and In-Line ST programming with a rich instruction set
- CAM editor for easy programming of complex motion profiles
- · Database Connectivity Function Block library

Sysmac Library



The Sysmac Library is a collection of software functional components that can be used in programs for the NJ/NX Machine Automation Controllers. Please download it from following URL and install to Sysmac Studio. http://www.ia.omron.com/sysmac_library/

• EtherCAT 1S Series Library: The EtherCAT 1S Series Library is used to initialize the absolute encoder, back up and restore the parameters for an OMRON 1S-series Servo Drive with built-in EtherCAT communications. You can use this library to reduce manpower of programming when implementing the processing for a Servo Drive.

Sysmac servo family

Machine Controller

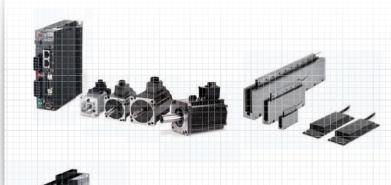




NJ/NX series

- Logic sequence, Motion, Safety, Robotics and Database connection functionality
- Scalable motion control: CPUs from 2 up to 256 axes
- IEC 61131-3 controller
- PLCopen Function Blocks for Motion Control and Safety
- Advanced motion with Robotics functionality
- · Built-in EtherCAT and EtherNet/IP ports

Motion





- · Servo drive for rotary or linear motors
- · Rotary motor: Up to 15 kW
- · Iron-core and Ironless linear motor models: Up to 2100 N peak force
- · Safety function: STO
- · Full closed loop control



- · Servo drive for rotary motors
- · Up to 3 kW
- · Safety function: STO

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R88M-1□/R88D-1SN□-ECT

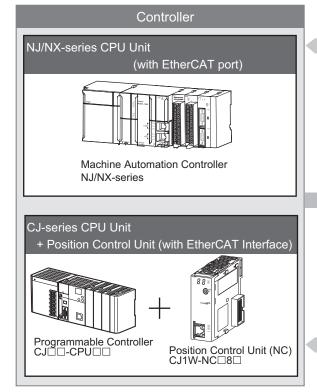
Best Machine Architecture

- Simple installation and wiring contributes to board design efficiency
- EtherCAT Communications Cycle of 125 μs
- Achievement of Safety on EtherCAT Network
- Supports two-degree-of-freedom control
- Battery-free system reduces maintenance and space
- Comes equipped with a 23-bit ABS encoder





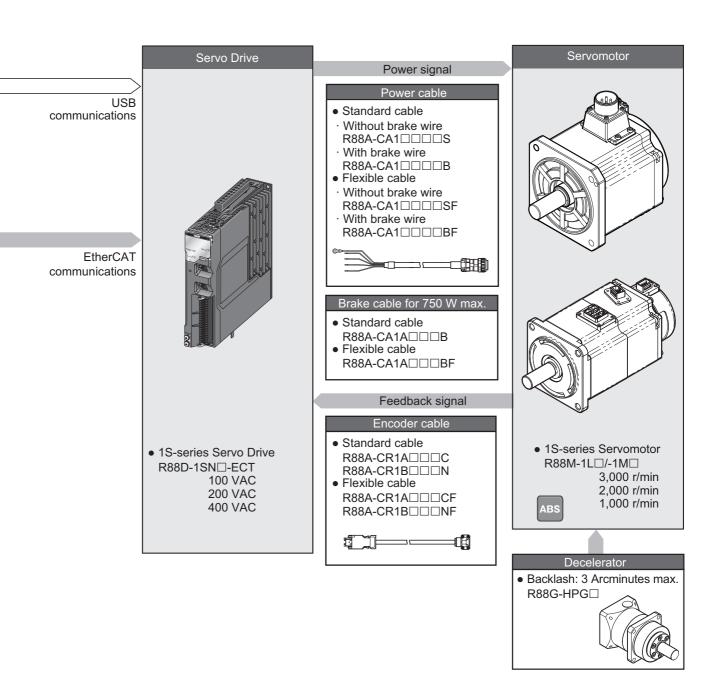
System Configuration







*You cannot use the CX-One to make the settings of 1S-series Servo Drives. Obtain the Sysmac Studio.



AC Servo Drives with Built-in EtherCAT Communications [1S-series]

R88D-1SN□-ECT

Contents

- Ordering Information
- Specifications
- EtherCAT Communication Specifications
- Version Information
- Names and Functions
- Dimensions



Ordering Information

Refer to the Ordering Information.

Specifications

General Specifications

	Item		Specifications	
Operating ambient temperature and humidity		nd humidity	0 to 55°C, 90% max. (with no condensation)	
Storage ambient temperature and humidity		humidity	-20 to 65°C, 90% max. (with no condensation)	
Operating and storage atmosphere		е	No corrosive gases	
Operating alti	tude		1,000 m max.	
Vibration resis	stance		10 to 60 Hz and at an acceleration of 5.88 m/s² or less (Not to be run continuously at the resonance frequency)	
Insulation res	istance		Between power supply terminals/power terminals and PE terminals: 0.5 M Ω min. (at 500 VDC)	
Dielectric stre	Dielectric strength		Between power supply terminals/power terminals and PE terminals: 1,500 VAC for 1 min (at 50/60 Hz)	
Protective str	ucture		IP20 (Built into IP54 panel)	
		EMC Directive	EN 61800-3 second environment, C3 category (EN61326-3-1; Functional Safety)	
	EU Directives	Low Voltage Directive	EN 61800-5-1	
International		Machinery Directive	EN ISO 13849-1 (Cat.3), EN 61508, EN 62061, EN 61800-5-2	
standard	UL standards		UL 61800-5-1	
	CSA standards		CSA C22.2 No. 274	
	Korean Radio Regu	ulations (KC)	Compliant	
(RCM)			Compliant	

Note: The above items reflect individual evaluation testing. The results may differ under compound conditions.

The detail of Machinery Directive is as follows:

The STO function via safety input signals: EN ISO 13849-1 (Cat3 PLe), EN 61508 (SIL3), EN 62061 (SIL3), EN 61800-5-2 (STO)

The STO function via EtherCAT communications: EN ISO 13849-1 (Cat.3 PLd), EN 61508 (SIL2), EN 62061 (SIL2), EN 61800-5-2 (STO)

Precautions for Correct Use

Disconnect all connections to the Servo Drive before attempting a megger test (insulation resistance measurement) on a Servo Drive. Not doing so may result in the Servo Drive failure.

Do not perform a dielectric strength test on the Servo Drive. Internal elements may be damaged.

Characteristics

100-VAC Input Models

	Servo Drive model (R88I	D-)	1SN01L-ECT	1SN02L-ECT	1SN04L-ECT			
	Item		100 W	200 W	400 W			
	Main circuit	Power supply voltage	Single-phase 100 to 120 VAC (85 to 132 V) *1					
		Frequency	50/60 Hz (47.5 to 63 Hz) *1					
Input	Control circuit	Power supply voltage		24 VDC (21.6 to 26.4 V)				
	Rated input current	Single-phase	2.9	4.9	8.4			
	[A (rms)] (Main circuit power supply voltage: 120 VAC)	3-phase						
Output	Rated current [A (rms)] Maximum current [A (rms)]		1.5	2.5	4.8			
Output			4.7	8.4	14.7			
Maximu	m power loss at power convers	ion	10% (Load condition: rated output)					
Applical	ble Servomotor rated output [W	1	100	200	400			
3,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS			1M10030S	1M20030S	1M40030S			
Hold time at momentary power interruption (Main circuit power supply voltage: 100 VAC)		10 ms	(Load condition: rated outp	ut) * 2				
Weight	[kg]		1.2	1.5	1.9			

^{*1.} The values outside parentheses indicate the rated value, and the values inside parentheses indicate the range of acceptable variation.

^{*2.} The control power supply is not specified here as long as a DC power supply that meets the following conditions is used. Reinforced insulation or double insulation, and the output hold time of 10 ms or more.

200-VAC Input Models

Servo Drive model (R88D-)		1SN01H-ECT	1SN02H-ECT	1SN04H-ECT	1SN08H-ECT			
Item		100 W	200 W	400 W	750 W			
	Main circuit	Power supply voltage	Single-ph	nase and 3-phase 200	use and 3-phase 200 to 240 VAC (170 to 252 V) *1			
		Frequency		50/60 Hz (47.5 to 63 Hz) *1				
Input	Control circuit	Power supply voltage		24 VDC (21	6 to 26.4 V)			
	Rated current [A (rms)]	Single-phase	1.8	2.7	4.6	7.3		
	(Main circuit power supply voltage: 240 VAC)	3-phase	1.0	1.5	2.7	4.0		
Output	Rated current [A (rms)]		0.8	1.5	2.5	4.6		
Output Maximum current [A (rms)]		s)]	3.1	5.6	9.1	16.9		
Maximum power loss at power conversion		10% (Load condition: rated output)						
Applicab	ole Servomotor rated outpu	ıt [W]	100	200	400	750		
3,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS		1M10030T	1M20030T	1M40030T	1M75030T			
2,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS								
1,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS								
Hold time at momentary power interruption (Main circuit power supply voltage: 200 VAC)			10 ms (Load condition	on: rated output) *2				
Weight [kg]		1.2	1.2	1.5	2.0		

Servo Drive model (R88D-)		1SN10H-ECT	1SN15H-ECT	1SN20H-ECT	1SN30H-ECT	
	Item		1 kW	1.5 kW	2 kW	3 kW
	Main circuit	Power supply voltage	3-phase 200 to 240 VAC (170 to 252 V) *1	Single-phase and 3-phase 200 to 240 VAC (170 to 252 V) *1	3-phase 200 to 240 VAC (170 to 252 *1	
Input		Frequency		50/60 Hz (47.5	5 to 63 Hz) * 1	
iliput	Control circuit	Power supply voltage		24 VDC (21	.6 to 26.4 V)	
	Rated current [A (rms)]	Single-phase		15.7		
	(Main circuit power supply voltage: 240 VAC)	3-phase	5.8	9.0	13.0	15.9
Output	Rated current [A (rms)]		7.7	9.7	16.2	22.3
Maximum current [A (rm		s)]	16.9	28.4	41.0	54.7
Maximum	n power loss at power con	version	10% (Load condition: rated output)			
Applicab	le Servomotor rated outρι	ıt [W]	1,000	1,500	2,000	3,000
3,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS			1L1K030T	1L1K530T	1L2K030T	1L3K030T
2,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS		1M1K020T	1M1K520T	1M2K020T	1M3K020T	
1,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS		1M90010T		1M2K010T	1M3K010T	
Hold time at momentary power interruption (Main circuit power supply voltage: 200 VAC)			10 ms (Load condition: rated output) *2			
Weight [k	(g]		2.0	3.4	3.4	3.4

^{*1.} The values outside parentheses indicate the rated value, and the values inside parentheses indicate the range of acceptable variation.

^{*2.} The control power supply is not specified here as long as a DC power supply that meets the following conditions is used. Reinforced insulation or double insulation, and the output hold time of 10 ms or more.

400-VAC Input Models

Use a neutral grounded 400 VAC 3-phase power supply for the 400 VAC input models in order to satisfy the conditions to obtain the standards.

Servo Drive model (R88D-)		1SN06F-ECT	1SN10F-ECT	1SN15F-ECT	1SN20F-ECT	1SN30F-ECT				
	Item		600 W	1 kW	1.5 kW	2 kW	3 kW			
Main circuit		Power supply voltage	3-phase 380 to 480 VAC (323 to 504 V) *1							
		Frequency		50/60 Hz (47.5 to 63 Hz) *1						
Input	Control circuit	Power supply voltage		24	VDC (21.6 to 26.4	4 V)				
	Rated current [A (rms)] (Main circuit power supply voltage: 480 VAC)	3-phase	2.4	3.1	4.3	6.5	8.4			
Output	Rated current [A (rms)]		1.8	4.1	4.7	7.8	11.3			
Output	Maximum current [A (rms)]		5.5	9.6	14.1	19.8	28.3			
Maximun	n power loss at power con	version	10% (Load condition: rated output)							
Applicab	le Servomotor rated outpu	ıt [W]	600	1,000	1,500	2,000	3,000			
3,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS			1L75030C 1L1K030C	1L1K530C	1L2K030C	1L3K030C				
2,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS		1M40020C 1M60020C	1M1K020C	1M1K520C	1M2K020C	1M3K020C				
1,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS			1M90010C		1M2K010C	1M3K010C				
	e at momentary power inte		10 ms (Load condition: rated output) *2							
Weight [kg]		3.4	3.4	3.4	3.4	3.4			

^{*1.} The values outside parentheses indicate the rated value, and the values inside parentheses indicate the range of acceptable variation.

^{*2.} The control power supply is not specified here as long as a DC power supply that meets the following conditions is used.

EtherCAT Communications Specifications

Item	Specifications
Communications standard	IEC 61158 Type 12, IEC 61800-7 CiA 402 Drive Profile
Physical layer	100BASE-TX (IEEE802.3)
Connectors	RJ45 × 2 (shielded) ECAT IN: EtherCAT input ECAT OUT: EtherCAT output
Communications media	Recommended media: Twisted-pair cable, which is doubly shielded by the aluminum tape and braid, with Ethernet Category 5 (100BASE-TX) or higher
Communications distance	Distance between nodes: 100 m max.
Process data	Fixed PDO mapping Variable PDO mapping
Mailbox (CoE) Emergency messages, SDO requests, SDO responses, and SDO information	
Synchronization mode and communications cycle	DC Mode (Synchronous with Sync0 Event) Communications cycle: 125 μs, 250 μs, 500 μs, 750 μs, 1 to 10 ms (in 0.25 ms increments) Free Run Mode
Indicators	ECAT-L/A IN (Link/Activity IN) × 1 ECAT-L/A OUT (Link/Activity OUT) × 1 ECAT-RUN × 1 ECAT-ERR × 1
CiA 402 Drive Profile	Cyclic synchronous position mode Cyclic synchronous torque mode Cyclic synchronous torque mode Profile position mode Profile velocity mode Homing mode Touch probe function Torque limit function

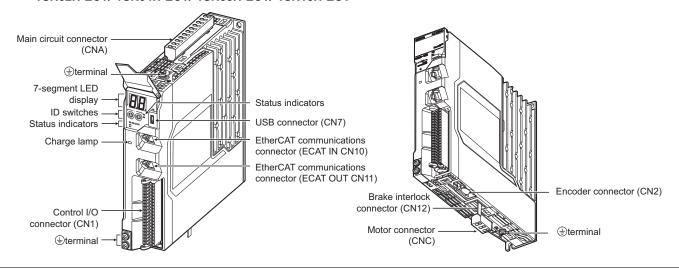
Version Information

1S-series S	Servo Drive	Corresponding version		
Model	Unit version	NJ/NX-series CPU Unit	Sysmac Studio	
R88D-1SN□-ECT	Version 1.0	NJ: Version 1.11 or later NX: Version 1.11 or later	Version 1.16 or higher	

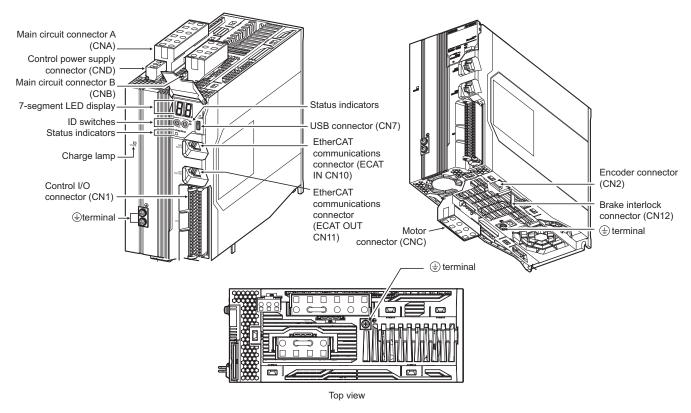
Part Names

Servo Drive Part Names

R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/-1SN01H-ECT/ -1SN02H-ECT/-1SN04H-ECT/-1SN08H-ECT/-1SN10H-ECT



R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/-1SN10F-ECT/-1SN20F-ECT/-1SN30F-ECT



Servo Drive Functions

Status Indicators

The following seven indicators are mounted.

Name	Color	Description	
PWR	Green	Displays the status of control power supply.	
ERR	Red	Gives the Servo Drive error status.	
ECAT-RUN	Green	Displayed the Father CAT communications status	
ECAT-ERR	Red	Displays the EtherCAT communications status.	
ECAT-L/A IN, ECAT-L/A OUT	Green	Lights or flashes according to the status of a link in the EtherCAT physical layer.	
FS	Red/green	Displays the safety communications status.	

7-segment LED Display

A 2-digit 7-segment LED display shows error numbers, the Servo Drive status, and other information.

ID Switches

Two rotary switches (0 to F hex) are used to set the EtherCAT node address.

Charge Lamp

Lights when the main circuit power supply carries electric charge.

Control I/O Connector (CN1)

Used for command input signals, I/O signals, and as the safety device connector. The short-circuit wire is installed on the safety signals before shipment.

Encoder Connector (CN2)

Connector for the encoder installed in the Servomotor.

EtherCAT Communications Connectors (ECAT IN CN10, ECAT OUT CN11)

These connectors are for EtherCAT communications.

USB Connector (CN7)

USB-Micro B Communications connector for the computer. This connector enables USB 2.0 Full Speed (12 Mbps) communications.

Brake Interlock Connector (CN12)

Used for brake interlock signals.

Main Circuit Connector (CNA)

Connector for the main circuit power supply input, control power supply input, external regeneration resistor, and DC reactor. Applicable models: R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/-1SN04L-ECT/-1SN04L-ECT/-1SN04H-ECT/

Main Circuit Connector A (CNA)

Connector for the main circuit power supply input and external regeneration resistor.

Applicable models: R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT

Main Circuit Connector B (CNB)

Connector for a DC reactor.

Applicable models: R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT

Control Power Supply Connector (CND)

Connector for control power supply input.

Applicable models: R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT

Motor Connector (CNC)

Connector for the power line to the phase U, V, and W of the Servomotor. The connector differs depending on the model.

⊕Terminal

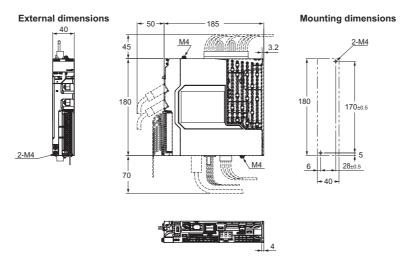
The number of (terminals of the Servo Drives and their connection targets are as follows.

Model	Number of terminals	Connection to
R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/	1 on top	PE wire of the main circuit power supply cable.
-1SN01H-ECT/-1SN02H-ECT/-1SN04H-ECT/	2 on front	FG wire inside the control panel, and FG wire for the motor
-1SN08H-ECT/-1SN10H-ECT	1 on bottom	cable and shielded wire.
R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/	1 on top	PE wire of the main circuit power supply cable.
-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/	2 on front	FG wire inside the control panel and the motor cable shielded
-1SN20F-ECT/-1SN30F-ECT	1 on bottom	wire.

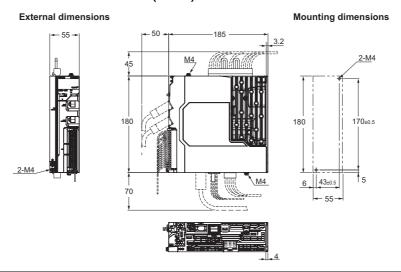
Dimensions (Unit: mm)

Single-phase 100 VAC: R88D-1SN01L-ECT (100 W)

Single-phase/3-phase 200 VAC: R88D-1SN01H-ECT/-1SN02H-ECT (100 to 200 W)



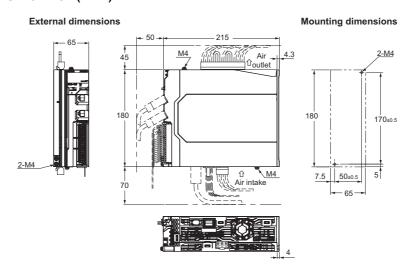
Single-phase 100 VAC: R88D-1SN02L-ECT (200 W) Single-phase/3-phase 200 VAC: R88D-1SN04H-ECT (400 W)



Single-phase 100 VAC: R88D-1SN04L-ECT (400 W)

Single-phase/3-phase 200 VAC: R88D-1SN08H-ECT (750 W)

3-phase 200 VAC: R88D-1SN10H-ECT (1 kW)



Single-phase/3-phase 200 VAC: R88D-1SN15H-ECT (1.5 kW) 3-phase 200 VAC: R88D-1SN20H-ECT/-1SN30H-ECT (2 to 3 kW)

3-phase 400 VAC: R88D-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT (600 W to 3 kW)

External dimensions Mounting dimensions **-** 50 -- 225 3-M4 M4_Air ⊕outlet 180 170±0.5 180 5 39±0.5 ☆ Air → 6 intake Air∜ **--** 78±0.5 utlet - 90 70

<u>M4</u>

MEMO

AC Servomotors [1S-series] R88M-1L\[\big| /-1 M\[\big| \]

Contents

- Ordering Information
- Specifications
- Names and Functions
- External Dimensions



The R88M-1L□ AC Servomotor will be available soon.

Ordering Information

Refer to the Ordering Information.

Specifications

General Specifications

	ltem -		Specifications	
Operating ambient temperature and humidity			0 to 40°C 20% to 90% (with no condensation)	
Storage ambien	t temperature	and humidity	-20 to 65°C 20% to 90% (with no condensation)	
Operating and s	storage atmosp	ohere	No corrosive gases	
Vibration resistance *			Acceleration of 49 m/s ² 24.5 m/s ² max. in X, Y, and Z directions when the motor is stopped	
Impact resistan	Impact resistance		Acceleration of 98 m/s ² max. 3 times each in X, Y, and Z directions	
Insulation resist	Insulation resistance		Between power terminals and FG terminals: 10 $\text{M}\Omega$ min. (at 500 VDC Megger)	
Dielectric streng	gth		Between power terminals and FG terminals: 1,500 VAC for 1 min (voltage 100 V, 200 V) Between power terminals and FG terminals: 1,800 VAC for 1 min (voltage 400 V) Between brake terminal and FG terminals: 1,000 VAC for 1 min	
Insulation class	•		Class F	
Protective structure			IP67 (except for the through-shaft part and connector pins) IP20 if you use a 30-meter or longer encoder cable.	
International	EU Directives	Low Voltage Directive	EN 60034-1/-5	
standard	UL standards		UL 1004-1/-6	
	CSA standards		CSA C22.2 No.100 (with cUR mark)	

^{*}The amplitude may be increased by machine resonance. As a guideline, 80% of the specified value must not be exceeded.

Note: 1. Do not use the cable when it is laying in oil or water.

Encoder Specifications

Item	Specifications
Encoder system	Optical batteryless absolute encoder
Resolution per rotation	23 bits
Multi-rotation data hold	16 bits
Power supply voltage	5 VDC±10%
Current consumption	230 mA max.
Output signal	Serial communications
Output interface	RS485 compliant

Note: It is possible to use an absolute encoder as an incremental encoder.

Refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual (Cat.No.I586) for details.

^{2.} Do not expose the cable outlet or connections to stress due to bending or its own weight.

Characteristics

3,000-r/min Servomotors

		Model (R88M-)	100 VAC			
	Item	Unit	1M10030S	1M20030S	1M40030S	
Rated output *1	*2	W	100	200	400	
Rated torque *1	*2	N·m	0.318	0.637	1.27	
Rated rotation s	speed *1 *2	r/min		3,000	l .	
Maximum rotation	on speed	r/min		6,000		
Momentary max	imum torque *1	N·m	0.95	1.91	3.8	
Rated current *	1 *2	A (rms)	1.50	2.50	4.8	
Momentary max	rimum current *1	A (rms)	4.70	8.40	14.7	
Without brake	× 10 ⁻⁴ kg·m ²	0.0890	0.2232	0.4452		
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	0.0968	0.2832	0.5052	
Applicable load	inertia	× 10 ⁻⁴ kg⋅m²	1.62	4.80	8.40	
Torque constan	t *1	N·m/ A (rms)	0.24	0.28	0.30	
Power rate *1 *	3	kW/s	11.9	18.5	36.6	
Mechanical time constant *3		ms	1.1	0.76	0.61	
Electrical time constant		ms	0.84	2.4	2.4	
Allowable radial load *4		N	68	245	245	
Allowable thrust load *4		N	58	88	88	
Mai-b+	Without brake	kg	0.52	1.0	1.4	
Weight	With brake	kg	0.77	1.3	1.9	
Radiator plate d	imensions (material)	mm	250 × 250 × t6 (aluminum)			
	Excitation voltage *5	V		24 VDC±10%		
	Current consumption (at 20°C)	Α	0.27	0.32	0.32	
	Static friction torque	N·m	0.32 min.	1.37 min.	1.37 min.	
	Attraction time	ms	25 max.	30 max.	30 max.	
	Release time *6	ms	15 max.	20 max.	20 max.	
Brake	Backlash	0	1.2 max.	1.2 max.	1.2 max.	
specifications	Allowable braking work	J	9	60	60	
	Allowable total work	J	9,000	60,000	60,000	
	Allowable angular acceleration	rad/s²	10,000 max.			
	Brake lifetime (acceleration/ deceleration)		10 million times min.			
	Insulation class			Class F		

For models with an oil seal, the following derating is used due to increase in friction torque.

Model (R88M-)		1M10030S-O/ -OS2/	1M20030S-O/ -OS2/	1M40030S-O/ -OS2/
Item	Unit	-BO/ -BOS2	-BO/ -BOS2	-BO/ -BOS2
Derating rate	%	95	95	80
Rated output	W	95	190	320
Rated current	A (rms)	1.50	2.50	4.0

		Model (R88M-)		200	VAC	
	Item		1M10030T	1M20030T	1M40030T	1M75030T
Rated output *1	1 *2	W	100	200	400	750
Rated torque *1	1 *2	N·m	0.318	0.637	1.27	2.39
Rated rotation speed *1 *2 r/min			3,0	000	<u>I</u>	
Maximum rotati	on speed	r/min		6,0	000	
Momentary maximum torque *1		N·m	1.11	2.2	4.5	8.4
Rated current *	:1 *2	A (rms)	0.84	1.5	2.5	4.6
Momentary max	rimum current *1	A (rms)	3.10	5.6	9.1	16.9
	Without brake	× 10⁻⁴ kg⋅m²	0.0890	0.2232	0.4452	1.8242
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	0.0968	0.2832	0.5052	2.0742
Applicable load	inertia	× 10 ⁻⁴ kg·m ²	1.62	4.80	8.40	19.4
Torque constan	nt *1	N·m/ A (rms)	0.42	0.48	0.56	0.59
Power rate *1 *3		kW/s	11.9	18.5	36.6	31.4
Mechanical time	e constant *3	ms	1.2	0.78	0.56	0.66
Electrical time constant		ms	0.83	2.4	2.6	3.3
Allowable radial load *4		N	68	245	245	490
Allowable thrus	t load *4	N	58	88	88	196
147 - 1 - d- 4	Without brake	kg	0.52	1.0	1.4	2.9
Weight	With brake	kg	0.77	1.3	1.9	3.9
Radiator plate d	limensions (material)	mm		250 × 250 ×	t6 (aluminum)	-
	Excitation voltage *5	V		24 VD	C±10%	
	Current consumption (at 20°C)	Α	0.27	0.32	0.32	0.37
	Static friction torque	N·m	0.32 min.	1.37 min.	1.37 min.	2.55 min.
	Attraction time	ms	25 max.	30 max.	30 max.	40 max.
	Release time *6	ms	15 max.	20 max.	20 max.	35 max.
Brake	Backlash	0	1.2 max.	1.2 max.	1.2 max.	1.0 max.
specifications	Allowable braking work	J	9	60	60	250
	Allowable total work	J	9,000	60,000	60,000	250,000
	Allowable angular acceleration	rad/s²	10,000 max.			
	Brake lifetime (acceleration/ deceleration)			10 million	times min.	
	Insulation class			Cla	ss F	

For models with an oil seal, the following derating is used due to increase in friction torque.

Мо	del (R88M-)	1M10030T-O/	1M20030T-O/	1M40030T-O/	1M75030T-O/
Item	Unit	-OS2/ -BO/ -BOS2	-OS2/ -BO/ -BOS2	-OS2/ -BO/ -BOS2	-OS2/ -BO/ -BOS2
Derating rate	%	95	95	80	90
Rated output	W	95	190	320	675
Rated current	A (rms)	0.84	1.5	2.1	4.2

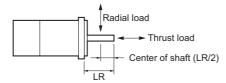
		Model (R88M-)	200 VAC				
	Item	Unit	1L1K030T	1L1K530T	1L2K030T	1L3K030T	
Rated output *1	*2	W	1,000	1,500	2,000	3,000	
Rated torque *1	*2	N·m	3.18	4.77	6.37	9.55	
Rated rotation speed *1 *2		r/min		3,0	000		
Maximum rotation speed		r/min		5,0	000		
Momentary max	ximum torque *1	N·m	9.55	14.3	19.1	28.7	
Rated current *	1 *2	A (rms)	5.2	8.8	12.5	17.1	
Momentary max	ximum current *1	A (rms)	16.9	28.4	41.0	54.7	
D - 4 !4! -	Without brake	× 10 ⁻⁴ kg·m ²	2.1042	2.1042	2.4042	6.8122	
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	2.5542	2.5542	2.8542	7.3122	
Applicable load	inertia	× 10 ⁻⁴ kg⋅m²	35.3	47.6	60.2	118	
Torque constant *1		N·m/ A (rms)	0.67	0.58	0.56	0.64	
Power rate *1 *3		kW/s	48	108	169	134	
Mechanical time constant *3		ms	0.58	0.58	0.50	0.47	
Electrical time constant		ms	5.9 6.1 6.4 11				
Allowable radia	Allowable radial load *4		490				
Allowable thrus	t load *4	N	196				
Waissbt	Without brake	kg	5.7	5.7	6.4	11.5	
Weight	With brake	kg	7.4	7.4	8.1	12.5	
Radiator plate d	limensions (material)	mm	$400 \times 400 \times t^2$	20 (aluminum)	470 × 470 × t	20 (aluminum)	
	Excitation voltage *5	V		24 VD	C±10%		
	Current consumption (at 20°C)	A	0.70	0.70	0.70	0.66	
	Static friction torque	N·m	9.3 min.	9.3 min.	9.3 min.	12.0 min.	
	Attraction time	ms	100 max.	100 max.	100 max.	100 max.	
	Release time *6	ms	30 max.	30 max.	30 max.	30 max.	
Brake	Backlash	۰	1.0 max.	1.0 max.	1.0 max.	0.8 max.	
specifications	Allowable braking work	J	500	500	500	1,000	
•	Allowable total work	J	900,000	900,000	900,000	3,000,000	
	Allowable angular acceleration	rad/s²		10,00	0 max.		
	Brake lifetime (acceleration/ deceleration)			10 million	times min.		
	Insulation class			Cla	ss F		

		Model (R88M-)		400 VAC		
	Item	Unit	1L75030C	1L1K030C	1L1K530C	
Rated output *1	I * 2	W	750	1,000	1,500	
Rated torque *1	l * 2	N·m	2.39	3.18	4.77	
Rated rotation s	speed *1 *2	r/min		3,000		
Maximum rotati	on speed	r/min		5,000		
Momentary max	rimum torque *1	N·m	7.16	9.55	14.3	
Rated current *	1 *2	A (rms)	3.0	3.0	4.5	
Momentary max	ximum current *1	A (rms)	9.6	9.6	14.1	
Datas in autic	Without brake	× 10 ⁻⁴ kg⋅m ²	1.3042	2.1042	2.1042	
Rotor inertia	With brake	× 10 ⁻⁴ kg⋅m ²	1.7542	2.5542	2.5542	
Applicable load	inertia	× 10⁻⁴ kg⋅m²	38.6	35.3	47.6	
Torque constan	t *1	N·m/ A (rms)	0.91	1.17	1.17	
Power rate *1 *	:3	kW/s	44	48	108	
Mechanical time constant *3		ms	1.09	0.6	0.58	
Electrical time constant		ms	4.3	5.9	5.9	
Allowable radia	l load *4	N	490			
Allowable thrus	t load *4	N	196			
Weight	Without brake	kg	4.1	5.7	5.7	
Weight	With brake	kg	5.8	7.4	7.4	
Radiator plate d	limensions (material)	mm	305 × 305 × t20 (aluminum) 400 × 400 × t20 (aluminum)			
	Excitation voltage *5	V	<u>"</u>	24 VDC±10%		
	Current consumption (at 20°C)	Α	0.70	0.70	0.70	
	Static friction torque	N·m	9.3 min.	9.3 min.	9.3 min.	
	Attraction time	ms	100 max.	100 max.	100 max.	
	Release time *6	ms	30 max.	30 max.	30 max.	
Brake	Backlash	0	1.0 max.	1.0 max.	1.0 max.	
specifications	Allowable braking work	J	500	500	500	
	Allowable total work	J	900,000	900,000	900,000	
	Allowable angular acceleration	rad/s²	10,000 max.			
	Brake lifetime (acceleration/ deceleration)			10 million times min.		
	Insulation class			Class F		

		Model (R88M-)	400	VAC	
	Item	Unit	1L2K030C	1L3K030C	
Rated output *1	*2	W	2,000	3,000	
Rated torque *1 *2		N·m	6.37	9.55	
Rated rotation s	speed *1 *2	r/min	3,	000	
Maximum rotati	on speed	r/min	5,	000	
Momentary max	rimum torque *1	N·m	19.1	28.7	
Rated current *	1 *2	A (rms)	6.3	8.7	
Momentary max	rimum current *1	A (rms)	19.8	27.7	
D - 4 ! !-	Without brake	× 10 ⁻⁴ kg·m ²	2.4042	6.8122	
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	2.8542	7.3122	
Applicable load	inertia	× 10 ⁻⁴ kg·m ²	60.2	118	
Torque constan	t *1	N·m/ A (rms)	1.15	1.23	
Power rate *1 *	3	kW/s	169	134	
Mechanical time	e constant *3	ms	0.52	0.49	
Electrical time constant		ms	6.3	11	
Allowable radia	l load *4	N	490		
Allowable thrus	t load *4	N	196		
	Without brake	kg	6.4	11.5	
Weight	With brake	kg	8.1	12.5	
Radiator plate d	limensions (material)	mm	470 × 470 × t	20 (aluminum)	
<u> </u>	Excitation voltage *5	V		C±10%	
	Current consumption (at 20°C)	A	0.70	0.66	
	Static friction torque	N·m	9.3 min.	12 min.	
	Attraction time	ms	100 max.	100 max.	
	Release time *6	ms	30 max.	30 max.	
Brake	Backlash	0	1.0 max.	0.8 max.	
specifications	Allowable braking work	J	500	1,000	
	Allowable total work	J	900,000	3,000,000	
	Allowable angular acceleration	rad/s²	10,00	00 max.	
	Brake lifetime (acceleration/ deceleration)		10 million	times min.	
	Insulation class		Cla	ass F	

- *1. This is a typical value for when the Servomotor is used at a normal temperature (20°C, 65%) in combination with a Servo Drive.

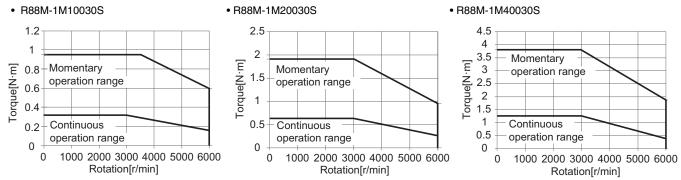
 *2. The rated values are the values with which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
- ***3.** This value is for models without options.
- *4. The allowable radial and thrust loads are the values determined for a limit of 20,000 hours at normal operating temperatures. The allowable radial loads are applied as shown in the following diagram.



- ***5.** This is a non-excitation brake. It is released when excitation voltage is applied.
- ***6.** This value is a reference value.

Torque-Rotation Speed Characteristics for 3,000-r/min Servomotors (100 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 100 VAC input.

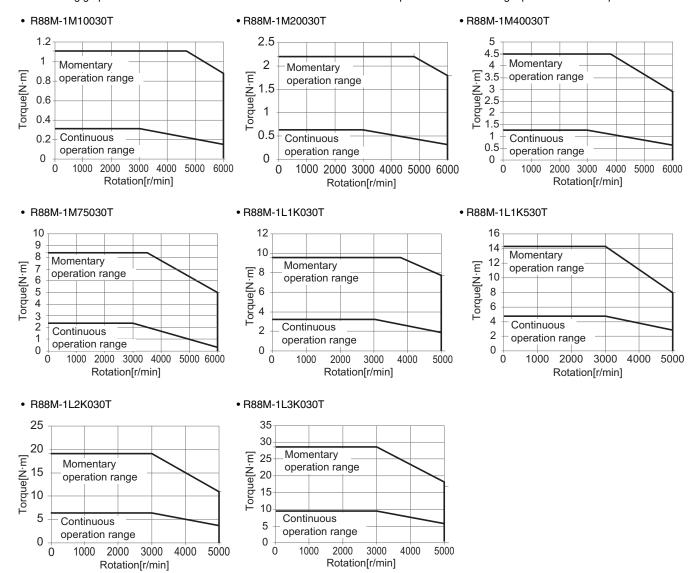


Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

Torque-Rotation Speed Characteristics for 3,000-r/min Servomotors (200 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 3-phase 200-VAC or single-phase 220-VAC input.

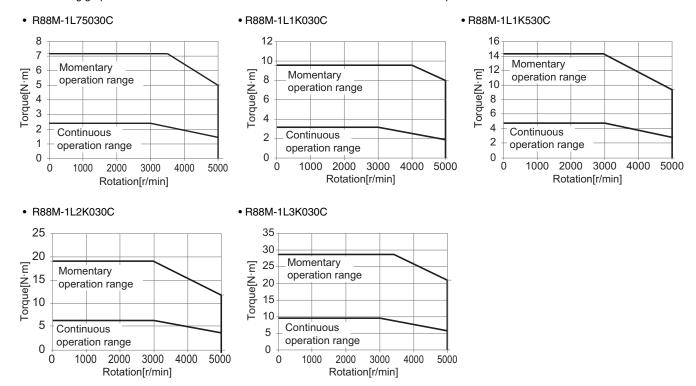


Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

Torque-Rotation Speed Characteristics for 3,000-r/min Servomotors (400 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 400 VAC input.



Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

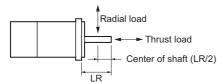
2,000-r/min Servomotors

	Model (R88M-)			200 VAC			
	Item	Unit	1M1K020T	1M1K520T	1M2K020T	1M3K020T	
Rated output *1	*2	W	1,000	1,500	2,000	3,000	
Rated torque *1	*2	N·m	4.77	7.16	9.55	14.3	
Rated rotation s	peed *1 *2	r/min	-	2,0	000		
Maximum rotation	on speed	r/min		3,0	000		
Momentary maximum torque *1		N-m	14.3	21.5	28.7	43.0	
Rated current *	1 *2	A (rms)	5.2	8.6	11.3	15.7	
Momentary max	imum current *1	A (rms)	16.9	28.4	40.6	54.7	
Datas inastia	Without brake	× 10 ⁻⁴ kg·m ²	6.0042	9.0042	12.2042	15.3122	
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	6.5042	9.5042	12.7042	17.4122	
Applicable load	inertia	× 10 ⁻⁴ kg·m ²	59.0	79.9	100	142	
Torque constant	t *1	N·m/ A (rms)	0.93	0.83	0.85	0.93	
Power rate *1 *	3	kW/s	38	57	75	134	
Mechanical time constant *3		ms	0.94	0.78	0.81	0.80	
Electrical time constant		ms	13	15	14	19	
Allowable radial load *4 N		N	490			784	
Allowable thrust	t load *4	N	196			343	
	Without brake	kg	6.6	8.5	10	12	
Weight	With brake	kg	8.6	10.5	12	15	
Radiator plate d	imensions (material)	mm	400 × 400 × t20 (aluminum) 470 × 470 × t20 (aluminum)			um)	
	Excitation voltage *5	V	-	24 VD	C±10%		
	Current consumption (at 20°C)	Α	0.51	0.51	0.66	0.60	
	Static friction torque	N·m	9.0 min.	9.0 min.	12 min.	16 min.	
	Attraction time	ms	100 max.	100 max.	100 max.	150 max.	
	Release time *6	ms	30 max.	30 max.	30 max.	50 max.	
Brake	Backlash	0	0.6 max.	0.6 max.	0.6 max.	0.6 max.	
specifications	Allowable braking work	J	1,000	1,000	1,000	350	
	Allowable total work	J	3,000,000	3,000,000	3,000,000	1,000,000	
	Allowable angular acceleration	rad/s²	10,000 max.			1	
	Brake lifetime (acceleration/ deceleration)			10 million	times min.		
	Insulation class			Cla	ss F		

		Model (R88M-)		400 VAC	
	Item		1M40020C	1M60020C	1M1K020C
Rated output *1	*2	W	400	600	1,000
Rated torque *1	*2	N·m	1.91	2.86	4.77
Rated rotation s	peed *1 *2	r/min		2,000	-
Maximum rotation	on speed	r/min		3,000	
Momentary max	imum torque *1	N·m	5.73	8.59	14.3
Rated current *	1 *2	A (rms)	1.1	1.6	2.9
Momentary max	imum current *1	A (rms)	3.9	5.5	9.4
	Without brake	× 10 ⁻⁴ kg·m ²	2.5042	3.9042	6.0042
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	2.8472	4.2472	6.5042
Applicable load	inertia	× 10 ⁻⁴ kg·m ²	19.0	23.5	59.0
Torque constan	t *1	N·m/ A (rms)	1.75	1.84	1.69
Power rate *1 *	3	kW/s	14.6	21.0	38
Mechanical time	constant *3	ms	1.57	1.21	0.94
Electrical time constant		ms	6.8	7.8	13
Allowable radial	load *4	N	490		
Allowable thrus	t load *4	N	196		
\A/ - !!- A	Without brake	kg	3.9	4.7	6.6
Weight	With brake	kg	4.8	5.8	8.6
Radiator plate d	imensions (material)	mm	305 × 305 × t12 (aluminum)		400 × 400 × t20 (aluminum)
	Excitation voltage *5	V		24 VDC±10%	<u> </u>
	Current consumption (at 20°C)	A	0.30	0.30	0.51
	Static friction torque	N·m	3.92 min.	3.92 min.	9.0 min.
	Attraction time	ms	40 max.	40 max.	100 max.
	Release time *6	ms	25 max.	25 max.	30 max.
Brake	Backlash	0	1.0 max.	1.0 max.	0.6 max.
specifications	Allowable braking work	J	330	330	1,000
	Allowable total work	J	330,000	330,000	3,000,000
	Allowable angular acceleration	rad/s²		10,000 max.	
	Brake lifetime (acceleration/ deceleration)			10 million times min.	
	Insulation class			Class F	

		Model (R88M-)		400 VAC		
	Item	Unit	1M1K520C	1M2K020C	1M3K020C	
Rated output *1	*2	W	1,500	2,000	3,000	
Rated torque *1	*2	N·m	7.16	9.55	14.3	
Rated rotation s	speed *1 *2	r/min		2,000		
Maximum rotati	on speed	r/min		3,000		
Momentary max	rimum torque *1	N·m	21.5	28.7	43.0	
Rated current *	1 *2	A (rms)	4.1	5.7	8.6	
Momentary max	rimum current *1	A (rms)	13.5	19.8	28.3	
n - 4 '4' -	Without brake	× 10 ⁻⁴ kg·m ²	9.0042	12.2042	15.3122	
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	9.5042	12.7042	17.4122	
Applicable load	inertia	× 10 ⁻⁴ kg·m ²	79.9	100	142	
Torque constan	t *1	N·m/ A (rms)	1.75	1.75	1.74	
Power rate *1 *	3	kW/s	57	75	134	
Mechanical time	constant *3	ms	0.85	0.80	0.76	
Electrical time constant		ms	13	14	20	
Allowable radia	l load *4	N	490		784	
Allowable thrus	t load *4	N	196		343	
M/a:ada4	Without brake	kg	8.5	10	12	
Weight	With brake	kg	10.5	12	15	
Radiator plate d	imensions (material)	mm	470 × 470 × t20 (aluminum)			
	Excitation voltage *5	V	24 VDC±10%			
	Current consumption (at 20°C)	Α	0.51	0.66	0.60	
	Static friction torque	N·m	9.0 min.	12 min.	16 min.	
	Attraction time	ms	100 max.	100 max.	150 max.	
	Release time *6	ms	30 max.	30 max.	50 max.	
Brake	Backlash	۰	0.6 max.	0.6 max.	0.6 max.	
specifications	Allowable braking work	J	1,000	1,000	350	
	Allowable total work	J	3,000,000	3,000,000	1,000,000	
	Allowable angular acceleration	rad/s²				
	Brake lifetime (acceleration/ deceleration)			10 million times min.		
	Insulation class			Class F		
			Class F			

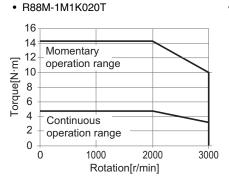
- *1. This is a typical value for when the Servomotor is used at a normal temperature (20°C, 65%) in combination with a Servo Drive.
- *2. The rated values are the values with which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
- ***3.** This value is for models without options.
- *4. The allowable radial and thrust loads are the values determined for a limit of 20,000 hours at normal operating temperatures. The allowable radial loads are applied as shown in the following diagram.

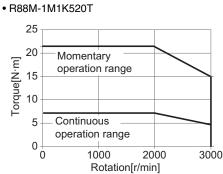


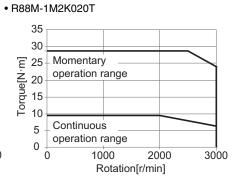
- ***5.** This is a non-excitation brake. It is released when excitation voltage is applied.
- ***6.** This value is a reference value.

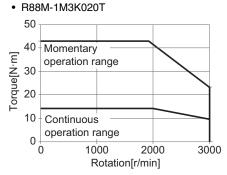
Torque-Rotation Speed Characteristics for 2,000-r/min Servomotors (200 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 3-phase 200-VAC or single-phase 220-VAC input.







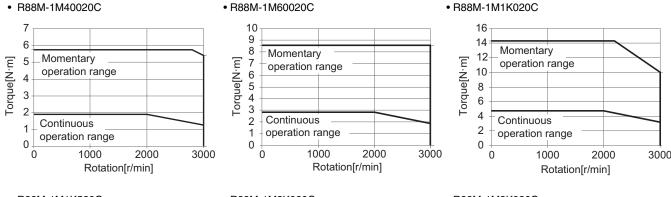


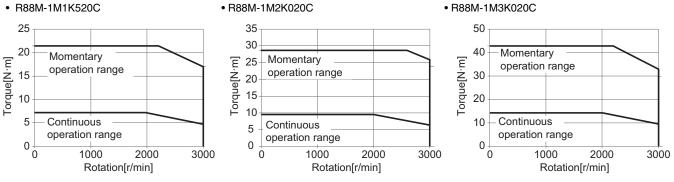
Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

Torque-Rotation Speed Characteristics for 2,000-r/min Servomotors (400 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 400 VAC input.





Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

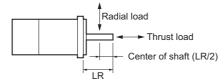
Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

1,000-r/min Servomotors

Model (R88M-)		Model (R88M-)	200 VAC			
	Item	Unit	1M90010T	1M2K010T	1M3K010T	
Rated output *1	*2	W	900	2,000	3,000	
Rated torque *1	*2	N·m	8.59	19.1	28.7	
Rated rotation s	peed *1 *2	r/min		1,000		
Maximum rotation	on speed	r/min		2,000		
Momentary max	imum torque *1	N·m	19.3	47.7	71.7	
Rated current *	1 *2	A (rms)	6.7	14.4	21.2	
Momentary max	imum current *1	A (rms)	16.9	40.6	54.7	
Without brake	Without brake	× 10 ⁻⁴ kg⋅m ²	9.0042	40.0122	68.0122	
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	9.5042	45.1122	73.1122	
Applicable load	inertia	× 10 ⁻⁴ kg⋅m²	79.9	314	492	
Torque constant	t *1	N·m/ A (rms)	1.28	1.45	1.51	
Power rate *1 *	3	kW/s	82	91	121	
Mechanical time	constant *3	ms	0.77	1.0	0.83	
Electrical time c	onstant	ms	15	18	22	
Allowable radial	llowable radial load *4		686	1,176	1,470	
Allowable thrust	Allowable thrust load *4		196	490		
NAV - 1 I- A	Without brake	kg	8.5	18	28	
Weight	With brake	kg	10.5	22	33	
Radiator plate d	imensions (material)	mm	470 × 470 × t20 (aluminum)		540 × 540 × t20 (aluminum)	
	Excitation voltage *5	V		24 VDC±10%		
	Current consumption (at 20°C)	Α	0.51	1.2	1.0	
	Static friction torque	N·m	9.0 min.	22 min.	42 min.	
	Attraction time	ms	100 max.	120 max.	150 max.	
	Release time *6	ms	30 max.	50 max.	60 max.	
Brake	Backlash	0	0.6 max.	0.8 max.	0.8 max.	
specifications	Allowable braking work	J	1,000	1,400	1,400	
	Allowable total work	J	3,000,000	4,600,000	4,600,000	
	Allowable angular acceleration	rad/s²		10,000 max.	ı	
	Brake lifetime (acceleration/ deceleration)			10 million times min.		
	Insulation class			Class F		

Model (R88M-)				400 VAC			
	Item	Unit	1M90010C	1M2K010C	1M3K010C		
Rated output *1	*2	W	900	2,000	3,000		
Rated torque *1 *2		N·m	8.59	19.1	28.7		
Rated rotation s	peed *1 *2	r/min		1,000			
Maximum rotation	on speed	r/min		2,000			
Momentary max	imum torque *1	N·m	19.3	47.7	71.7		
Rated current *	1 *2	A (rms)	3.6	7.1	10.6		
Momentary max	imum current *1	A (rms)	9.0	19.5	27.7		
Without brake	× 10 ⁻⁴ kg·m ²	9.0042	40.0122	68.0122			
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	9.5042	45.1122	73.1122		
Applicable load	inertia	× 10 ⁻⁴ kg⋅m²	79.9	314	492		
Torque constant	t *1	N·m/ A (rms)	2.41	3.00	2.97		
Power rate *1 *	3	kW/s	82	91	121		
Mechanical time	constant *3	ms	0.88	1.2	0.92		
Electrical time constant		ms	13	16	19		
Allowable radial load *4		N	686	1,176	1,470		
Allowable thrust	t load *4	N	196	4	190		
Mainlat	Without brake	kg	8.5	18	28		
Veight	With brake	kg	10.5	22	33		
Radiator plate d	imensions (material)	mm	470 × 470 × t20 (aluminum)		540 × 540 × t20 (aluminum)		
	Excitation voltage *5	V		24 VDC±10%	-		
	Current consumption (at 20°C)	Α	0.51	1.2	1.0		
	Static friction torque	N·m	9.0 min.	22 min.	42 min.		
	Attraction time	ms	100 max.	120 max.	150 max.		
	Release time *6	ms	30 max.	50 max.	60 max.		
Brake	Backlash	0	0.6 max.	0.8 max.	0.8 max.		
specifications	Allowable braking work	J	1,000	1,400	1,400		
	Allowable total work	J	3,000,000	4,600,000	4,600,000		
	Allowable angular acceleration	rad/s²	10,000 max.		1		
	Brake lifetime (acceleration/ deceleration)			10 million times min.			
	Insulation class			Class F			

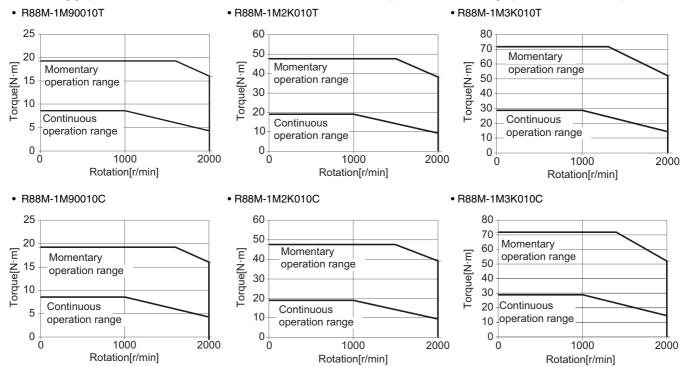
- *1. This is a typical value for when the Servomotor is used at a normal temperature (20°C, 65%) in combination with a Servo Drive.
- *2. The rated values are the values with which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
- ***3.** This value is for models without options.
- *4. The allowable radial and thrust loads are the values determined for a limit of 20,000 hours at normal operating temperatures. The allowable radial loads are applied as shown in the following diagram.



- $\textbf{\$5.} \ \text{This is a non-excitation brake. It is released when excitation voltage is applied.}$
- ***6.** This value is a reference value.

Torque-Rotation Speed Characteristics for 1,000-r/min Servomotors (200 V/400 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 3-phase 200-VAC or single-phase 220/400-VAC input.



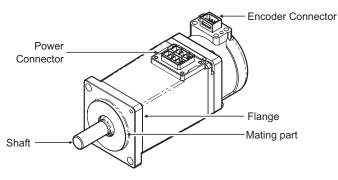
Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

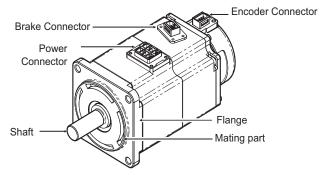
Part Names

Servomotor Part Names

Flange Size of 80 × 80 or less

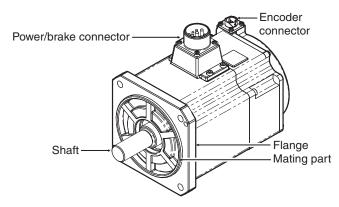


100 VAC 100 W Servomotors (without Brake)



200 VAC 200 W Servomotors (with Brake)

Flange Size of 100 × 100 or more



200 VAC 1.5 kW Servomotors (with Brake)

Servomotor Functions

Shaft

The load is mounted on this shaft.

The direction which is in parallel with the shaft is called the thrust direction, and the direction which is perpendicular to the shaft is called the radial direction.

Flange

Used for mounting the Servomotor on the equipment.

Fit the mating part into the equipment and use the mounting holes to screw the Servomotor.

Power Connector

Used for supplying power to the phase U, V, and W of the Servomotor.

For Servomotors with a brake and flange size of 100 × 100 or more, the pins for power and brake are set on the same connector.

Encoder Connector

Used for supplying power to the encoder of the Servomotor and communicating with the Servo Drive.

Brake Connector

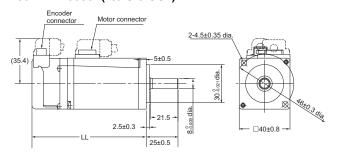
Used for supplying power to the brake coil of the Servomotor.

This part is attached only to the Servomotors with a brake and flange size of 80×80 or less.

3,000-r/min Servomotors (100 V and 200 V)

100 W (without Brake)

R88M-1M10030S(-O/-S2/-OS2) R88M-1M10030T(-O/-S2/-OS2)

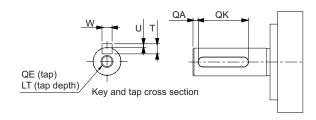


Model	Dimensions [mm]			
Model	LL			
R88M-1M10030S(-S2) R88M-1M10030T(-S2)	90±1			
R88M-1M10030S(-O/-OS2) R88M-1M10030T(-O/-OS2)	95±1			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

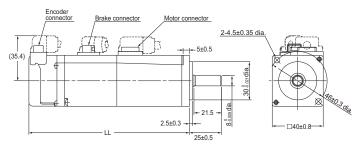
Shaft-end with key and tap



Model	Dimensions [mm]						
	QA	QK	W	Т	U	QE	LT
R88M- 1M10030S(-S2/-OS2)	2	12	3-0.025	3	1.2 0	МЗ	8
R88M- 1M10030T(-S2/-OS2)	2	12	3-0.025	3	1.2.0	МЗ	8

100 W (with Brake)

R88M-1M10030S-B(O/S2/OS2) R88M-1M10030T-B(O/S2/OS2)

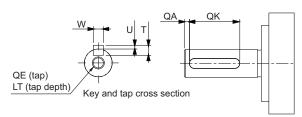


Model	Dimensions [mm]			
	LL			
R88M-1M10030S-B(S2) R88M-1M10030T-BS2)	126±1			
R88M-1M10030S-B(O/OS2) R88M-1M10030T-B(O/OS2)	131±1			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

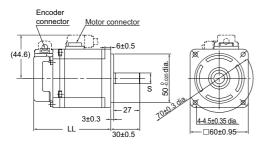
Shaft-end with key and tap



Model	Dimensions [mm]						
	QA	QK	w	Т	U	QE	LT
R88M- 1M10030S-B(S2/OS2)	2	12	3-0.025	3	1.2.0.2	МЗ	8
R88M- 1M10030T-B(S2/OS2)	2	12	3-0.025	3	1.2.0.2	МЗ	8

200 W/400 W (without Brake)

R88M-1M20030S(-O/-S2/-OS2)/R88M-1M20030T(-O/-S2/-OS2) R88M-1M40030S(-O/-S2/-OS2)/R88M-1M40030T(-O/-S2/-OS2)

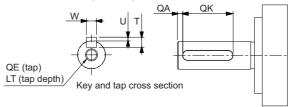


Model	Dimensions [mm]				
Wodel	S	LL			
R88M-1M20030S(-S2) R88M-1M20030T(-S2)	11 _{-0.011} dia.	79.5±1			
R88M-1M40030S(-S2) R88M-1M40030T(-S2)	14 _{-0.011} dia.	105.5±1			
R88M-1M20030S(-O/-OS2) R88M-1M20030T(-O/-OS2)	11 _{-0.011} dia.	86.5±1			
R88M-1M40030S(-O/-OS2) R88M-1M40030T(-O/-OS2)	14 _{-0.011} dia.	112.5±1			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

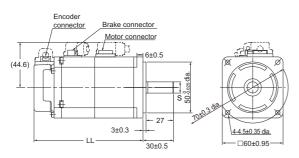
Shaft-end with key and tap



Model	Dimensions [mm]							
Wodei	QA	QK	W	T	U	QE	LT	
R88M- 1M20030S(-S2/-OS2)	2	20	4-0.03	4	1.5-0.2	M4	10	
R88M- 1M20030T(-S2/-OS2)	2	20	4-0.03	4	1.5.0	M4	10	
R88M- 1M40030S(-S2/-OS2)	2	20	5-0.03	5	2.0.2	M5	12	
R88M- 1M40030T(-S2/-OS2)	2	20	5-0.03	5	2-0.2	M5	12	

200 W/400 W (with Brake)

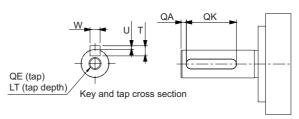
R88M-1M20030S-B(O/S2/OS2)/R88M-1M20030T-B(O/S2/OS2) R88M-1M40030S-B(O/S2/OS2)/R88M-1M40030T-B(O/S2/OS2)



Model	Dimensions [mm]				
Wodei	S	LL			
R88M-1M20030S-B(S2) R88M-1M20030T-B(S2)	11 _{-0.011} dia.	107.5±1			
R88M-1M40030S-B(S2) R88M-1M40030T-B(S2)	14 _{-0.011} dia.	133.5±1			
R88M-1M20030S-B(O/OS2) R88M-1M20030T-B(O/OS2)	11 _{-0.011} dia.	114.5±1			
R88M-1M40030S-B(O/OS2) R88M-1M40030T-B(O/OS2)	14 _{-0.011} dia.	140.5±1			

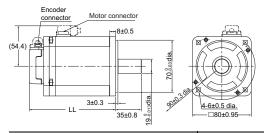
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.



Model	Dimensions [mm]							
Model	QA	QK	W	Т	U	QE	LT	
R88M- 1M20030S-B(S2/OS2)	2	20	4-0.03	4	1.5.0.2	M4	10	
R88M- 1M20030T-B(S2/OS2)	2	20	4-0.03	4	1.5.0	M4	10	
R88M- 1M40030S-B(S2/OS2)	2	20	5-0.03	5	2.0.2	M5	12	
R88M- 1M40030T-B(S2/OS2)	2	20	5-0.03	5	2.0.2	M5	12	

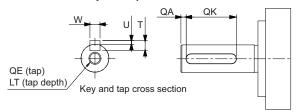
750 W (without Brake) R88M-1M75030T(-O/-S2/-OS2)



Model	Dimensions [mm]
Widdel	LL
R88M-1M75030T(-S2)	117.3±1
R88M-1M75030T(-O/-OS2)	124.3±1

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

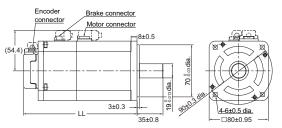
Shaft-end with key and tap



Model	Dimensions [mm]							
	QA	QK	W	Т	U	QE	LT	
R88M- 1M75030T(-S2/-OS2)	3	24	6-0.03	6	2.5.0	M5	12	

750 W (with Brake)

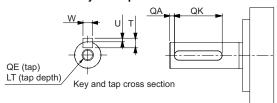
R88M-1M75030T-B(O/S2/OS2)



Model	Dimensions [mm]
Wodei	LL
R88M-1M75030T-B(S2)	153±1
R88M-1M75030T-B(O/OS2)	160±1

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

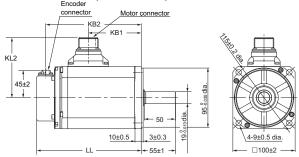
Shaft-end with key and tap



Model	Dimensions [mm]						
	QA	QK	W	Т	U	QE	LT
R88M- 1M75030T-B(S2/OS2)	3	24	6-0.03	6	2.5.0	M5	12

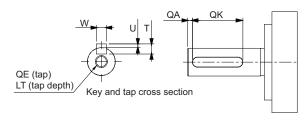
1 kW/1.5 kW/2 kW (without Brake)

R88M-1L1K030T(-O/-S2/-OS2)/R88M-1L1K530T(-O/-S2/-OS2)/ R88M-1L2K030T(-O/-S2/-OS2)



Model	Dimensions [mm]					
Model	LL	KB1	KB2	KL2		
R88M-1L1K030T(-O/-S2/-OS2)	168±2	85±1	153±2	97±2		
R88M-1L1K530T(-O/-S2/-OS2)	168±2	85±1	153±2	97±2		
R88M-1L2K030T(-O/-S2/-OS2)	179±2	96±1	164±2	102±2		

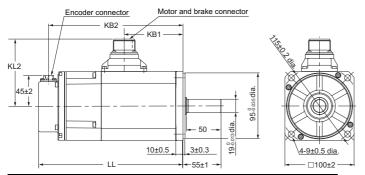
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



Model	Dimensions [mm]							
Woder	QA	QK	W	Т	U	QE	LT	
R88M- 1L1K030T(-S2/-OS2)	3	42	6-0.03	6	2.5 0	M5	12	
R88M- 1L1K530T(-S2/-OS2)	3	42	6-0.03	6	2.5 _{-0.2}	M5	12	
R88M- 1L2K030T(-S2/OS2)	3	42	6-0.03	6	2.5.0	M5	12	

1 kW/1.5 kW/2 kW (with Brake)

R88M-1L1K030T-B(O/S2/OS2)/R88M-1L1K530T-B(O/S2/OS2)/R88M-1L2K030T-B(O/S2/OS2)

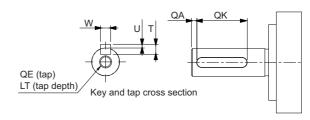


Model	Dimensions [mm]						
Wodel	LL	KB1	KB2	KL2			
R88M-1L1K030T-B(O/S2/OS2)	209±3	85±1	194±2	97±2			
R88M-1L1K530T-B(O/S2/OS2)	209±3	85±1	194±2	97±2			
R88M-1L2K030T-B(O/S2/OS)	220±3	96±1	205±2	104±2			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

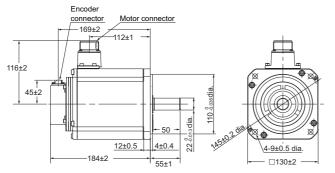
Shaft-end with key and tap



Model	Dimensions [mm]							
Model	QA	QK	W	Т	U	QE	LT	
R88M- 1L1K030T-B(S2/OS2)	3	42	6-0.03	6	2.5 0	M5	12	
R88M- 1L1K530T-B(S2/OS2)	3	42	6-0.03	6	2.5_0	M5	12	
R88M- 1L2K030T-B(S2/OS2)	3	42	6-0.03	6	2.5-0.2	M5	12	

3 kW (without Brake)

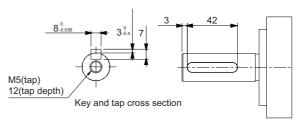
R88M-1L3K030T(-O/-S2/-OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

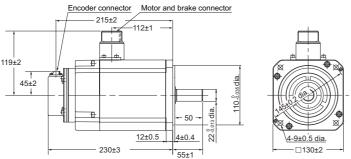
Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



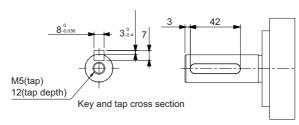
3 kW (with Brake)

R88M-1L3K030T-B(O/S2/OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

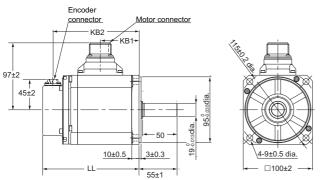
Models with an oil seal are indicated with "O" at the end of the model number.



3,000-r/min Servomotors (400 V)

750 W/1 kW/1.5 kW/2 kW (without Brake)

R88M-1L75030C(-O/-S2/-OS2)/R88M-1L1K030C(-O/-S2/-OS2) R88M-1L1K530C(-O/-S2/-OS2)/R88M-1L2K030C(-O/-S2/-OS2)

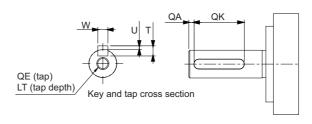


Model	Dimensions [mm]					
Wiodei	LL	KB1	KB			
R88M-1L75030C(-O/-S2/-OS2)	139±2	56±1	124±2			
R88M-1L1K030C(-O/-S2/-OS2)	168±2	85±1	153±2			
R88M-1L1K530C(-O/-S2/-OS2)	168±2	85±1	153±2			
R88M-1L2K030C(-O/-S2/-OS2)	179±2	96±1	164±2			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

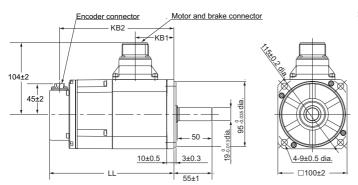
Shaft-end with key and tap



Model		Dimensions [mm]								
Model	QA	QK	w	Т	U	QE	LT			
R88M- 1L75030C(-S2/-OS2)	3	42	6-0.03	6	2.5 0	M5	12			
R88M- 1L1K030C(-S2/-OS2)	3	42	6-0.03	6	2.5.0.2	M5	12			
R88M- 1L1K530C(-S2/-OS2)	3	42	6-0.03	6	2.5_0	M5	12			
R88M- 1L2K030C(-S2/-OS2)	3	42	6-0.03	6	2.5 0	M5	12			

750 W/1 kW/1.5 kW/2 kW (with Brake)

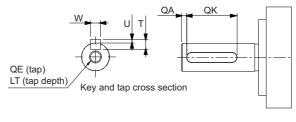
R88M-1L75030C-B(O/S2/OS2)/R88M-1L1K030C-B(O/S2/OS2) R88M-1L1K530C-B(O/S2/OS2)/R88M-1L2K030C-B(O/S2/OS2)



Model	Dimensions [mm]				
Wodei	LL	KB1	KB		
R88M-1L75030C-B(O/S2/OS2)	180±2	56±1	165±2		
R88M-1L1K030C-B(O/S2/OS2)	209±3	85±1	194±2		
R88M-1L1K530C-B(O/S2/OS2)	209±3	85±1	194±2		
R88M-1L2K030C-B(O/S2/OS2)	220±3	96±1	205±2		

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

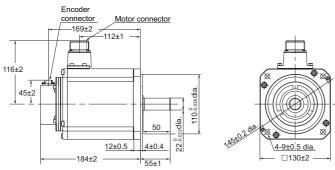
Models with an oil seal are indicated with "O" at the end of the model number.



Model		Dimensions [mm]								
Wodei	QA	QK	W	Т	U	QE	LT			
R88M- 1L75030C-B(S2/OS2)	3	42	6-0.03	6	2.5 -0.2	M5	12			
R88M- 1L1K030C-B(S2/OS2)	3	42	6-0.03	6	2.5 0	M5	12			
R88M- 1L1K530C-B(S2/OS2)	3	42	6-0.03	6	2.5 -0.2	M5	12			
R88M- 1L2K030C-B(S2/OS2)	3	42	6-0.03	6	2.5 -0.2	M5	12			

3 kW (without Brake)

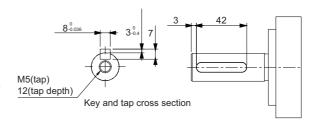
R88M-1L3K030C(-O/-S2/-OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

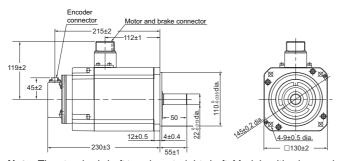
Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



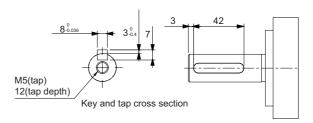
3 kW (with Brake)

R88M-1L3K030C-B(O/S2/OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

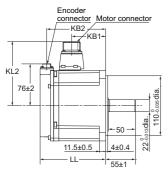
Models with an oil seal are indicated with "O" at the end of the model number.



2,000-r/min Servomotors (200 V)

1 kW/1.5 kW/2 kW (without Brake)

R88M-1M1K020T(-O/-S2/-OS2) R88M-1M1K520T(-O/-S2/-OS2) R88M-1M2K020T(-O/-S2/-OS2)

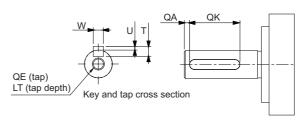




Model		Dimensions [mm]							
Wodel	LL	KB1	KB2	KL2					
R88M- 1M1K020T(-O/-S2/-OS2)	120.5±2	63±1	109±2	118±2					
R88M- 1M1K520T(-O/-S2/-OS2)	138±2	79±1	125±2	118±2					
R88M- 1M2K020T(-O/-S2/-OS2)	160±2	99±1	147±2	116±2					

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

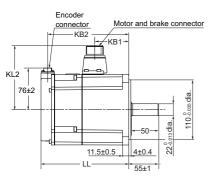
Shaft-end with key and tap



Model		Dimensions [mm]								
Model	QA	QK	W	Т	U	QE	LT			
R88M- 1M1K020T(-S2/-OS2)	3	42	8-0.036	7	3.0.4	M5	12			
R88M- 1M1K520T(-S2/-OS2)	3	42	8-0.036	7	3-0.4	M5	12			
R88M- 1M2K020T(-S2/-OS2)	3	42	8-0.036	7	3-0.4	M5	12			

1 kW/1.5 kW/2 kW (with Brake)

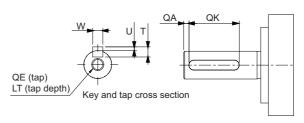
R88M-1M1K020T-B (O/S2/OS2) R88M-1M1K520T-B(O/S2/OS2) R88M-1M2K020T-B(O/S2/OS2)





Model		Dimensions [mm]							
Wodel	LL	KB1	KB2	KL2					
R88M- 1M1K020T-B(O/S2/OS2)	162±2	63±1	149±2	118±2					
R88M- 1M1K520T-B(O/S2/OS2)	179±2	79±1	166±2	118±2					
R88M- 1M2K020T-B(O/S2/OS2)	201±3	99±1	189±2	119±2					

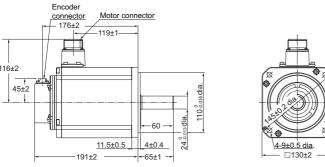
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



Model	Dimensions [mm]									
	QA	QK	W	Т	U	QE	LT			
R88M- 1M1K020T-B(S2/OS2)	3	42	8-0.036	7	3-0.4	M5	12			
R88M- 1M1K520T-B(S2/OS2)	3	42	8-0.036	7	3.0.4	M5	12			
R88M- 1M2K020T-B(S2/OS2)	3	42	8-0.036	7	3-0.4	M5	12			

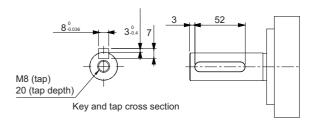
3 kW (without Brake)

R88M-1M3K020T(-O/-S2/-OS2)



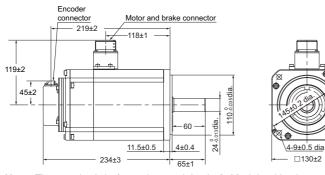
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



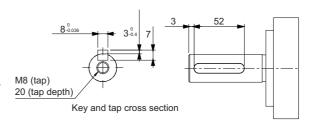
3 kW (with Brake)

R88M-1M3K020T-B(O/S2/OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

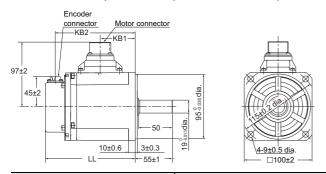
Models with an oil seal are indicated with "O" at the end of the model number.



2,000-r/min Servomotors (400 V)

400 W/600 W (without Brake)

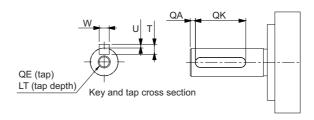
R88M-1M40020C(-O/-S2/-OS2)/R88M-1M60020C(-O/-S2/-OS2)



Model	Dimensions [mm]					
Model	LL	KB1	KB2			
R88M-1M40020C(-O/-S2/-OS2)	134.8±1	52±1	120.5±2			
R88M-1M60020C(-O/-S2/-OS2)	151.8±1	69±1	137.5±2			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

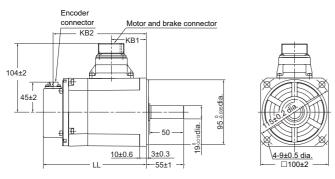
Shaft-end with key and tap



Model		Dimensions [mm]								
	QA	QK	W	Т	U	QE	LT			
R88M- 1M40020C(-S2/-OS2)	3	42	6-0.03	6	2.5 0	M5	12			
R88M- 1M60020C(-S2/-OS2)	3	42	6-0.03	6	2.5.0	M5	12			

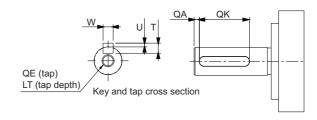
400 W/600 W (with Brake)

R88M-1M40020C-B(O/S2/OS2)/R88M-1M60020C-B(O/S2/OS2)



Model	Dimensions [mm]					
	LL	KB1	KB2			
R88M-1M40020C-B(O/S2/OS2)	152.3±1	52±1	138±2			
R88M-1M60020C-B(O/S2/OS2)	169.3±1	69±1	155±2			

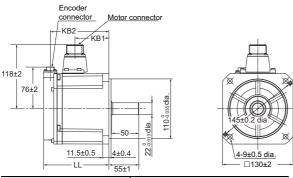
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



Model		Dimensions [mm]									
	QA	QK	W	Т	U	QE	LT				
R88M- 1M40020C-B(S2/OS2)	3	42	6-0.03	6	2.5 0	M5	12				
R88M- 1M60020C-B(S2/OS2)	3	42	6-0.03	6	2.5 0	M5	12				

1 kW/1.5 kW/2 kW (without Brake)

R88M-1M1K020C(-O/-S2/-OS2) R88M-1M1K520C(-O/-S2/-OS2) R88M-1M2K020C(-O/-S2/-OS2)

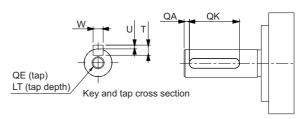


Model	Dir	mensions [m	ım]
Wodei	LL	KB1	KB2
R88M- 1M1K020C(-O/-S2/-OS2)	120.5±2	63±1	109±2
R88M- 1M1K520C(-O/-S2/-OS2)	138±2	79±1	125±2
R88M- 1M2K020C(-O/-S2/-OS2)	160±2	98±1	148±2

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

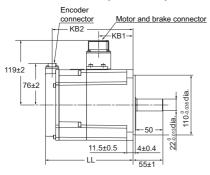
Shaft-end with key and tap

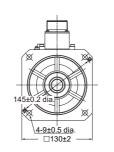


Model			Dimen	sions	s [mm]		
Wodei	QA	QK	W	Т	U	QE	LT
R88M- 1M1K020C(-S2/-OS2)	3	42	8-0.036	7	3-0.4	M5	12
R88M- 1M1K520C(-S2/-OS2)	3	42	8-0.036	7	3-0.4	M5	12
R88M- 1M2K020C(-S2/-OS2)	3	42	8-0.036	7	3-0.4	M5	12

1 kW/1.5 kW/2 kW (with Brake)

R88M-1M1K020C-B(O/S2/OS2) R88M-1M1K520C-B(O/S2/OS2) R88M-1M2K020C-B(O/S2/OS2)

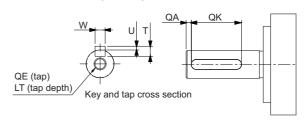




Model	Dir	mensions [m	ım]
Wodei	LL	KB1	KB2
R88M- 1M1K020C-B(O/S2/OS2)	162±2	64±1	150±2
R88M- 1M1K520C-B(O/S2/OS2)	179±2	81±1	167±2
R88M- 1M2K020C-B(O/S2/OS2)	201±3	99±1	189±2

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

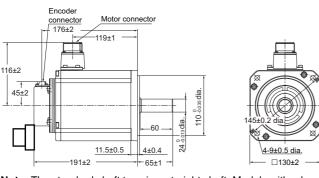
Models with an oil seal are indicated with "O" at the end of the model number.



Model			Dimen	sions	s [mm]		
Wodei	QA	QK	W	Т	U	QE	LT
R88M- 1M1K020C-B(S2/OS2)	3	42	8-0.036	7	3-0.4	M5	12
R88M- 1M1K520C-B(S2/OS2)	3	42	8-0.036	7	3-0.4	M5	12
R88M- 1M2K020C-B(S2/OS2)	3	42	8-0.036	7	3-0.4	M5	12

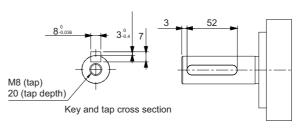
3 kW (without Brake)

R88M-1M3K020C(-O/-S2/-OS2)



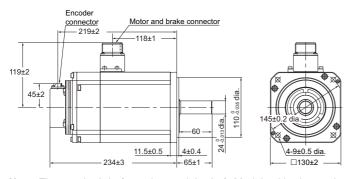
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



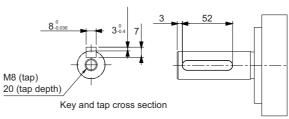
3 kW (with Brake)

R88M-1M3K020C-B(O/S2/OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

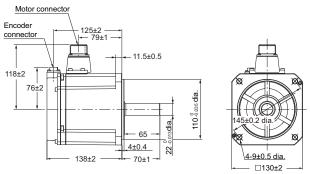
Models with an oil seal are indicated with "O" at the end of the model number.



1,000-r/min Servomotors (200 V)

900 W (without Brake)

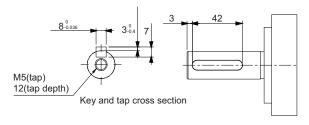
R88M-1M90010T(-O/-S2/-OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

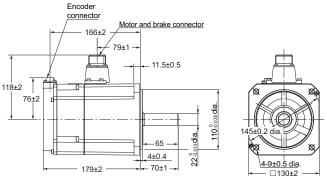
Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



900 W (with Brake)

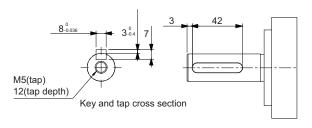
R88M-1M90010T-B(O/S2/OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

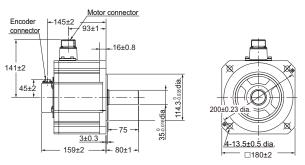
Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap

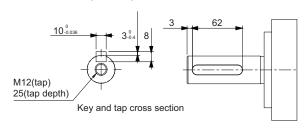


2 kW (without Brake)

R88M-1M2K010T(-O/-S2/-OS2)

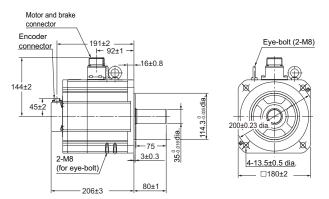


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



2 kW (with Brake)

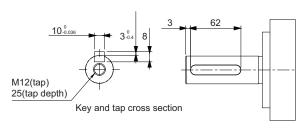
R88M-1M2K010T-B(O/S2/OS2)



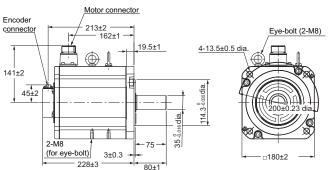
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



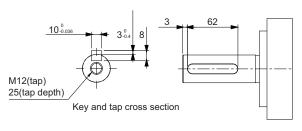
3 kW (without Brake) R88M-1M3K010T(-O/-S2/-OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

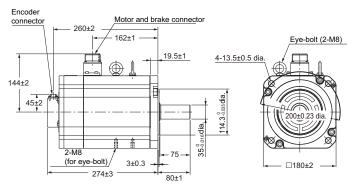
Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



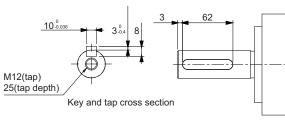
3 kW (with Brake)

R88M-1M3K010T-B(O/S2/OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

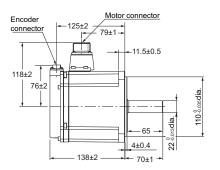
Models with an oil seal are indicated with "O" at the end of the model number.

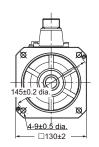


1,000-r/min Servomotors (400 V)

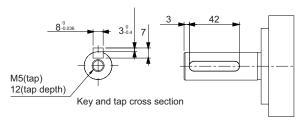
900 W (without Brake)

R88M-1M90010C(-O/-S2/-OS2)





Shaft-end with key and tap

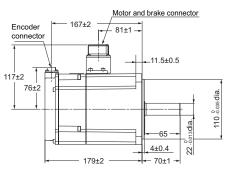


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

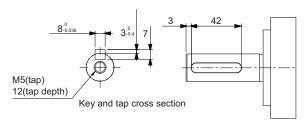
900 W (with Brake)

R88M-1M90010C-B(O/S2/OS2)





Shaft-end with key and tap

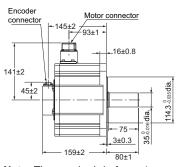


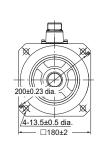
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

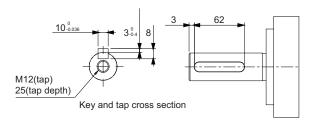
2 kW (without Brake)

R88M-1M2K010C(-O/-S2/-OS2)



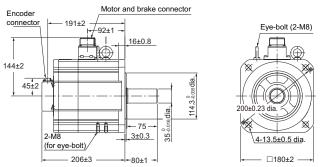


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



2 kW (with Brake)

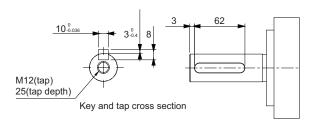
R88M-1M2K010C-B(O/S2/OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

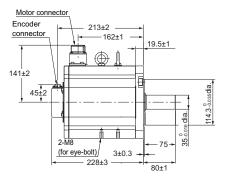
Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



3 kW (without Brake)

R88M-1M3K010C(-O/-S2/-OS2)

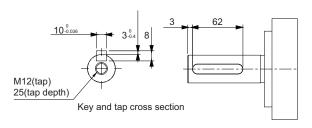




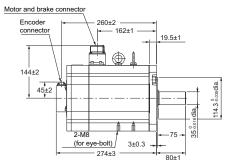
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



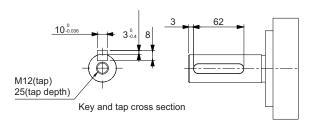
3 kW (with Brake) R88M-1M3K010C-B(O/S2/OS2)





Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.



MEMO

Decelerator AC Servo System [1S-series] R88G-HPG

Contents

- Ordering Information
- Specifications
- External Dimensions



Ordering Information

Refer to the Ordering Information.

Specifications

Backlash: 3 Arcminutes Max.

● For 3,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N⋅m	%	r/min	N⋅m	× 10 ⁻⁴ kg⋅m ²	N	N	kg
	1/5	R88G-HPG11B05100B□	600	1.2	77.0	1200	4.2	0.005	135	538	0.3
	1/11	R88G-HPG14A11100B□	272	2.5	72.1	545	9.0	0.06	280	1119	1.0
100 W (100 V)	1/21	R88G-HPG14A21100B□	142	5.2	77.8	285	17.5	0.05	340	1358	1.0
(100 1)	1/33	R88G-HPG20A33100B□	90	6.8	65.2	181	26.9	0.065	916	3226	2.4
	1/45	R88G-HPG20A45100B□	66	9.8	68.2	133	37.1	0.063	1006	3541	2.4
	1/5	R88G-HPG11B05100B□	600	1.2	77.0	1200	4.9	0.005	135	538	0.3
	1/11	R88G-HPG14A11100B□	272	2.5	72.1	545	10.6	0.06	280	1119	1.0
100 W (200 V)	1/21	R88G-HPG14A21100B□	142	5.2	77.8	285	20.7	0.05	340	1358	1.0
(200 1)	1/33	R88G-HPG20A33100B□	90	6.8	65.2	181	31.9	0.065	916	3226	2.4
	1/45	R88G-HPG20A45100B□	66	9.8	68.2	133	44.0	0.063	1006	3541	2.4
	1/5	R88G-HPG14A05200B□	600	2.4	75.4	1200	8.3	0.207	221	883	1.0
	1/11	R88G-HPG14A11200B□	272	5.8	82.6	545	18.8	0.197	280	1119	1.1
200 W (100 V)	1/21	R88G-HPG20A21200B□	142	10.2	76.2	285	35.9	0.49	800	2817	2.9
,	1/33	R88G-HPG20A33200B□	90	17.0	80.6	181	57.3	0.45	916	3226	2.9
	1/45	R88G-HPG20A45200B□	66	23.5	82.1	133	78.5	0.45	1006	3541	2.9
	1/5	R88G-HPG14A05200B□	600	2.4	75.4	1200	9.7	0.207	221	883	1.0
	1/11	R88G-HPG14A11200B□	272	5.8	82.6	545	21.8	0.197	280	1119	1.1
200 W (200 V)	1/21	R88G-HPG20A21200B□	142	10.2	76.2	285	41.7	0.49	800	2817	2.9
,	1/33	R88G-HPG20A33200B□	90	17.0	80.6	181	66.5	0.45	916	3226	2.9
	1/45	R88G-HPG20A45200B□	66	23.5	82.1	133	91.1	0.45	1006	3541	2.9
	1/5	R88G-HPG14A05400B□	600	5.3	84.2	1200	17.1	0.207	221	883	1.1
	1/11	R88G-HPG20A11400B□	272	11.4	81.6	545	38.1	0.57	659	2320	2.9
400 W (100 V)	1/21	R88G-HPG20A21400B□	142	23.0	86.1	285	74.0	0.49	800	2817	2.9
,,	1/33	R88G-HPG32A33400B□	90	33.8	80.7	181	114.0	0.62	1565	6240	7.5
	1/45	R88G-HPG32A45400B□	66	46.6	81.5	133	155.9	0.61	1718	6848	7.5

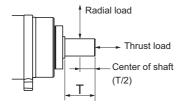
Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N⋅m	%	r/min	N⋅m	× 10 ⁻⁴ kg·m ²	N	N	kg
	1/5	R88G-HPG14A05400B□	600	5.3	84.2	1200	20.4	0.207	221	883	1.1
	1/11	R88G-HPG20A11400B□	272	11.4	81.6	545	45.5	0.57	659	2320	2.9
400 W (200 V)	1/21	R88G-HPG20A21400B□	142	23.0	86.1	285	88.1	0.49	800	2817	2.9
(,	1/33	R88G-HPG32A33400B□	90	33.8	80.7	181	136.2	0.62	1565	6240	7.5
	1/45	R88G-HPG32A45400B□	66	46.6	81.5	133	186.1	0.61	1718	6848	7.5
	1/5	R88G-HPG20A05750B□	600	9.9	82.9	1200	38.7	0.68	520	1832	2.9
	1/11	R88G-HPG20A11750B□	272	20.0 *1	87.2	545	86.7	0.6	659	2320	3.1
750 W (200 V)	1/21	R88G-HPG32A21750B□	142	42.1	84.0	285	163.3	3.0	1367	5448	7.8
(====,	1/33	R88G-HPG32A33750B□	90	69.3	87.9	181	259.7	2.7	1565	6240	7.8
	1/45	R88G-HPG32A45750B□	66	94.9	88.3	133	299.0 *2	2.7	1718	6848	7.8
	1/5	R88G-HPG32A052K0B□	600	7.7	64.3	1000	30.6	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B□	272	20.5	78.0	454	70.9	3.4	1126	4488	7.9
750 W (400 V)	1/21	R88G-HPG32A211K5B□	142	42.1	84.0	238	138.3	3.0	1367	5448	7.9
(400 V)	1/33	R88G-HPG32A33600SB□	90	69.3	87.9	151	220.4	2.7	1565	6240	7.9
	1/45	R88G-HPG50A451K5B□	66	92.0	85.5	111	298.0	4.7	4538	15694	19.0
	1/5	R88G-HPG32A052K0B□	600	11.5	72.2	1000	42.0	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B□	272	28.9	82.5	454	96.1	3.4	1126	4488	7.9
1 kW	1/21	R88G-HPG32A211K5B□	142	58.1	86.9	238	186.5	3.0	1367	5448	7.9
	1/33	R88G-HPG50A332K0B□	90	90.9	86.7	151	292.7	4.8	4135	14300	19.0
	1/45	R88G-HPG50A451K5B□	66	126.1	88.1	111	401.3	4.7	4538	15694	19.0
	1/5	R88G-HPG32A052K0B□	600	19.1	80.1	1000	64.8	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B□	272	45.7	87.0	454	146.3	3.4	1126	4488	7.9
1.5 kW	1/21	R88G-HPG32A211K5B□	142	90.1	90.0	238	282.2	3.0	1367	5448	7.9
	1/33	R88G-HPG50A332K0B□	90	141.3	89.8	151	443.2	4.8	4135	14300	19.0
	1/45	R88G-HPG50A451K5B□	66	194.8	90.8	111	606.5	4.7	4538	15694	19.0
	1/5	R88G-HPG32A052K0B□	600	26.8	84.1	1000	87.9	3.8	889	3542	7.4
2 kW	1/11	R88G-HPG32A112K0B□	272	62.5	89.3	454	197.0	3.4	1126	4488	7.9
Z KVV	1/21	R88G-HPG50A212K0B□	142	119.0	89.0	238	375.7	5.8	3611	12486	19.0
	1/33	R88G-HPG50A332K0B□	90	192.0	91.3	151	595.3	4.8	4135	14300	19.0
	1/5	R88G-HPG32A053K0B□	600	42.0	88.1	1000	134.0	3.8	889	3542	7.3
3 kW	1/11	R88G-HPG50A113K0B□	272	93.9	89.3	454	296.1	7.7	2974	10285	19.0
	1/21	R88G-HPG50A213K0B□	142	183.1	91.3	238	569.2	5.8	3611	12486	19.0

*1. The value is the allowable continuous output torque of the Decelerator. Take care so that this value is not exceeded.

*2. The value is the maximum allowable torque of the Decelerator. Take care so that this value is not exceeded.

Note: 1. The Decelerator inertia is the Servomotor shaft conversion value.

- 2. The protective structure rating of the Servomotor with the Decelerator is IP44.
- 3. The Allowable radial load column shows the values obtained at the center of the shaft (T/2).



- 4. The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the model number.
- 5. Take care so that the surface temperature of the Decelerator does not exceed 70°C.

● For 2,000-r/min Servomotors

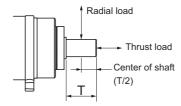
Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N⋅m	%	r/min	N⋅m	× 10 ⁻⁴ kg·m ²	N	N	kg
	1/5	R88G-HPG32A052K0B□	400	6.5	68.4	600	24.9	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B□	181	16.8	79.9	272	57.1	3.4	1126	4488	7.9
400 W	1/21	R88G-HPG32A211K5B□	95	34.0	84.9	142	111.1	3.0	1367	5448	7.9
	1/33	R88G-HPG32A33600SB□	60	55.6	88.2	90	176.6	2.7	1565	6240	7.9
	1/45	R88G-HPG32A45400SB□	44	76.0	88.5	66	241.1	2.7	1718	6848	7.9
	1/5	R88G-HPG32A052K0B□	400	11.1	77.6	600	38.6	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B□	181	26.8	85.3	272	87.3	3.4	1126	4488	7.9
600 W	1/21	R88G-HPG32A211K5B□	95	53.2	88.6	142	168.7	3.0	1367	5448	7.9
	1/33	R88G-HPG32A33600SB□	60	85.7	90.8	90	267.2	2.7	1565	6240	7.9
	1/45	R88G-HPG50A451K5B□	44	115.1	89.4	66	362.6	4.7	4538	15694	19.0
	1/5	R88G-HPG32A053K0B□	400	20.3	85.0	600	66.0	3.8	889	3542	7.3
	1/11	R88G-HPG32A112K0SB□	181	47.0	89.6	272	147.6	3.4	1126	4488	7.8
1 kW	1/21	R88G-HPG32A211K0SB□	95	91.7	91.5	142	283.8	2.9	1367	5448	7.8
	1/33	R88G-HPG50A332K0SB□	60	143.9	91.4	90	445.8	4.7	4135	14300	19.0
	1/45	R88G-HPG50A451K0SB□	44	197.6	92.1	66	609.3	4.7	4538	15694	19.0
	1/5	R88G-HPG32A053K0B□	400	31.7	88.7	600	100.6	3.8	889	3542	7.3
1.5 kW	1/11	R88G-HPG32A112K0SB□	181	72.2	91.7	272	223.7	3.4	1126	4488	7.8
1.5 KW	1/21	R88G-HPG50A213K0B□	95	137.6	91.5	142	426.7	5.8	3611	12486	19.0
	1/33	R88G-HPG50A332K0SB□	60	219.6	92.9	90	673.9	4.7	4135	14300	19.0
	1/5	R88G-HPG32A053K0B□	400	43.2	90.5	600	135.1	3.8	889	3542	7.3
2 kW	1/11	R88G-HPG32A112K0SB□	181	97.5	92.8	272	299.7	3.4	1126	4488	7.8
Z KVV	1/21	R88G-HPG50A213K0B□	95	185.8	92.7	142	571.9	5.8	3611	12486	19.0
	1/33	R88G-HPG50A332K0SB□	60	270.0 *1	93.5	90	849.0 *2	4.7	4135	14300	19.0
	1/5	R88G-HPG32A054K0B□	400	66.0	92.3	600	203.8	3.8	889	3542	7.9
3 kW	1/11	R88G-HPG50A115K0B□	181	146.1	92.9	272	449.2	8.8	2974	10285	19.1
3 KVV	1/21	R88G-HPG50A213K0SB□	95	260.0 *1	93.6	142	849.0 *2	6.9	3611	12486	19.1
	1/25	R88G-HPG65A253K0SB□	80	322.9	90.3	120	1011.7	14	7846	28654	52.0

*1. The value is the allowable continuous output torque of the Decelerator. Take care so that this value is not exceeded.

*2. The value is the maximum allowable torque of the Decelerator. Take care so that this value is not exceeded.

Note: 1. The Decelerator inertia is the Servomotor shaft conversion value.

- 2. The protective structure rating of the Servomotor with the Decelerator is IP44.
- 3. The Allowable radial load column shows the values obtained at the center of the shaft (T/2).



- 4. The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at \square of the model number.
- 5. Take care so that the surface temperature of the Decelerator does not exceed 70°C.

For 1,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N⋅m	%	r/min	N⋅m	× 10 ⁻⁴ kg·m ²	N	N	kg
	1/5	R88G-HPG32A05900TB□	200	39.8	92.6	400	91.2	3.8	889	3542	7.9
900 W	1/11	R88G-HPG32A11900TB□	90	88.7	93.9	181	201.8	3.4	1126	4488	8.4
900 W	1/21	R88G-HPG50A21900TB□	47	169.2	93.8	95	385.1	7.0	3611	12486	19.1
	1/33	R88G-HPG50A33900TB□	30	267.5	94.4	60	606.8	5.9	4135	14300	19.1
	1/5	R88G-HPG32A052K0TB□	200	90.2	94.5	400	227.5	5.2	889	3542	8.90
2 kW	1/11	R88G-HPG50A112K0TB□	90	198.9	94.7	181	500.9	8.4	2974	10285	20.1
2 KVV	1/21	R88G-HPG50A212K0TB□	47	320.1 *1	94.8	95	849.0 *2	6.5	3611	12486	20.1
	1/25	R88G-HPG65A255K0SB□	40	446.7	93.6	80	1133.1	14	7846	28654	55.4
	1/5	R88G-HPG50A055K0SB□	200	135.4	94.4	400	341.8	11	2347	8118	22.0
0.1-14/	1/11	R88G-HPG50A115K0SB□	90	246.2 *1	94.9	181	754.4	8.4	2974	10285	23.5
3 kW	1/20	R88G-HPG65A205K0SB□	50	540.4	94.2	100	1366.0	14	7338	26799	55.4
	1/25	R88G-HPG65A255K0SB□	40	677.1	94.4	80	1709.1	14	7846	28654	55.4

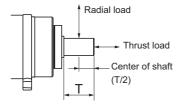
*1. The value is the allowable continuous output torque of the Decelerator. Take care so that this value is not exceeded.

*2. The value is the maximum allowable torque of the Decelerator. Take care so that this value is not exceeded.

Note: 1. The Decelerator inertia is the Servomotor shaft conversion value.

2. The protective structure rating of the Servomotor with the Decelerator is IP44.

3. The Allowable radial load column shows the values obtained at the center of the shaft (T/2).



- **4.** The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at \square of the model number. **5.** Take care so that the surface temperature of the Decelerator does not exceed 70°C.

External Dimensions (Unit: mm)

Backlash: 3 Arcminutes Max.

• For 3,000-r/min Servomotors (100 to 200 W)

									Dimen	sions [mm]					
Servomotor rated output	Reduction ratio	Model	Outline drawing	LM	LR	C1	C2	D1	D2	D3	D4	D5	D6	E	F1	F2
	1/5	R88G-HPG11B05100B□	1*	39.5	42	40	40 × 40	46	46	40	39.5	29		27	2.2	15
	1/11	R88G-HPG14A11100B□	1	64.0	58	60	60 × 60	70	46	56	55.5	40		37	2.5	21
100 W	1/21	R88G-HPG14A21100B□	1	64.0	58	60	60 × 60	70	46	56	55.5	40		37	2.5	21
	1/33	R88G-HPG20A33100B□	2	66.5	80	90	55 dia.	105	46	85	84	59		53	7.5	27
	1/45	R88G-HPG20A45100B□	2	66.5	80	90	55 dia.	105	46	85	84	59		53	7.5	27
	1/5	R88G-HPG14A05200B□	1	64.0	58	60	60×60	70	70	56	55.5	40	-	37	2.5	21
	1/11	R88G-HPG14A11200B□	1	64.0	58	60	60×60	70	70	56	55.5	40	-	37	2.5	21
200 W	1/21	R88G-HPG20A21200B□	2	71.0	80	90	89 dia.	105	70	85	84	59	-	53	7.5	27
	1/33	R88G-HPG20A33200B□	2	71.0	80	90	89 dia.	105	70	85	84	59		53	7.5	27
	1/45	R88G-HPG20A45200B□	2	71.0	80	90	89 dia.	105	70	85	84	59		53	7.5	27

*Two set bolts are positioned at 90° from each other.

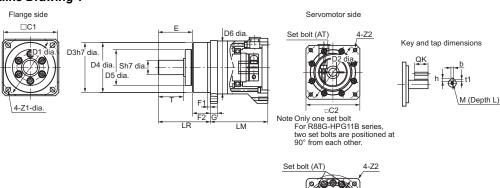
Note: 1. The standard shaft type is a straight shaft.

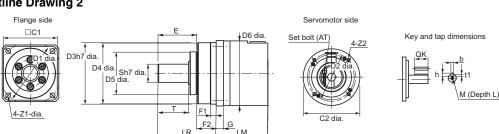
- A model with a key and tap is indicated with "J" at □ of the model number. (Example: R88G-HPG11B05100BJ)
- 3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
- 4. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.
- 5. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.

							D	imensior	ns [mm]						
Servomotor rated output	Reduction ratio	Model	G	s	_	Z 1	Z2	AT *1		K	еу		Тар		
ratea output	Tatio		G	5	'	21		AITI	QK	b	h	t1	M	L	
	1/5	R88G-HPG11B05100B□	5	8	20	3.4	M4 × 9	МЗ	15	3	3	1.8	МЗ	6	
	1/11	R88G-HPG14A11100B□	8	16	28	5.5	M4 × 10	М3	25	5	5	3	M4	8	
100 W	1/21	R88G-HPG14A21100B□	8	16	28	5.5	M4 × 10	М3	25	5	5	3	M4	8	
	1/33	R88G-HPG20A33100B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12	
	1/45	R88G-HPG20A45100B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12	
	1/5	R88G-HPG14A05200B□	8	16	28	5.5	M4 × 10	M4	25	5	5	3	M4	8	
	1/11	R88G-HPG14A11200B□	8	16	28	5.5	M4 × 10	M4	25	5	5	3	M4	8	
200 W	1/21	R88G-HPG20A21200B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12	
	1/33	R88G-HPG20A33200B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12	
	1/45	R88G-HPG20A45200B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12	

*1. Indicates set bolt.

Outline Drawing 1





● For 3,000-r/min Servomotors (400 to 750 W)

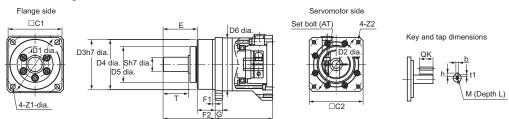
Servomotor		Model	Outline						Dimen	sions [mm]					
rated output	ratio	Woder	drawing	LM	LR	C1	C2	D1	D2	D3	D4	D5	D6	Е	F1	F2
	1/5	R88G-HPG14A05400B□	1	64	58	60	60 × 60	70	70	56	55.5	40		37	2.5	21
	1/11	R88G-HPG20A11400B□	2	71	80	90	89 dia.	105	70	85	84	59		53	7.5	27
400 W	1/21	R88G-HPG20A21400B□	2	71	80	90	89 dia.	105	70	85	84	59		53	7.5	27
	1/33	R88G-HPG32A33400B□	2	104	133	120	122 dia.	135	70	115	114	84		98	12.5	35
	1/45	R88G-HPG32A45400B□	2	104	133	120	122 dia.	135	70	115	114	84		98	12.5	35
	1/5	R88G-HPG20A05750B□	1	78	80	90	80 × 80	105	90	85	84	59	89	53	7.5	27
750 W	1/11	R88G-HPG20A11750B□	1	78	80	90	80 × 80	105	90	85	84	59	89	53	7.5	27
750 W (200 V)	1/21	R88G-HPG32A21750B□	2	104	133	120	122 dia.	135	90	115	114	84		98	12.5	35
(==== 1)	1/33	R88G-HPG32A33750B□	2	104	133	120	122 dia.	135	90	115	114	84		98	12.5	35
	1/45	R88G-HPG32A45750B□	2	104	133	120	122 dia.	135	90	115	114	84		98	12.5	35
	1/5	R88G-HPG32A052K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
750 W	1/11	R88G-HPG32A112K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
750 W (400 V)	1/21	R88G-HPG32A211K5B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
(400 V)	1/33	R88G-HPG32A33600SB□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/45	R88G-HPG50A451K5B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53

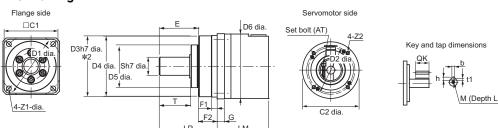
Note: 1. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.
2. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.

							D	imensior	ns [mm]					
Servomotor rated output	Reduction ratio	Model	G	s	т	Z 1	Z 2	AT *1		K	еу		Ta	ар
raica oatpat	latio		G	5	'	21		AI TI	QK	b	h	t1	М	L
	1/5	R88G-HPG14A05400B□	8	16	28	5.5	M4 × 10	M4	25	5	5	3	M4	8
	1/11	R88G-HPG20A11400B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
400 W	1/21	R88G-HPG20A21400B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
	1/33	R88G-HPG32A33400B□	13	40	82	11	M4 × 10	M4	70	12	8	5	M10	20
	1/45	R88G-HPG32A45400B□	13	40	82	11	M4 × 10	M4	70	12	8	5	M10	20
750.14	1/5	R88G-HPG20A05750B□	10	25	42	9	M5 × 12	M4	36	8	7	4	M6	12
	1/11	R88G-HPG20A11750B□	10	25	42	9	M5 × 12	M4	36	8	7	4	M6	12
750 W (200 V)	1/21	R88G-HPG32A21750B□	13	40	82	11	M5 × 12	M6	70	12	8	5	M10	20
(200 1)	1/33	R88G-HPG32A33750B□	13	40	82	11	M5 × 12	M6	70	12	8	5	M10	20
	1/45	R88G-HPG32A45750B□	13	40	82	11	M5 × 12	M6	70	12	8	5	M10	20
	1/5	R88G-HPG32A052K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
750 W (400 V)	1/21	R88G-HPG32A211K5B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/33	R88G-HPG32A33600SB□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/45	R88G-HPG50A451K5B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20

^{*1.} Indicates set bolt.

Outline Drawing 1





***2.** The tolerance is "h8" for R88G-HPG50□.

• For 3,000-r/min Servomotors (1 to 3 kW)

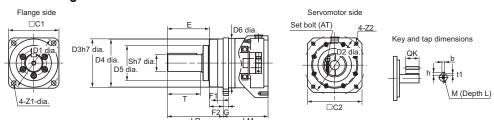
Servomotor	Reduction	Model	Outline						Dimens	sions [r	nm]					
rated output	ratio	woder	drawing	LM	LR	C1	C2	D1	D2	D3	D4	D5	D6	Е	F1	F2
	1/5	R88G-HPG32A052K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/11	R88G-HPG32A112K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
1 kW	1/21	R88G-HPG32A211K5B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/33	R88G-HPG50A332K0B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/45	R88G-HPG50A451K5B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/5	R88G-HPG32A052K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
1.5 kW	1/11	R88G-HPG32A112K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/21	R88G-HPG32A211K5B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/33	R88G-HPG50A332K0B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/45	R88G-HPG50A451K5B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/5	R88G-HPG32A052K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
2 kW	1/11	R88G-HPG32A112K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
Z KVV	1/21	R88G-HPG50A212K0B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/33	R88G-HPG50A332K0B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/5	R88G-HPG32A053K0B□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
3 kW	1/11	R88G-HPG50A113K0B□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53
	1/21	R88G-HPG50A213K0B□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53

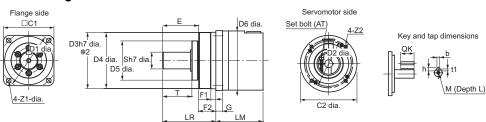
- Note: 1. The standard shaft type is a straight shaft.
 - A model with a key and tap is indicated with "J" at □ of the model number. Example: R88G-HPG32A051K0BJ
 - 3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
 - 4. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.
 - 5. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.

	5.1						D	imensior	ns [mm]					
Servomotor rated output	Reduction ratio	Model	G	s	_	Z 1	Z2	AT *1		K	е у		Ta	ар
raica oaipai	ratio		G	3	•	21		ΑΙ ΦΙ	QK	b	h	t1	М	L
	1/5	R88G-HPG32A052K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
1 kW	1/21	R88G-HPG32A211K5B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/33	R88G-HPG50A332K0B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/45	R88G-HPG50A451K5B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/5	R88G-HPG32A052K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
1.5 kW	1/11	R88G-HPG32A112K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/21	R88G-HPG32A211K5B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/33	R88G-HPG50A332K0B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/45	R88G-HPG50A451K5B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/5	R88G-HPG32A052K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
2 kW	1/11	R88G-HPG32A112K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
Z RVV	1/21	R88G-HPG50A212K0B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/33	R88G-HPG50A332K0B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/5	R88G-HPG32A053K0B□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
3 kW	1/11	R88G-HPG50A113K0B□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
J KW	1/21	R88G-HPG50A213K0B□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20

*1. Indicates set bolt.

Outline Drawing 1





***2.** The tolerance is "h8" for R88G-HPG50□.

● For 2,000-r/min Servomotors (400 W to 1 kW)

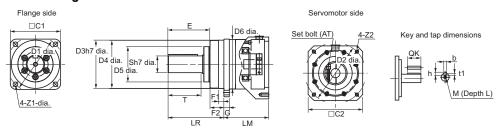
Servomotor	Reduction	Model	Outline						Dimens	ions [r	nm]					
rated output	ratio	Woder	drawing	LM	LR	C1	C2	D1	D2	D3	D4	D5	D6	E	F1	F2
	1/5	R88G-HPG32A052K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
400 111	1/11	R88G-HPG32A112K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
400 W (400 V)	1/21	R88G-HPG32A211K5B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
(400 1)	1/33	R88G-HPG32A33600SB□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/45	R88G-HPG32A45400SB□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
600 W (400 V)	1/5	R88G-HPG32A052K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/11	R88G-HPG32A112K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/21	R88G-HPG32A211K5B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
(,	1/33	R88G-HPG32A33600SB□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/45	R88G-HPG50A451K5B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/5	R88G-HPG32A053K0B□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
	1/11	R88G-HPG32A112K0SB□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
1 kW	1/21	R88G-HPG32A211K0SB□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
	1/33	R88G-HPG50A332K0SB□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53
	1/45	R88G-HPG50A451K0SB□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53

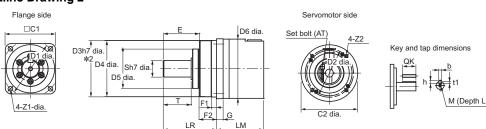
- Note: 1. The standard shaft type is a straight shaft.
 - 2. A model with a key and tap is indicated with "J" at □ of the model number. (Example: R88G-HPG32A053K0BJ)
 - 3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
 - 4. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.
 5. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is
 - 5. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.

							D	imensior	ns [mm]					
Servomotor rated output	Reduction ratio	Model	G	s	т	Z 1	Z2	AT *1		Ke	Э у		Ta	ap
raica output	Tauo		G	3		21		AIAI	QK	b	h	t1	M	L
	1/5	R88G-HPG32A052K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
400 W	1/11	R88G-HPG32A112K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
400 W (400 V)	1/21	R88G-HPG32A211K5B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
1/33	1/33	R88G-HPG32A33600SB□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/45	R88G-HPG32A45400SB□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/5	R88G-HPG32A052K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
COO W	1/11	R88G-HPG32A112K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
600 W (400 V)	1/21	R88G-HPG32A211K5B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
(400 1)	1/33	R88G-HPG32A33600SB□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/45	R88G-HPG50A451K5B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/5	R88G-HPG32A053K0B□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0SB□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
1 kW	1/21	R88G-HPG32A211K0SB□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
	1/33	R88G-HPG50A332K0SB□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/45	R88G-HPG50A451K0SB□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20

*1. Indicates set bolt.

Outline Drawing 1





***2.** The tolerance is "h8" for R88G-HPG50□.

● For 2,000-r/min Servomotors (1.5 to 3 kW)

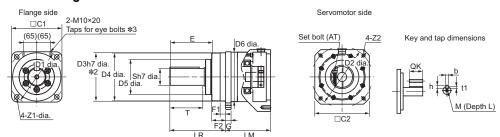
Servomotor	Reduction	Model	Outline					C	imens	ions [m	m]					
rated output	ratio	woder	drawing	LM	LR	C1	C2	D1	D2	D3	D4	D5	D6	E	F1	F2
	1/5	R88G-HPG32A053K0B□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
1.5 kW	1/11	R88G-HPG32A112K0SB□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
1.5 KW	1/21	R88G-HPG50A213K0B□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53
	1/33	R88G-HPG50A332K0SB□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53
	1/5	R88G-HPG32A053K0B□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
2 kW	1/11	R88G-HPG32A112K0SB□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
Z KVV	1/21	R88G-HPG50A213K0B□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53
	1/33	R88G-HPG50A332K0SB□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53
	1/5	R88G-HPG32A054K0B□	1	129	133	120	130 × 130	135	145	115	114	84		98	12.5	35
3 kW	1/11	R88G-HPG50A115K0B□	1	149	156	170	130 × 130	190	145	165	163	122		103	12	53
3 KW	1/21	R88G-HPG50A213K0SB□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
	1/25	R88G-HPG65A253K0SB□	1	231	222	230	130 × 130	260	145	220	214	168	170	165	12	57

Note: 1. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.
 D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.

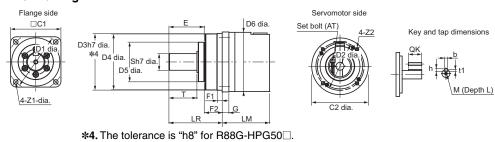
							D	imensior	ns [mm]					
Servomotor rated output	Reduction ratio	Model	G	s	_	Z 1	Z 2	AT *1		K	еу		Ta	ар
ratou output	lutio		"	3	'	21		ΑΙΦΙ	QK	b	h	t1	М	L
	1/5	R88G-HPG32A053K0B□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
1.5 kW	1/11	R88G-HPG32A112K0SB□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
1.5 KW	1/21	R88G-HPG50A213K0B□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/33	R88G-HPG50A332K0SB□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/5	R88G-HPG32A053K0B□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
2 kW	1/11	R88G-HPG32A112K0SB□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
2 KVV	1/21	R88G-HPG50A213K0B□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/33	R88G-HPG50A332K0SB□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/5	R88G-HPG32A054K0B□	13	40	82	11	M8 × 25	M6	70	12	8	5	M10	20
2 14/1/	1/11	R88G-HPG50A115K0B□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
3 kW	1/21	R88G-HPG50A213K0SB□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
	1/25	R88G-HPG65A253K0SB□	25	80	130	18	M8 × 25	M8	110	22	14	9	M16	35

*1. Indicates set bolt.

Outline Drawing 1



- ***2.** The tolerance is "h8" for R88G-HPG50□ and R88G-HPG65□.
- ***3.** The model R88G-HPG65□ has the taps for eye bolts.



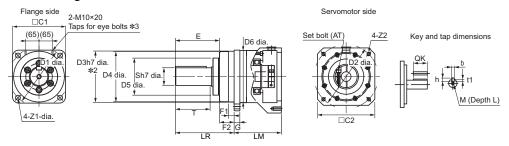
● For 1,000-r/min Servomotors (900 W to 3 kW)

Servomotor	Reduction	Model	Outline						Dimens	ions [m	ım]					
rated output	ratio	Woder	drawing	LM	LR	C1	C2	D1	D2	D3	D4	D5	D6	E	F1	F2
	1/5	R88G-HPG32A05900TB□	1	129	133	120	130 × 130	135	145	115	114	84		98	12.5	35
900 W	1/11	R88G-HPG32A11900TB□	1	129	133	120	130 × 130	135	145	115	114	84		98	12.5	35
900 W	1/21	R88G-HPG50A21900TB□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
	1/33	R88G-HPG50A33900TB□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
		R88G-HPG32A052K0TB□	1	129	133	120	180 × 180	135	200	115	114	84		98	12.5	35
2 kW	1/11	R88G-HPG50A112K0TB□	1	149	156	170	180 × 180	190	200	165	163	122		103	12	53
2 RVV	1/21	R88G-HPG50A212K0TB□	1	149	156	170	180 × 180	190	200	165	163	122		103	12	53
	1/25	R88G-HPG65A255K0SB□	1	231	222	230	180 × 180	260	200	220	214	168	220	165	12	57
	1/5	R88G-HPG50A055K0SB□	1	149	156	170	180 × 180	190	200	165	163	122		103	12	53
3 kW	1/11	R88G-HPG50A115K0SB□	1	149	156	170	180 × 180	190	200	165	163	122		103	12	53
3 KVV	1/20	R88G-HPG65A205K0SB□	1	231	222	230	180 × 180	260	200	220	214	168	220	165	12	57
	1/25	R88G-HPG65A255K0SB□	1	231	222	230	180 × 180	260	200	220	214	168	220	165	12	57

- Note: 1. The standard shaft type is a straight shaft.
 - 2. A model with a key and tap is indicated with "J" at □ of the model number. (Example: R88G-HPG32A05900TBJ)
 - 3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
 - 4. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.
 - 5. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.

							Di	imensior	ns [mm]					
Servomotor rated output	Reduction ratio	Model	G	s	-	Z 1	Z2	AT *1		K	еу		Ta	ар
ratea output	Tauo		G	5	•	21		AITI	QK	b	h	t1	М	L
	1/5	R88G-HPG32A05900TB□	13	40	82	11	M8 × 25	M6	70	12	8	5	M10	20
900 W	1/11	R88G-HPG32A11900TB□	13	40	82	11	M8 × 25	M6	70	12	8	5	M10	20
900 W	1/21	R88G-HPG50A21900TB□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
	1/33	R88G-HPG50A33900TB□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
2 kW	1/5	R88G-HPG32A052K0TB□	13	40	82	11	M12 × 25	M6	70	12	8	5	M10	20
	1/11	R88G-HPG50A112K0TB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
2 KW	1/21	R88G-HPG50A212K0TB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
	1/25	R88G-HPG65A255K0SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35
	1/5	R88G-HPG50A055K0SB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
3 kW	1/11	R88G-HPG50A115K0SB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
3 KW	1/20	R88G-HPG65A205K0SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35
	1/25	R88G-HPG65A255K0SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35

*1. Indicates set bolt.



- ***2.** The tolerance is "h8" for R88G-HPG50 \square and R88G-HPG65 \square .
- ***3.** The model R88G-HPG65 has the taps for eye bolts.

MEMO

Ordering Information

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Interpreting Model Numbers

AC Servo Drives with Built-in EtherCAT **Communications**

R88D-1S N 01 H -ECT

(2) (3) (4)

No	Item	Symbol	Specifications
(1)	1S-series Servo Driv	/e	
(2)	Servo Drive Type	N	Communication type
		01	100 W
		02	200 W
		04	400 W
	Applicable	06	600 W
(3)	Servomotor	08	750 W
	rated output	10	1 kW
		15	1.5 kW
		20	2 kW
		30	3 kW
		L	100 VAC
(4)	Power Supply Voltage	Н	200 VAC
	· onago	F	400 VAC
(5)	Communications type	ECT	EtherCAT Communications

AC Servomotor

R88M-1 M 100 30 S -BOS2

(2)

(3) (4) (5)

No	Item	Oh al	On a Mination a
		Symbol	Specifications
(1)	1S-series Servomot		
(2)	Servomotor Type	L	Low inertia
	,,	М	Middle inertia
		100	100 W
		200	200 W
		400	400 W
		600	600 W
(2)	Poted output	750	750 W
(3)	Rated output	900	900 W
		1K0	1 kW
		1K5	1.5 kW
		2K0	2 kW
		3K0	3 kW
-		10	1,000 r/min
(4)	Rated rotation speed	20	2,000 r/min
	Ороса	30	3,000 r/min
-	Servo Drive main	S	100 VAC absolute encoder
(5)	power supply voltage and	Т	200 VAC absolute encoder
	encoder type	С	400 VAC absolute encoder
	Options		
	Brake	None	Without brake
	Diake	В	With 24-VDC brake
(6)	Oileasi	None	Without oil seal
	Oil seal	0	With oil seal
	Kay and tan	None	Straight shaft
	Key and tap	S2	With key and tap

Decelerator

$\underset{(1)}{\textbf{R88G-HPG}} \ \underset{(2)}{\overset{\textbf{14A}}{\cancel{05}}} \ \underset{(3)}{\overset{\textbf{05}}{\cancel{05}}} \ \underset{(4)}{\overset{\textbf{100}}{\cancel{05}}} \ \underset{(5)}{\overset{\textbf{B}}{\cancel{05}}} \ \underset{(7)}{\overset{\textbf{J}}{\cancel{05}}}$

(1) Decelerator for Servomotor Backlash: 3 Arcminutes max. 11B	No	Item	Symbol	Specifications
(2) Flange size number 14A	(1)	Decelerator for Serv	omotor Bad	cklash: 3 Arcminutes max.
(2) Flange size number 20A		11B	40 × 40	
(2) Interest Size number 32A 120 × 120 50A 170 × 170 65A 230 × 230 05 1/5 11 1/11 20 1/20 (3) Reduction ratio 21 1/21 25 1/25 33 1/33 45 1/45 100 100 W 200 200 W 400 400 W 600 600 W 750 750 W 900 900 W (4) Applicable Servomotor rated output * 1K5 1.5 kW 2K0 2 kW 3K0 3 kW 4K0 4 kW 5K0 5 kW None 3,000-r/min Servomotors			14A	60 × 60
100 100	(2)	Flange size	20A	90 × 90
(4) Applicable Servomotor rated output ★ Applicable Servomotor rated output ★ (4) Servomotor rated output ★ (4) Servomotor rated output ★ (5) Control of the control output ★ (6) Control output ★ (6) Control output ★ (6) Control output ★ (7) Control output ★ (8) Control output ★ (8) Control output ★ (9) Control output ★ (10) Control output ★ (11) Control output ★ (11) Control output ★ (12) Control output ★ (13) Reduction ratio (14) Control output ★ (14) Control output ★ (15) Control output ★ (15) Control output ★ (16) Control output ★ (17) Control output ★ (17) Control output ★ (18) Control output ★ (18) Control output ★ (18) Control output ★ (19) Control output ★ (19) Control output ★ (10) Control output ★ (11) Control output ★ (12) Control output ★ (13) Control output ★ (14) Control output ★ (15) Control output ★ (15) Control output ★ (16) Control output ★ (17) Control output ★ (17) Control output ★ (18) Contro	(2)	number	32A	120 × 120
(3) Reduction ratio Reduction ratio 11	1.0.		50A	170 × 170
(3) Reduction ratio 11			65A	230 × 230
(3) Reduction ratio 20 1/20 21 1/21 25 1/25 33 1/33 45 1/45 100 100 W 200 200 W 400 400 W 600 600 W 750 750 W 900 900 W 1K0 1 kW 1K5 1.5 kW 2K0 2 kW 3K0 3 kW 4K0 4 kW 5K0 5 kW None 3,000-r/min Servomotors			05	1/5
(3) Reduction ratio 21			11	1/11
25 1/25 33 1/33 45 1/45 100 100 W 200 200 W 400 400 W 600 600 W 750 750 W 900 900 W 1K0 1 kW 1K5 1.5 kW 2K0 2 kW 3K0 3 kW 4K0 4 kW 5K0 5 kW None 3,000-r/min Servomotors			20	1/20
33	(3)	Reduction ratio	21	1/21
45 1/45 100 100 W 200 200 W 400 400 W 600 600 W 750 750 W 900 900 W 1K0 1 kW 1K5 1.5 kW 2K0 2 kW 3K0 3 kW 4K0 4 kW 5K0 5 kW None 3,000-r/min Servomotors			25	1/25
Applicable Servomotor rated output *			33	1/33
(4) Applicable Servomotor rated output ★ 1K5 1.5 kW 2K0 2 kW 3K0 4 kW 5K0 5 kW None 3,000-r/min Servomotors			45	1/45
400 400 W 600 600 W 750 750 W Servomotor rated output 1K0 1 kW 1K5 1.5 kW 2K0 2 kW 3K0 3 kW 4K0 4 kW 5K0 5 kW None 3,000-r/min Servomotors			100	100 W
(4) Applicable Servomotor rated output ★ 900 900 W 1K0 1 kW 1K5 1.5 kW 2K0 2 kW 3K0 3 kW 4K0 4 kW 5K0 5 kW None 3,000-r/min Servomotors			200	200 W
(4) Applicable Servomotor rated output ★			400	400 W
(4) Applicable Servomotor rated output * 900 900 W 1K0 1 kW 1K5 1.5 kW 2K0 2 kW 3K0 3 kW 4K0 4 kW 5K0 5 kW None 3,000-r/min Servomotors			600	600 W
(4) Servomotor rated output * 1KO 1 kW 1K5 1.5 kW 2K0 2 kW 3K0 3 kW 4K0 4 kW 5K0 5 kW None 3,000-r/min Servomotors			750	750 W
output * 1K0 1 kW 1K5 1.5 kW 2K0 2 kW 3K0 3 kW 4K0 4 kW 5K0 5 kW None 3,000-r/min Servomotors	(4)		900	900 W
1K5 1.5 kW 2K0 2 kW 3K0 3 kW 4K0 4 kW 5K0 5 kW None 3,000-r/min Servomotors	(4)		1K0	1 kW
3K0 3 kW 4K0 4 kW 5K0 5 kW None 3,000-r/min Servomotors		output in	1K5	1.5 kW
4K0 4 kW 5K0 5 kW None 3,000-r/min Servomotors			2K0	2 kW
5K0 5 kW None 3,000-r/min Servomotors			3K0	3 kW
None 3,000-r/min Servomotors			4K0	4 kW
			5K0	5 kW
(5) Motor type S 2.000-r/min Servemeters			None	3,000-r/min Servomotors
(-,	(5)	Motor type	S	2,000-r/min Servomotors
T 1,000-r/min Servomotors			Т	1,000-r/min Servomotors
(6) Backlash B Backlash: 3 Arcminutes max.	(6)	Backlash	В	Backlash: 3 Arcminutes max.
None Straight shaft	(7)	Ontion	None	Straight shaft
(7) Option J With key and tap	(7)	Option	J	With key and tap

^{*} This is based on the rated output of a typical applicable Servomotor.
For the selection, check the Servomotor and Decelerator Combination Tables.

Table of AC Servomotor Variations

R88M-1					- 🗌		
	(2)	(3)	(4)	(5)	(6)	(7)	(8)

(2)	(3)	(4)			(5)		(6	5)	(7	7)	3)	3)	
				Power su	ipply spec	ifications							
T	Rated	Datation and	Model	ABS	ABS	ABS	Bra	ike	Oil	seal	Shaft	type	
Туре	output	Rotation speed		400	200	100							
				С	Т	S	None	В	None	0	None	S2	
	100 W		R88M-1M10030		1	1	/	1	1	✓	1	/	
М	200 W		R88M-1M20030		1	1	1	1	1	/	1	✓	
IVI	400 W		R88M-1M40030		1	1	/	1	1	/	1	/	
	750 W		R88M-1M75030		1		/	1	1	✓	1	✓	
	750 W	3,000 r/min	R88M-1L75030	1			/	1	1	1	1	✓	
	1 kW		R88M-1L1K030	1	1		/	1	1	/	1	/	
L	1.5 kW		R88M-1L1K530	1	1		/	1	1	✓	1	✓	
	2 kW		R88M-1L2K030	1	1		/	1	1	1	1	✓	
	3 kW		R88M-1L3K030	1	1		/	1	1	✓	1	✓	
	400 W		R88M-1M40020	1			/	1	1	✓	1	✓	
	600 W		R88M-1M60020	1			/	1	1	/	1	/	
М	1 kW	0.000 -/	R88M-1M1K020	1	1		/	1	1	✓	1	✓	
IVI	1.5 kW	2,000 r/min	R88M-1M1K520	1	1		/	1	1	1	1	✓	
	2 kW		R88M-1M2K020	1	1		1	/	1	/	1	/	
	3 kW		R88M-1M3K020	1	1		/	1	1	1	1	/	
	900 W		R88M-1M90010	1	1		/	1	1	1	1	✓	
M	2 kW	1,000 r/min	R88M-1M2K010	1	1		1	/	1	/	1	/	
	3 kW		R88M-1M3K010	1	1		/	1	1	1	1	/	
M:Middle inertia L:Low inertia	100: 100 W 1K0: 1 kW 3K0: 3 kW	10: 1,000 r/min 20: 2,000 r/min 30: 3,000 r/min		C: 400 VAC (with absolute encoder) ABS/INC T: 200 VAC (with absolute encoder) ABS/INC S: 100 VAC (with absolute encoder) ABS/INC		None: Without brake B: With 24-VDC brake		None: Without oil seal O: With oil seal		None: Straight shaft S2: With key and tap			

Ordering Information

AC Servo Drives with Built-in EtherCAT Communications

Power supply voltage	Rated output	Model
	100 W	R88D-1SN01L-ECT
Single-phase 100 VAC	200 W	R88D-1SN02L-ECT
	400 W	R88D-1SN04L-ECT
	100 W	R88D-1SN01H-ECT
	200 W	R88D-1SN02H-ECT
Single-phase/3-phase 200 VAC	400 W	R88D-1SN04H-ECT
	750 W	R88D-1SN08H-ECT
	1.5 kW	R88D-1SN15H-ECT
	1 kW	R88D-1SN10H-ECT
3-phase 200 VAC	2 kW	R88D-1SN20H-ECT
	3 kW	R88D-1SN30H-ECT
	600 W	R88D-1SN06F-ECT
	1 kW	R88D-1SN10F-ECT
3-phase 400 VAC	1.5 kW	R88D-1SN15F-ECT
	2 kW	R88D-1SN20F-ECT
	3 kW	R88D-1SN30F-ECT

AC Servomotors

• 3,000-r/min Servomotors

		Model					
Sp	Specifications		Without oil seal				
			Straight shaft	With key and tap			
		100 W	R88M-1M10030S	R88M-1M10030S-S2			
	100 VAC	200 W	R88M-1M20030S	R88M-1M20030S-S2			
		400 W	R88M-1M40030S	R88M-1M40030S-S2			
		100 W	R88M-1M10030T	R88M-1M10030T-S2			
		200 W	R88M-1M20030T	R88M-1M20030T-S2			
		400 W	R88M-1M40030T	R88M-1M40030T-S2			
	000 1/40	750 W	R88M-1M75030T	R88M-1M75030T-S2			
	200 VAC	1 kW	R88M-1L1K030T Available soon	R88M-1L1K030T-S2 Available soon			
Vithout brake		1.5 kW	R88M-1L1K530T Available soon	R88M-1L1K530T-S2 Available soon			
		2 kW	R88M-1L2K030T Available soon	R88M-1L2K030T-S2 Available soon			
		3 kW	R88M-1L3K030T Available soon	R88M-1L3K030T-S2 Available soon			
		750 W	R88M-1L75030C Available soon	R88M-1L75030C-S2 Available soon			
		1 kW	R88M-1L1K030C Available soon	R88M-1L1K030C-S2 Available soon			
	400 VAC	1.5 kW	R88M-1L1K530C Available soon	R88M-1L1K530C-S2 Available soon			
		2 kW	R88M-1L2K030C Available soon	R88M-1L2K030C-S2 Available soon			
		3 kW	R88M-1L3K030C Available soon	R88M-1L3K030C-S2 Available soon			
		100 W	R88M-1M10030S-B	R88M-1M10030S-BS2			
	100 VAC	200 W	R88M-1M20030S-B	R88M-1M20030S-BS2			
		400 W	R88M-1M40030S-B	R88M-1M40030S-BS2			
		100 W	R88M-1M10030T-B	R88M-1M10030T-BS2			
		200 W	R88M-1M20030T-B	R88M-1M20030T-BS2			
		400 W	R88M-1M40030T-B	R88M-1M40030T-BS2			
		750 W	R88M-1M75030T-B	R88M-1M75030T-BS2			
	200 VAC	1 kW	R88M-1L1K030T-B Available soon	R88M-1L1K030T-BS2 Available soon			
Vith brake		1.5 kW	R88M-1L1K530T-B Available soon	R88M-1L1K530T-BS2 Available soon			
		2 kW	R88M-1L2K030T-B Available soon	R88M-1L2K030T-BS2 Available soon			
-		3 kW	R88M-1L3K030T-B Available soon	R88M-1L3K030T-BS2 Available soon			
		750 W	R88M-1L75030C-B Available soon	R88M-1L75030C-BS2 Available soon			
		1 kW	R88M-1L1K030C-B Available soon	R88M-1L1K030C-BS2 Available soon			
	400 VAC	1.5 kW	R88M-1L1K530C-B Available soon	R88M-1L1K530C-BS2 Available soon			
		2 kW	R88M-1L2K030C-B Available soon	R88M-1L2K030C-BS2 Available soon			
		3 kW	R88M-1L3K030C-B Available soon	R88M-1L3K030C-BS2 Available soon			

			N	lodel		
Sp	ecifications		With oil seal			
			Straight shaft	With key and tap		
		100 W	R88M-1M10030S-O	R88M-1M10030S-OS2		
	100 VAC	200 W	R88M-1M20030S-O	R88M-1M20030S-OS2		
		400 W	R88M-1M40030S-O	R88M-1M40030S-OS2		
	200 VAC	100 W	R88M-1M10030T-O	R88M-1M10030T-OS2		
		200 W	R88M-1M20030T-O	R88M-1M20030T-OS2		
		400 W	R88M-1M40030T-O	R88M-1M40030T-OS2		
		750 W	R88M-1M75030T-O	R88M-1M75030T-OS2		
Without brake		1 kW	R88M-1L1K030T-O Available soon	R88M-1L1K030T-OS2 Available soon		
Williout brake		1.5 kW	R88M-1L1K530T-O Available soon	R88M-1L1K530T-OS2 Available soon		
		2 kW	R88M-1L2K030T-O Available soon	R88M-1L2K030T-OS2 Available soon		
		3 kW	R88M-1L3K030T-O Available soon	R88M-1L3K030T-OS2 Available soon		
		750 W	R88M-1L75030C-O Available soon	R88M-1L75030C-OS2 Available soon		
		1 kW	R88M-1L1K030C-O Available soon	R88M-1L1K030C-OS2 Available soon		
	400 VAC	1.5 kW	R88M-1L1K530C-O Available soon	R88M-1L1K530C-OS2 Available soon		
	.00 17.0	2 kW	R88M-1L2K030C-O Available soon	R88M-1L2K030C-OS2 Available soon		
		3 kW	R88M-1L3K030C-O Available soon	R88M-1L3K030C-OS2 Available soon		
		100 W	R88M-1M10030S-BO	R88M-1M10030S-BOS2		
	100 VAC	200 W	R88M-1M20030S-BO	R88M-1M20030S-BOS2		
		400 W	R88M-1M40030S-BO	R88M-1M40030S-BOS2		
		100 W	R88M-1M10030T-BO	R88M-1M10030T-BOS2		
		200W	R88M-1M20030T-BO	R88M-1M20030T-BOS2		
		400 W	R88M-1M40030T-BO	R88M-1M40030T-BOS2		
	200 VAC	750 W	R88M-1M75030T-BO	R88M-1M75030T-BOS2		
With brake	200 VAC	1 kW	R88M-1L1K030T-BO Available soon	R88M-1L1K030T-BOS2 Available soo		
willi brake		1.5 kW	R88M-1L1K530T-BO Available soon	R88M-1L1K530T-BOS2 Available soo		
		2 kW	R88M-1L2K030T-BO Available soon	R88M-1L2K030T-BOS2 Available soo		
		3 kW	R88M-1L3K030T-BO Available soon	R88M-1L3K030T-BOS2 Available soo		
		750 W	R88M-1L75030C-BO Available soon	R88M-1L75030C-BOS2 Available soo		
		1 kW	R88M-1L1K030C-BO Available soon	R88M-1L1K030C-BOS2 Available soo		
	400 VAC	1.5 kW	R88M-1L1K530C-BO Available soon	R88M-1L1K530C-BOS2 Available soo		
		2 kW	R88M-1L2K030C-BO Available soon	R88M-1L2K030C-BOS2 Available soo		
	+	3 kW	R88M-1L3K030C-BO Available soon	R88M-1L3K030C-BOS2 Available soo		

• 2,000-r/min Servomotors

				Model
Specifications		Without oil seal		
			Straight shaft	With key and tap
		1 kW	R88M-1M1K020T	R88M-1M1K020T-S2
	200 VAC	1.5 kW	R88M-1M1K520T	R88M-1M1K520T-S2
	200 VAC	2 kW	R88M-1M2K020T	R88M-1M2K020T-S2
		3 kW	R88M-1M3K020T	R88M-1M3K020T-S2
Nithout brake		400 W	R88M-1M40020C	R88M-1M40020C-S2
Williout brake		600 W	R88M-1M60020C	R88M-1M60020C-S2
	400 VAC	1 kW	R88M-1M1K020C	R88M-1M1K020C-S2
		1.5 kW	R88M-1M1K520C	R88M-1M1K520C-S2
		2 kW	R88M-1M2K020C	R88M-1M2K020C-S2
		3 kW	R88M-1M3K020C	R88M-1M3K020C-S2
		1 kW	R88M-1M1K020T-B	R88M-1M1K020T-BS2
	200 VAC	1.5 kW	R88M-1M1K520T-B	R88M-1M1K520T-BS2
	200 VAC	2 kW	R88M-1M2K020T-B	R88M-1M2K020T-BS2
		3 kW	R88M-1M3K020T-B	R88M-1M3K020T-BS2
Witht brake		400 W	R88M-1M40020C-B	R88M-1M40020C-BS2
with brake		600 W	R88M-1M60020C-B	R88M-1M60020C-BS2
	400 VAC	1 kW	R88M-1M1K020C-B	R88M-1M1K020C-BS2
	400 VAC	1.5 kW	R88M-1M1K520C-B	R88M-1M1K520C-BS2
		2 kW	R88M-1M2K020C-B	R88M-1M2K020C-BS2
		3 kW	R88M-1M3K020C-B	R88M-1M3K020C-BS2

			Model With oil seal		
Specifications					
			Straight shaft	With key and tap	
		1 kW	R88M-1M1K020T-O	R88M-1M1K020T-OS2	
	200 VAC	1.5 kW	R88M-1M1K520T-O	R88M-1M1K520T-OS2	
	200 VAC	2 kW	R88M-1M2K020T-O	R88M-1M2K020T-OS2	
		3 kW	R88M-1M3K020T-O	R88M-1M3K020T-OS2	
Nithout brake		400 W	R88M-1M40020C-O	R88M-1M40020C-OS2	
vitnout brake		600 W	R88M-1M60020C-O	R88M-1M60020C-OS2	
	400 VAC	1 kW	R88M-1M1K020C-O	R88M-1M1K020C-OS2	
		1.5 kW	R88M-1M1K520C-O	R88M-1M1K520C-OS2	
		2 kW	R88M-1M2K020C-O	R88M-1M2K020C-OS2	
		3 kW	R88M-1M3K020C-O	R88M-1M3K020C-OS2	
		1 kW	R88M-1M1K020T-BO	R88M-1M1K020T-BOS2	
	200 VAC	1.5 kW	R88M-1M1K520T-BO	R88M-1M1K520T-BOS2	
	200 VAC	2 kW	R88M-1M2K020T-BO	R88M-1M2K020T-BOS2	
		3 kW	R88M-1M3K020T-BO	R88M-1M3K020T-BOS2	
Witht brake		400 W	R88M-1M40020C-BO	R88M-1M40020C-BOS2	
Witht brake		600 W	R88M-1M60020C-BO	R88M-1M60020C-BOS2	
	400 VAC	1 kW	R88M-1M1K020C-BO	R88M-1M1K020C-BOS2	
	400 VAC	1.5 kW	R88M-1M1K520C-BO	R88M-1M1K520C-BOS2	
		2 kW	R88M-1M2K020C-BO	R88M-1M2K020C-BOS2	
		3 kW	R88M-1M3K020C-BO	R88M-1M3K020C-BOS2	

• 1,000-r/min Servomotors

			Model			
Specifications			Without oil seal			
			Straight shaft	With key and tap		
		900 W	R88M-1M90010T	R88M-1M90010T-S2		
	200 VAC	2 kW	R88M-1M2K010T	R88M-1M2K010T-S2		
		3 kW	R88M-1M3K010T	R88M-1M3K010T-S2		
Without brake		900 W	R88M-1M90010C	R88M-1M90010C-S2		
	400 VAC	2 kW	R88M-1M2K010C	R88M-1M2K010C-S2		
		3 kW	R88M-1M3K010C	R88M-1M3K010C-S2		
		900 W	R88M-1M90010T-B	R88M-1M90010T-BS2		
	200 VAC	2 kW	R88M-1M2K010T-B	R88M-1M2K010T-BS2		
Mith hades		3 kW	R88M-1M3K010T-B	R88M-1M3K010T-BS2		
With brake	400 VAC	900 W	R88M-1M90010C-B	R88M-1M90010C-BS2		
		2 kW	R88M-1M2K010C-B	R88M-1M2K010C-BS2		
		3 kW	R88M-1M3K010C-B	R88M-1M3K010C-BS2		

				Model		
Specifications			With oil seal			
			Straight shaft	With key and tap		
		900 W	R88M-1M90010T-O	R88M-1M90010T-OS2		
	200 VAC	2 kW	R88M-1M2K010T-O	R88M-1M2K010T-OS2		
		3 kW	R88M-1M3K010T-O	R88M-1M3K010T-OS2		
Without brake		900 W	R88M-1M90010C-O	R88M-1M90010C-OS2		
	400 VAC	2 kW	R88M-1M2K010C-O	R88M-1M2K010C-OS2		
		3 kW	R88M-1M3K010C-O	R88M-1M3K010C-OS2		
		900 W	R88M-1M90010T-BO	R88M-1M90010T-BOS2		
	200 VAC	2 kW	R88M-1M2K010T-BO	R88M-1M2K010T-BOS2		
VACAL- I I		3 kW	R88M-1M3K010T-BO	R88M-1M3K010T-BOS2		
With brake	400 VAC	900 W	R88M-1M90010C-BO	R88M-1M90010C-BOS2		
		2 kW	R88M-1M2K010C-BO	R88M-1M2K010C-BOS2		
		3 kW	R88M-1M3K010C-BO	R88M-1M3K010C-BOS2		

Decelerator (Backlash: 3 Arcminutes Max.)

● For 3,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model (Straight shaft) *
	1/5	R88G-HPG11B05100B□
	1/11	R88G-HPG14A11100B□
100 W	1/21	R88G-HPG14A21100B□
	1/33	R88G-HPG20A33100B□
	1/45	R88G-HPG20A45100B□
	1/5	R88G-HPG14A05200B□
	1/11	R88G-HPG14A11200B□
200 W	1/21	R88G-HPG20A21200B□
	1/33	R88G-HPG20A33200B□
	1/45	R88G-HPG20A45200B□
	1/5	R88G-HPG14A05400B□
	1/11	R88G-HPG20A11400B□
400 W	1/21	R88G-HPG20A21400B□
	1/33	R88G-HPG32A33400B□
	1/45	R88G-HPG32A45400B□
	1/5	R88G-HPG20A05750B□
750 W (200 V)	1/11	R88G-HPG20A11750B□
	1/21	R88G-HPG32A21750B□
	1/33	R88G-HPG32A33750B□
	1/45	R88G-HPG32A45750B□
	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
750 W (400 V)	1/21	R88G-HPG32A211K5B□
(400 V)	1/33	R88G-HPG32A33600SB□
	1/45	R88G-HPG50A451K5B
	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
1 kW	1/21	R88G-HPG32A211K5B□
	1/33	R88G-HPG50A332K0B□
	1/45	R88G-HPG50A451K5B□
	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
1.5 kW	1/21	R88G-HPG32A211K5B□
	1/33	R88G-HPG50A332K0B□
	1/45	R88G-HPG50A451K5B□
	1/5	R88G-HPG32A052K0B□
2 kW	1/11	R88G-HPG32A112K0B□
	1/21	R88G-HPG50A212K0B□
	1/33	R88G-HPG50A332K0B□
	1/5	R88G-HPG32A053K0B□
3 kW	1/11	R88G-HPG50A113K0B□
•	1/21	R88G-HPG50A213K0B□

^{*} The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the Decelerator model number. e.g. R88G-HPG11B05100BJ

● For 2,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model (Straight shaft) ∗		
	1/5	R88G-HPG32A052K0B□		
400 W	1/11	R88G-HPG32A112K0B□		
	1/21	R88G-HPG32A211K5B□		
	1/33	R88G-HPG32A33600SB□		
	1/45	R88G-HPG32A45400SB□		
	1/5	R88G-HPG32A052K0B□		
	1/11	R88G-HPG32A112K0B□		
600 W	1/21	R88G-HPG32A211K5B□		
	1/33	R88G-HPG32A33600SB□		
	1/45	R88G-HPG50A451K5B□		
	1/5	R88G-HPG32A053K0B□		
1 kW	1/11	R88G-HPG32A112K0SB□		
	1/21	R88G-HPG32A211K0SB□		
	1/33	R88G-HPG50A332K0SB□		
	1/45	R88G-HPG50A451K0SB□		
	1/5	R88G-HPG32A053K0B□		
1.5 kW	1/11	R88G-HPG32A112K0SB□		
1.5 KW	1/21	R88G-HPG50A213K0B□		
	1/33	R88G-HPG50A332K0SB□		
	1/5	R88G-HPG32A053K0B□		
2 kW	1/11	R88G-HPG32A112K0SB□		
∠ KVV	1/21	R88G-HPG50A213K0B□		
	1/33	R88G-HPG50A332K0SB□		
	1/5	R88G-HPG32A054K0B□		
3 kW	1/11	R88G-HPG50A115K0B□		
3 KVV	1/21	R88G-HPG50A213K0SB□		
	1/25	R88G-HPG65A253K0SB□		

^{*}The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the Decelerator model number. e.g. R88G-HPG11B05100BJ

● For 1,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model (Straight shaft) *
	1/5	R88G-HPG32A05900TB□
000 W	1/11	R88G-HPG32A11900TB□
900 W	1/21	R88G-HPG50A21900TB□
	1/33	R88G-HPG50A33900TB□
	1/5	R88G-HPG32A052K0TB□
2 kW	1/11	R88G-HPG50A112K0TB□
∠ KVV	1/21	R88G-HPG50A212K0TB□
	1/25	R88G-HPG65A255K0SB□
	1/5	R88G-HPG50A055K0SB□
0 1444	1/11	R88G-HPG50A115K0SB□
3 kW	1/20	R88G-HPG65A205K0SB□
	1/25	R88G-HPG65A255K0SB□

^{*}The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the Decelerator model number. e.g. R88G-HPG11B05100BJ

Cables and Peripheral Devices

Encoder Cables (Standard Cable)

Applicable Servomotor			Model
100 V 200 V	3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	3 m	R88A-CR1A003C
		5 m	R88A-CR1A005C
		10 m	R88A-CR1A010C
		15 m	R88A-CR1A015C
		20 m	R88A-CR1A020C
		30 m	R88A-CR1A030C
		40 m	R88A-CR1A040C
		50 m	R88A-CR1A050C
200 V 400 V	200 V: 3,000-r/min Servomotors of 1 kW or more 2,000-r/min Servomotors 1,000-r/min Servomotors 400 V: 3,000-r/min Servomotors 2,000-r/min Servomotors 1,000-r/min Servomotors	3 m	R88A-CR1B003N
		5 m	R88A-CR1B005N
		10 m	R88A-CR1B010N
		15 m	R88A-CR1B015N
		20 m	R88A-CR1B020N
		30 m	R88A-CR1B030N
		40 m	R88A-CR1B040N
		50 m	R88A-CR1B050N

Brake Cables (Standard Cable)

Applicable Servomotor			Model
100 V 200 V	3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	3 m	R88A-CA1A003B
		5 m	R88A-CA1A005B
		10 m	R88A-CA1A010B
		15 m	R88A-CA1A015B
		20 m	R88A-CA1A020B
		30 m	R88A-CA1A030B
		40 m	R88A-CA1A040B
		50 m	R88A-CA1A050B

Motor Power Cables (Standard Cable)

Applicable Servomotor			Without brake wire	With brake wire
			Model	Model
		3 m	R88A-CA1A003S	
		5 m	R88A-CA1A005S	
	3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	10 m	R88A-CA1A010S	
100 V		15 m	R88A-CA1A015S	
200 V		20 m	R88A-CA1A020S	
		30 m	R88A-CA1A030S	
		40 m	R88A-CA1A040S	
		50 m	R88A-CA1A050S	
		3 m	R88A-CA1B003S	R88A-CA1B003B
		5 m	R88A-CA1B005S	R88A-CA1B005B
		10 m	R88A-CA1B010S	R88A-CA1B010B
000 1/	3,000-r/min Servomotors of 1 kW	15 m	R88A-CA1B015S	R88A-CA1B015B
200 V	2,000-r/min Servomotors of 1 kW 1,000-r/min Servomotors of 900 W	20 m	R88A-CA1B020S	R88A-CA1B020B
		30 m	R88A-CA1B030S	R88A-CA1B030B
		40 m	R88A-CA1B040S	R88A-CA1B040B
		50 m	R88A-CA1B050S	R88A-CA1B050B
		3 m	R88A-CA1C003S	R88A-CA1C003B
	3,000-r/min Servomotors of 1.5 kW 2,000-r/min Servomotors of 1.5 kW	5 m	R88A-CA1C005S	R88A-CA1C005B
		10 m	R88A-CA1C010S	R88A-CA1C010B
200 V		15 m	R88A-CA1C015S	R88A-CA1C015B
		20 m	R88A-CA1C020S	R88A-CA1C020B
		30 m	R88A-CA1C030S	R88A-CA1C030B
		40 m	R88A-CA1C040S	R88A-CA1C040B
		50 m	R88A-CA1C050S	R88A-CA1C050B
400 V	3,000-r/min Servomotors of 750 W, 1 kW, 1.5 kW, and 2 kW 2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, and 2 kW 1,000-r/min Servomotors of 900 W	3 m	R88A-CA1C003S	R88A-CA1D003B
		5 m	R88A-CA1C005S	R88A-CA1D005B
		10 m	R88A-CA1C010S	R88A-CA1D010B
		15 m	R88A-CA1C015S	R88A-CA1D015B
		20 m	R88A-CA1C020S	R88A-CA1D020B
		30 m	R88A-CA1C030S	R88A-CA1D030B
		40 m	R88A-CA1C040S	R88A-CA1D040B
		50 m	R88A-CA1C050S	R88A-CA1D050B

	A - Parkla O	Without brake wire	With brake wire	
	Applicable Servomotor		Model	Model
		3 m	R88A-CA1E003S	R88A-CA1E003B
		5 m	R88A-CA1E005S	R88A-CA1E005B
	3,000-r/min Servomotors of 2 kW (200 V) and 3 kW (200 V/400 V)	10 m	R88A-CA1E010S	R88A-CA1E010B
200 V	2,000-r/min Servomotors of 2 kW	15 m	R88A-CA1E015S	R88A-CA1E015B
400 V	(200 V) and 3 kW (200 V/400 V)	20 m	R88A-CA1E020S	R88A-CA1E020B
	1,000-r/min Servomotors of 2 kW (200 V/400 V) and 3 kW (400 V)	30 m	R88A-CA1E030S	R88A-CA1E030B
	, , , , , , , , , , , , , , , , , , , ,	40 m	R88A-CA1E040S	R88A-CA1E040B
		5 m 10 m 15 m 20 m 30 m	R88A-CA1E050S	R88A-CA1E050B
		3 m 5 m 10 m 15 m 10 m 15 m 20 m 30 m 40 m 50 m 10 m 15 m 20 m 30 m 40 m 50 m 10 m 20 m 30 m 40 m 50 m 10 m 20 m 30 m 40 m 50 m 10 m 15 m 20 m 30 m 40 m 50 m 10 m 15 m 20 m 30 m 40 m 50 m 10	R88A-CA1F003S	R88A-CA1F003B
		5 m	R88A-CA1F005S	R88A-CA1F005B
		10 m	R88A-CA1F010S	R88A-CA1F010B
200 V	1 000 r/min Conservatore of 2 kW	15 m	R88A-CA1F015S	R88A-CA1F015B
200 V	1,000-r/min Servomotors of 3 kW	20 m	R88A-CA1F020S	R88A-CA1F020B
		30 m	R88A-CA1F030S	R88A-CA1F030B
		40 m	R88A-CA1F040S	R88A-CA1F040B
		50 m	R88A-CA1F050S	R88A-CA1F050B

Encoder Cables (Flexible Cable)

	Applicable Servomotor	Model	
		3 m	R88A-CR1A003CF
		5 m	R88A-CR1A005CF
		3,000-r/min Servomotors of 100 W, 15 m	R88A-CR1A010CF
100 V	3,000-r/min Servomotors of 100 W,		R88A-CR1A015CF
200 V	200 W, 400 W, and 750 W	20 m	R88A-CR1A020CF
		30 m	R88A-CR1A030CF
		40 m	R88A-CR1A040CF
		50 m	R88A-CR1A050CF
		3 m	R88A-CR1B003NF
	200 V:	5 m	R88A-CR1B005NF
	3,000-r/min Servomotors of 1 kW or more For 2,000-r/min Servomotors	10 m	R88A-CR1B010NF
200 V	For 1,000-r/min Servomotors	15 m	R88A-CR1B015NF
400 V	400 V: 3,000-r/min Servomotors 2,000-r/min Servomotors	20 m	R88A-CR1B020NF
		30 m	R88A-CR1B030NF
	1,000-r/min Servomotors	40 m	R88A-CR1B040NF
		50 m	R88A-CR1B050NF

Brake Cables (Flexible Cable)

	Applicable Servomotor	Model	
		3 m	R88A-CA1A003BF
		5 m	R88A-CA1A005BF
	10 m 100 V 3,000-r/min Servomotors of 100 W, 15 m	10 m	R88A-CA1A010BF
100 V		15 m	R88A-CA1A015BF
200 V	200 W, 400 W, and 750 W	30 m	R88A-CA1A020BF
			R88A-CA1A030BF
			R88A-CA1A040BF
		50 m	R88A-CA1A050BF

Motor Power Cables (Flexible Cable)

Annlicable Conventer			Without brake wire	With brake wire
	Applicable Servomotor		Model	Model
		3 m	R88A-CA1A003SF	
		5 m	R88A-CA1A005SF	
		10 m	R88A-CA1A010SF	
100 V	3,000-r/min Servomotors of 100 W, 200 W,	15 m	R88A-CA1A015SF	
200 V	400 W, and 750 W	20 m	R88A-CA1A020SF	
		30 m	R88A-CA1A030SF	
		40 m	R88A-CA1A040SF	
		50 m	R88A-CA1A050SF	
		3 m	R88A-CA1B003SF	R88A-CA1B003BF
		5 m	R88A-CA1B005SF	R88A-CA1B005BF
		10 m	R88A-CA1B010SF	R88A-CA1B010BF
	3,000-r/min Servomotors of 1 kW	15 m	R88A-CA1B015SF	R88A-CA1B015BF
200 V	2,000-r/min Servomotors of 1 kW 1,000-r/min Servomotors of 900 W	20 m	R88A-CA1B020SF	R88A-CA1B020BF
	1,000 7.1 00.10	30 m	R88A-CA1B030SF	R88A-CA1B030BF
		40 m	R88A-CA1B040SF	R88A-CA1B040BF
		50 m	R88A-CA1B050SF	R88A-CA1B050BF
		3 m	R88A-CA1C003SF	R88A-CA1C003BF
		5 m	R88A-CA1C005SF	R88A-CA1C005BF
		10 m	R88A-CA1C010SF	R88A-CA1C010BF
	3,000-r/min Servomotors of 1.5 kW	15 m	R88A-CA1C015SF	R88A-CA1C015BF
200 V	2,000-r/min Servomotors of 1.5 kW	20 m	R88A-CA1C020SF	R88A-CA1C020BF
		30 m	R88A-CA1C030SF	R88A-CA1C030BF
		40 m	R88A-CA1C040SF	R88A-CA1C040BF
		50 m	R88A-CA1C050SF	R88A-CA1C050BF
		3 m	R88A-CA1C003SF	R88A-CA1D003BF
		5 m	R88A-CA1C005SF	R88A-CA1D005BF
	3,000-r/min Servomotors of 750 W, 1 kW,	10 m	R88A-CA1C010SF	R88A-CA1D010BF
	1.5 kW, and 2 kW	15 m	R88A-CA1C015SF	R88A-CA1D015BF
400 V	2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, and 2 kW	20 m	R88A-CA1C020SF	R88A-CA1D020BF
	1,000-r/min Servomotors of 900 W	30 m	R88A-CA1C030SF	R88A-CA1D030BF
		40 m	R88A-CA1C040SF	R88A-CA1D040BF
		50 m	R88A-CA1C050SF	R88A-CA1D050BF
		3 m	R88A-CA1E003SF	R88A-CA1E003BF
		5 m	R88A-CA1E005SF	R88A-CA1E005BF
	3,000-r/min Servomotors of 2 kW (200 V)	10 m	R88A-CA1E010SF	R88A-CA1E010BF
200 V	and 3 kW (200 V/400 V) 2,000-r/min Servomotors of 2 kW (200 V)	15 m	R88A-CA1E015SF	R88A-CA1E015BF
400 V	and 3 kW (200 V/400 V)	20 m	R88A-CA1E020SF	R88A-CA1E020BF
	1,000-r/min Servomotors of 2 kW (200 V/400 V)	30 m	R88A-CA1E030SF	R88A-CA1E030BF
	and 3 kW (400 V)	40 m	R88A-CA1E040SF	R88A-CA1E040BF
		50 m	R88A-CA1E050SF	R88A-CA1E050BF
		3 m	R88A-CA1F003SF	R88A-CA1F003BF
		5 m	R88A-CA1F005SF	R88A-CA1F005BF
		10 m	R88A-CA1F010SF	R88A-CA1F010BF
		15 m	R88A-CA1F015SF	R88A-CA1F015BF
200 V	1,000-r/min Servomotors of 3 kW	20 m	R88A-CA1F020SF	R88A-CA1F020BF
		30 m	R88A-CA1F030SF	R88A-CA1F030BF
				R88A-CA1F040BF
		40 m	R88A-CA1F040SF	
		50 m	R88A-CA1F050SF	R88A-CA1F050BF

Recommended EtherCAT Communications Cable

Use a straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT.

Cabel with Connectors

Item	Appearance	Recommended manufacturer	Cable length [m] *1	Model
			0.3	XS6W-6LSZH8SS30CM-Y
Standard type			0.5	XS6W-6LSZH8SS50CM-Y
Cable with Connectors on Both Ends (RJ45/RJ45) Wire gauge and number of pairs: AWG27, 4-pair cable		OMRON	1	XS6W-6LSZH8SS100CM-Y
Cable sheath material: LSZH *2			2	XS6W-6LSZH8SS200CM-Y
Cable color: Yellow *3	8		3	XS6W-6LSZH8SS300CM-Y
			5	XS6W-6LSZH8SS500CM-Y
			0.3	XS5W-T421-AMD-K
			0.5	XS5W-T421-BMD-K
Rugged type Cable with Connectors on Both Ends (RJ45/RJ45)	100	OMRON	1	XS5W-T421-CMD-K
Wire gauge and number of pairs: AWG22, 2-pair cable	10		2	XS5W-T421-DMD-K
			5	XS5W-T421-GMD-K
			10	XS5W-T421-JMD-K
		OMRON	0.3	XS5W-T421-AMC-K
			0.5	XS5W-T421-BMC-K
Rugged type			1	XS5W-T421-CMC-K
Cable with Connectors on Both Ends (M12 Straight/RJ45) Wire gauge and number of pairs: AWG22, 2-pair cable			2	XS5W-T421-DMC-K
			5	XS5W-T421-GMC-K
			10	XS5W-T421-JMC-K
			0.3	XS5W-T422-AMC-K
	-		0.5	XS5W-T422-BMC-K
Rugged type Cable with Connectors on Both Ends (M12 Bight angle/B M5)		OMBON	1	XS5W-T422-CMC-K
Cable with Connectors on Both Ends (M12 Right-angle/RJ45) Wire gauge and number of pairs: AWG22, 2-pair cable	10	OWINON	2	XS5W-T422-DMC-K
, , , , , , , , , , , , , , , , , , , ,			5	XS5W-T422-GMC-K
			10	XS5W-T422-JMC-K

^{*1.} Standard type cables length 0.2, 0.3, 0.5, 1, 1.5, 2, 3, 5, 7.5, 10, 15 and 20 m are available.

Rugged type cables length 0.3, 0.5, 1, 2, 3, 5, 10 and 15 m are available.

*2. The lineup features Low Smoke Zero Halogen cables for in-cabinet use and PUR cables for out-of-cabinet use.

*3. Cables colors are available in blue, yellow, or Green.

Note: For details, refer to Cat.No.G019.

Cables/Connectors

Wire Gauge and Number of Pairs: AWG24, 4-pair Cable

		, ·	
Item	Appearance	Recommended manufacturer	Model
		Hitachi Metals, Ltd.	NETSTAR-C5E SAB 0.5×4P *
Cables		Kuramo Electric Co.	KETH-SB *
		SWCC Showa Cable Systems Co.	FAE-5004 *
RJ45 Connectors		Panduit Corporation	MPS588-C *

^{*}We recommend you to use above cable and connector together.

Wire Gauge and Number of Pairs: AWG22, 2-pair Cable

Item	Appearance	Recommended manufacturer	Model
Cables		Kuramo Electric Co.	KETH-PSB-OMR *
Cables		JMACS Japan Co., Ltd.	PNET/B *
RJ45 Assembly Connector		OMRON	XS6G-T421-1 *

^{*}We recommend you to use above cable and connector together.

Note: Connect both ends of cable shielded wires to the connector hoods.

Peripheral Connector Servo Drive Side Connectors

Name and applications	Model
Main circuit connector (CNA) * 1 For R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/-1SN01H-ECT/-1SN02H-ECT/-1SN04H-ECT/-1SN08H-ECT/ -1SN10H-ECT	R88A-CN102P *4 Available soon
Main circuit connector A (CNA) *2 For R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT/-1SN30F-ECT/-1SN30F-ECT/-1SN30F-ECT/-1SN30F-ECT/-1SN30F-ECT/-1SN30F-ECT/-1SN30F-ECT	R88A-CN103P *4 Available soon
Main circuit connector B (CNB) *2 For R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT/-1SN30F-ECT/-1SN30F-ECT/-1SN30F-ECT/-1SN30F-ECT/-1SN30F-ECT/-1SN30F-ECT/-1SN30F-ECT	R88A-CN104P *4 Available soon
Motor connector (CNC) For R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/-1SN01H-ECT/-1SN02H-ECT/-1SN04H-ECT/-1SN08H-ECT/ -1SN10H-ECT	R88A-CN101A *4 Available soon
Motor connector (CNC) For R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/ -1SN30F-ECT	R88A-CN102A *4 Available soon
Control power supply connector (CND) For R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT/1SN30F-ECT/	R88A-CN101P *4 Available soon
Control I/O connector (CN1) *3	R88A-CN101C Available soon
Encoder connector (CN2)	R88A-CN101R
Brake interlock connector (CN12)	R88A-CN101B Available soon

^{*1.} Two short-circuit wires are connected to the connector.

Servomotor Side Connector

	Model		
	100 V, 200 V	For 3,000 r/min (100 to 750 W)	R88A-CNK02R
Encoder connector	100 V, 200 V	For 3,000 r/min (1 to 3 kW), 2,000 r/min, 1,000 r/min	- R88A-CN104R
	400 V	For 3,000 r/min, 2,000 r/min, 1,000 r/min	
Power connector (For 750 W max.)			R88A-CN111A
Brake connector (For 750 W max.)			R88A-CN111B

External Regeneration Resistors

Applicable Servo Drive	Specifications	Model
R88D-1SN01L-ECT/-1SN02L-ECT	Regeneration process capacity: 24 W, 15 Ω	R88A-RR12015
R88D-1SN01H-ECT/-1SN02H-ECT	Regeneration process capacity: 24 W, 25 Ω	R88A-RR12025
R88D-1SN20H-ECT/-1SN30H-ECT	Regeneration process capacity: 60 W, 10 Ω	R88A-RR30010
R88D-1SN04L-ECT	Regeneration process capacity: 60 W, 12 Ω	R88A-RR30012
R88D-1SN01L-ECT/-1SN02L-ECT	Regeneration process capacity: 60 W, 15 Ω	R88A-RR30015
R88D-1SN15H-ECT	Regeneration process capacity: 60 W, 17 Ω	R88A-RR30017
R88D-1SN08H-ECT/-1SN10H-ECT/-1SN20F-ECT */ -1SN30F-ECT *	Regeneration process capacity: 60 W, 20 Ω	R88A-RR30020
R88D-1SN01H-ECT/-1SN02H-ECT/-1SN04H-ECT	Regeneration process capacity: 60 W, 25 Ω	R88A-RR30025
R88D-1SN06F-ECT */-1SN10F-ECT */-1SN15F-ECT *	Regeneration process capacity: 60 W, 33 Ω	R88A-RR30033

^{*} Use two series-connected External Regeneration Resistors for this model.

^{*2.} One short-circuit wire is connected to the connector.

^{*3.} Four short-circuit wires are connected to the connector.

^{*4.} One opener is included.

External Regeneration Resistance Unit

Applicable Servo Drive	Specifications	Model
R88D-1SN20H-ECT/-1SN30H-ECT	Regeneration process capacity: 640 W, 10 Ω	R88A-RR1K610
R88D-1SN15H-ECT	Regeneration process capacity: 640 W, 17 Ω	R88A-RR1K617
R88D-1SN08H-ECT/-1SN10H-ECT/-1SN20F-ECT */ -1SN30F-ECT *	Regeneration process capacity: 640 W, 20 Ω	R88A-RR1K620
R88D-1SN20F-ECT/-1SN30F-ECT	Regeneration process capacity: 640 W, 40 Ω	R88A-RR1K640
R88D-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT	Regeneration process capacity: 640 W, 66 Ω	R88A-RR1K666

^{*}Use two series-connected External Regeneration Resistance Units for this model.

Reactor

Applicable Servomotor	Model
R88D-1SN01L-ECT/-1SN01H-ECT/-1SN02H-ECT	R88A-PD2002
R88D-1SN02L-ECT/-1SN04H-ECT	R88A-PD2004
R88D-1SN04L-ECT/-1SN08H-ECT	R88A-PD2007
R88D-1SN10H-ECT/-1SN15H-ECT	R88A-PD2015
R88D-1SN20H-ECT	R88A-PD2022
R88D-1SN30H-ECT	R88A-PD2037
R88D-1SN06F-ECT	R88A-PD4007
R88D-1SN10F-ECT/-1SN15F-ECT	R88A-PD4015
R88D-1SN20F-ECT	R88A-PD4022
R88D-1SN30F-ECT	R88A-PD4037

Footprint-type Noise Filter

Applicable Servo Drive	Model
R88D-1SN01L-ECT/-1SN01H-ECT/-1SN02H-ECT (Single-phase input)	R88A-FI1S103
R88D-1SN02L-ECT/-1SN04H-ECT (Single-phase input)	R88A-FI1S105
R88D-1SN04L-ECT/-1SN08H-ECT (Single-phase input)	R88A-FI1S109
R88D-1SN15H-ECT (Single-phase input)	R88A-FI1S116
DOOD 40N0411 FOT/ 40N0011 FOT /0 -b i t)	R88A-FI1S202
R88D-1SN01H-ECT/-1SN02H-ECT (3-phase input)	R88A-FI1S203
R88D-1SN04H-ECT (3-phase input)	R88A-FI1S203
R88D-1SN08H-ECT (3-phase input)/-1SN10H-ECT	R88A-FI1S208
R88D-1SN15H-ECT (3-phase input)/-1SN20H-ECT/-1SN30H-ECT	R88A-FI1S216
R88D-1SN06F-ECT/-1SN10F-ECT-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT	R88A-FI1S309

Software

Automation Software Sysmac Studio

Please purchase a DVD and required number of licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. Each model of licenses does not include any DVD.

Product name	Specifications	Number of licenses	Media	Model
Sysmac Studio Standard	The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX-series, EtherCat Slave, and the HMI. Sysmac Studio runs on the following OS. Windows XP (Service Pack 3 or higher, 32-bit version)/Windows Vista (32-bit version)/Windows 7 (32-bit/64-bit version)/Windows 8 (32-bit/64-bit	 (Media only)	DVD	SYSMAC-SE200D
Edition Ver.1. \(\square\) version)/Windows 8.1 (32-bit/64-bit version)/Windows 10 (32-bit/64-bit version) The Sysmac Studio Standard Edition DVD includes Support Software to set up EtherNet/IP Units, DeviceNet slaves, Serial Communications Units, and Support Software for creating screens on HMIs (CX-Designer). For details, refer to the Sysmac Integrated Catalogue (P072).	1 license *		SYSMAC-SE201L	
Sysmac Studio Drive Edition Ver.1.□□	Sysmac Studio Drive Edition is a limited license that provides selected functions required for 1S/G5 series Servo settings. This product is a license only. You need the Sysmac Studio Standard Edition DVD media to install it. With Drive Edition, you can use only the setup functions for 1S, G5-series Servo System	1 license		SYSMAC-DE001L

^{*} Multi licenses are available for the Sysmac Studio (3, 10, 30, or 50 licenses).

Collections of software functional components

Sysmac Library

Sysmac Library is POU Libraries (Function Block and Function) provided for NJ/NX-series Controller.

Please download it from following URL and install to Sysmac Studio.

http://www.ia.omron.com/sysmac_library/

Product	Features	Model
EtherCAT 1S Series Library	The EtherCAT 1S Series Library is used to initialize the absolute encoder, back up and restore the parameters for an OMRON 1S-series Servo Drive with built-in EtherCAT communications. You can use this library to reduce manpower of programming when implementing the processing for a Servo Drive.	SYSMAC-XR011

Combination table

Servo Drive and Servomotor Combinations

The following tables show the possible combinations of 1S-series Servo Drives and Servomotors.

The Servomotors and Servo Drives can only be used in the listed combinations. "
"at the end of the motor model number is for options, such as the shaft type and brake.

3,000-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Servomotor rated output	Servomotor	Servo Drive
	100 W	R88M-1M10030S-□	R88D-1SN01L-ECT
Single-phase 100 VAC	200 W	R88M-1M20030S-□	R88D-1SN02L-ECT
	400 W	R88M-1M40030S-□	R88D-1SN04L-ECT
	100 W	R88M-1M10030T-□	R88D-1SN01H-ECT
	200 W	R88M-1M20030T-□	R88D-1SN02H-ECT
Single-phase/3-phase 200 VAC	400 W	R88M-1M40030T-□	R88D-1SN04H-ECT
	750 W	R88M-1M75030T-□	R88D-1SN08H-ECT
	1.5 kW	R88M-1L1K530T-□	R88D-1SN15H-ECT
	1 kW	R88M-1L1K030T-□	R88D-1SN10H-ECT
3-phase 200 VAC	2 kW	R88M-1L2K030T-□	R88D-1SN20H-ECT
	3 kW	R88M-1L3K030T-□	R88D-1SN30H-ECT
	750 W	R88M-1L75030C-□	R88D-1SN10F-ECT
	1 kW	R88M-1L1K030C-□	R88D-1SN10F-ECT
3-phase 400 VAC	1.5 kW	R88M-1L1K530C-□	R88D-1SN15F-ECT
	2 kW	R88M-1L2K030C-□	R88D-1SN20F-ECT
	3 kW	R88M-1L3K030C-□	R88D-1SN30F-ECT

2,000-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Servomotor rated output	Servomotor	Servo Drive
Single-phase/3-phase 200 VAC	1.5 kW	R88M-1M1K520T-□	R88D-1SN15H-ECT
	1 kW	R88M-1M1K020T-□	R88D-1SN10H-ECT
3-phase 200 VAC	2 kW	R88M-1M2K020T-□	R88D-1SN20H-ECT
	3 kW	R88M-1M3K020T-□	R88D-1SN30H-ECT
	400 W	R88M-1M40020C-□	R88D-1SN06F-ECT
	600 W	R88M-1M60020C-□	R88D-1SN06F-ECT
2 phase 400 VAC	1 kW	R88M-1M1K020C-□	R88D-1SN10F-ECT
3-phase 400 VAC	1.5 kW	R88M-1M1K520C-□	R88D-1SN15F-ECT
	2 kW	R88M-1M2K020C-□	R88D-1SN20F-ECT
	3 kW	R88M-1M3K020C-□	R88D-1SN30F-ECT

1,000-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Servomotor rated output	Servomotor	Servo Drive
	900 W	R88M-1M90010T-□	R88D-1SN10H-ECT
3-phase 200 VAC	2 kW	R88M-1M2K010T-□	R88D-1SN20H-ECT
	3 kW	R88M-1M3K010T-□	R88D-1SN30H-ECT
	900 W	R88M-1M90010C-□	R88D-1SN10F-ECT
3-phase 400 VAC	2 kW	R88M-1M2K010C-□	R88D-1SN20F-ECT
	3 kW	R88M-1M3K010C-□	R88D-1SN30F-ECT

Servomotor and Decelerator Combinations

3,000-r/min Servomotors and Decelerators (Backlash:3 Arcminutes Max.)

Servomotor models *	1/5	1/11	1/21	1/33	1/45		
R88M-1M10030□	R88G- HPG11B05100B□	R88G- HPG14A11100B□	R88G- HPG14A21100B□	R88G- HPG20A33100B□	R88G- HPG20A45100B□		
R88M-1M20030□	R88G- HPG14A05200B□	R88G- HPG14A11200B□	R88G- HPG20A21200B□	R88G- HPG20A33200B□	R88G- HPG20A45200B□		
R88M-1M40030□	R88G- HPG14A05400B□	R88G- HPG20A11400B□	R88G- HPG20A21400B□	R88G- HPG32A33400B□	R88G- HPG32A45400B□		
R88M-1M75030□ (200 VAC)	R88G- HPG20A05750B□	R88G- HPG20A11750B□	R88G- HPG32A21750B□	R88G- HPG32A33750B□	R88G- HPG32A45750B□		
R88M-1L75030□ (400 VAC)			R88G- HPG32A211K5B□	R88G- HPG32A33600SB□	R88G-		
R88M-1L1K030□	R88G-	R88G-			HPG50A451K5B□		
R88M-1L1K530□	HPG32A052K0B□	HPG32A112K0B□	HPG32A112K0B□	HPG32A112K0B□		R88G-	
R88M-1L2K030□			R88G- HPG50A212K0B□	HPG50A332K0B□			
R88M-1L3K030□	R88G- HPG32A053K0B□	R88G- HPG50A113K0B□	R88G- HPG50A213K0B□				

^{*}You cannot use a Servomotor with a key and tap (model numbers with -S2 at the end) in combination with a Decelerator.

2,000-r/min Servomotors and Decelerators (Backlash:3 Arcminutes Max.)

Servomotor models *	1/5	1/11	1/21	1/33 (1/25 for flange 65)	1/45	
R88M-1M40020□ (400 VAC)	R88G-	R88G-	R88G-	R88G-	R88G- HPG32A45400SB□	
R88M-1M60020□ (400 VAC)	HPG32A052K0B□	HPG32A112K0B□	HPG32A211K5B□	HPG32A33600SB□	R88G- HPG50A451K5B□	
R88M-1M1K020□	R88G-	R88G- HPG32A112K0SB	R88G- HPG32A211K0SB□	R88G-	R88G- HPG50A451K0SB□	
R88M-1M1K520□	HPG32A053K0B□		HPG32A112K0SB□ F		HPG50A332K0SB□	
R88M-1M2K020□				HPG50A213K0B□		
R88M-1M3K020□	R88G- HPG32A054K0B□	R88G- HPG50A115K0B□	R88G- HPG50A213K0SB□	R88G- HPG65A253K0SB□		

^{*}You cannot use a Servomotor with a key and tap (model numbers with -S2 at the end) in combination with a Decelerator.

1,000-r/min Servomotors and Decelerators (Backlash:3 Arcminutes Max.)

Servomotor models *	1/5	1/11	1/21 (1/20 for flange 65)	1/33 (1/25 for flange 65)
R88M-1M90010□	R88G- HPG32A05900TB□	R88G- HPG32A11900TB□	R88G- HPG50A21900TB□	R88G- HPG50A33900TB□
R88M-1M2K010□	R88G- HPG32A052K0TB□	R88G- HPG50A112K0TB□	R88G- HPG50A212K0TB□	R88G-
R88M-1M3K020□	R88G- HPG50A055K0SB□	R88G- HPG50A115K0SB□	R88G- HPG65A205K0SB□	HPG65A255K0SB□

^{*}You cannot use a Servomotor with a key and tap (model numbers with -S2 at the end) in combination with a Decelerator.

Cable Connection Configuration

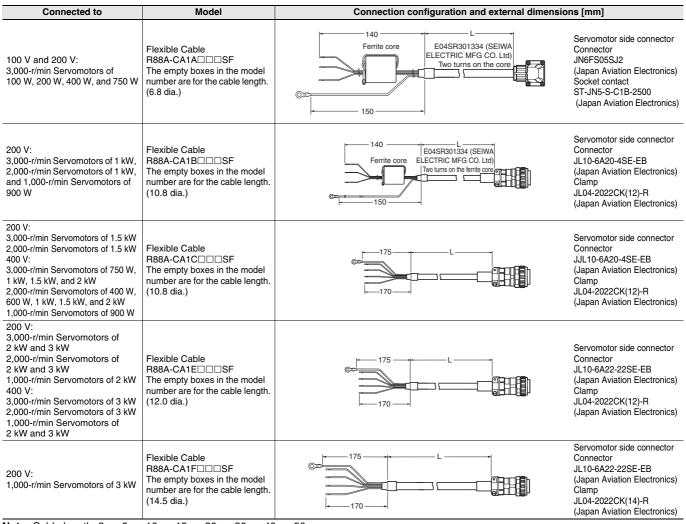
Encoder Cables

Connected to	Model	Connect	Connection configuration and external dimensions [mm]			
100 V and 200 V: 3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	Standard Cable R88A-CR1A□□□C The empty boxes in the model number are for the cable length. (3 to 20 m: 5.3 dia. 30 to 50 m: 6.0 dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Angle clamp model JN6FR07SM1 (Japan Aviation Electronics) Connector pin model LY10-C1-A1-10000 (Japan Aviation Electronics)		
200 V: 3,000-r/min Servomotors of 1 kW, 2,000-r/min Servomotors, and 1,000-r/min Servomotors 400 V: 3,000-r/min Servomotors, 2,000-r/min Servomotors, and 1,000-r/min Servomotors	Standard Cable R88A-CR1B□□□N The empty boxes in the model number are for the cable length. (6.0 dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Straight plug model JN2DS10SL1-R (Japan Aviation Electronics) Contact model JN1-22-22S-10000 (Japan Aviation Electronics)		
100 V and 200 V: 3,000-r/min Servomotors of 100 W, 200 W, 400 W and 750 W	Flexible Cable R88A-CR1A□□□CF The empty boxes in the model number are for the cable length. (3 to 20 m: 5.3 dia. 30 to 50 m: 6.0 dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Angle clamp model JN6FR07SM1 Connector pin model LY10-C1-A1-10000 (Japan Aviation Electronics)		
200 V: 3,000-r/min Servomotors of 1 kW, 2,000-r/min Servomotors, and 1,000-r/min Servomotors 400 V: 3,000-r/min Servomotors, 2,000-r/min Servomotors, and 1,000-r/min Servomotors	Flexible Cable R88A-CR1B□□□NF The empty boxes in the model number are for the cable length. (6.0 dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Straight plug model JN2DS10SL1-R (Japan Aviation Electronics) Contact model JN1-22-22S-10000 (Japan Aviation Electronics)		

Note: Cable length: 3 m, 5 m, 10 m, 15 m, 20 m, 30 m, 40 m, 50 mThe empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.

Power Cables without Brake Wire

Connected to	Model	Connection configuration and external dimensi	ons [mm]
100 V and 200 V: 3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	Standard Cable R88A-CA1A□□□S The empty boxes in the model number are for the cable length. (6.8 dia.)	Ferrite core E04SR301334 (SEIWA ELECTRIC MFG CO. Ltd) Two turns on the core	Servomotor side connector Connector JN6FS05SJ2 (Japan Aviation Electronics) Socket contact ST-JN6-S-C1B-2500 (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1 kW, 2,000-r/min Servomotors of 1 kW, and 1,000-r/min Servomotors of 900 W	Standard Cable R88A-CA1B□□□S The empty boxes in the model number are for the cable length. (10.8 dia.)	Ferrite core SEWA ELECTRIC MFG CO. Ltd) Two turns on the core	Servomotor side connector Connector JL10-6A20-4SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1.5 kW and 2,000-r/min Servomotors of 1.5 kW 400 V: 3,000-r/min Servomotors of 750 W, 1 kW, 1.5 kW, and 2 kW 2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, and 2 kW 1,000-r/min Servomotors of 900 W	Standard Cable R88A-CA1C□□□S The empty boxes in the model number are for the cable length. (10.8 dia.)	175	Servomotor side connector Connector JL10-6A20-4SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 2 kW and 3 kW 2,000-r/min Servomotors of 2 kW and 3 kW 1,000-r/min Servomotors of 2 kW 400 V: 3,000-r/min Servomotors of 3 kW 2,000-r/min Servomotors of 3 kW 1,000-r/min Servomotors of 2 kW and 3 kW	Standard Cable R88A-CA1E□□□S The empty boxes in the model number are for the cable length. (12.0 dia.)	175	Servomotor side connector Connector JL10-6A22-22SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Japan Aviation Electronics)
200 V: 1,000-r/min Servomotors of 3 kW	Standard Cable R88A-CA1F□□□S The empty boxes in the model number are for the cable length. (14.5 dia.)	175	Servomotor side connector Connector JL10-6A22-22SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(14)-R (Japan Aviation Electronics)

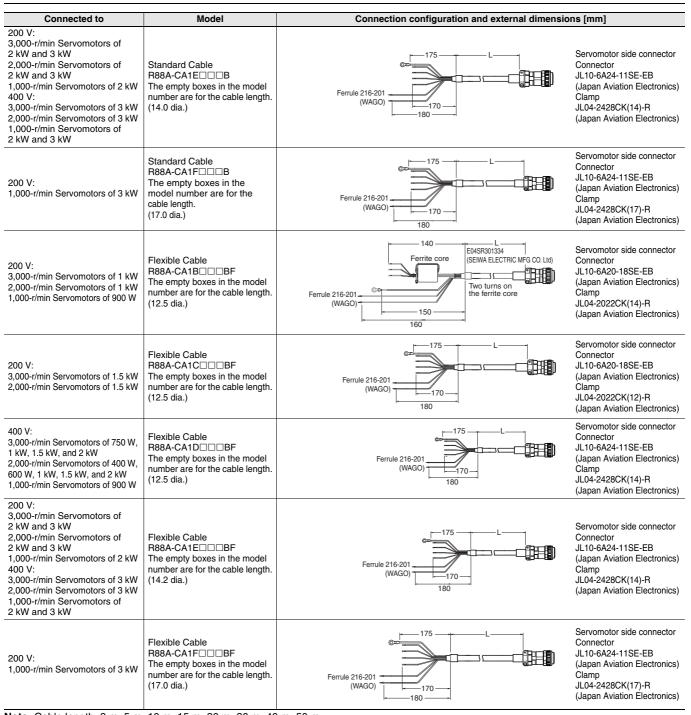


Note: Cable length: 3 m, 5 m, 10 m, 15 m, 20 m, 30 m, 40 m, 50 m

The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.

Power Cables with Brake Wire

Connected to	Model	Connection configuration and external dimension	ons [mm]
200 V: 3,000-r/min Servomotors of 1 kW 2,000-r/min Servomotors of 1 kW 1,000-r/min Servomotors of 900 W	Standard Cable R88A-CA1B□□□B The empty boxes in the model number are for the cable length. (12.5 dia.)	Ferrule 216-201 (WAGO) 150	Servomotor side connector Connector JL10-6A20-18SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1.5 kW 2,000-r/min Servomotors of 1.5 kW	Standard Cable R88A-CA1C□□□B The empty boxes in the model number are for the cable length. (12.5 dia.)	Ferrule 216-201 (WAGO) 170 — 180	Servomotor side connector Connector JL10-6A20-18SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Japan Aviation Electronics)
400 V: 3,000-r/min Servomotors of 750 W, 1 kW, 1.5 kW, and 2 kW 2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, and 2 kW 1,000-r/min Servomotors of 900 W	Standard Cable R88A-CA1D□□□B The empty boxes in the model number are for the cable length. (12.5 dia.)	Ferrule 216-201 (WAGO) 170 180	Servomotor side connector Connector JL10-6A24-11SE-EB (Japan Aviation Electronics) Clamp JL04-2428CK(14)-R (Japan Aviation Electronics)



Note: Cable length: 3 m, 5 m, 10 m, 15 m, 20 m, 30 m, 40 m, 50 mThe empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.

Brake Cables

Connected to	Model	Connection configuration and external dimensions [mm]	
100 V and 200 V: 3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	Standard Cable R88A-CA1A□□□B The empty boxes in the model number are for the cable length. (5.0 dia.)	Ferrule 216-201 (WAGO) Servomotor side Connector JN6FR02SM1 (Japan Aviation Socket contact LY10-C1-A1-100 (Japan Aviation	Electronics)
100 V and 200 V: 3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	Flexible Cable R88A-CA1A□□□BF The empty boxes in the model number are for the cable length. (5.0 dia.)	Ferrule 216-201 (WAGO) Servomotor side Connector JN6FR02SM1 (Japan Aviation Socket contact LY10-C1-A1-100 (Japan Aviation	Electronics)

Note: Cable length: 3 m, 5 m, 10 m, 15 m, 20 m, 30 m, 40 m, 50 m

The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.

Related Manuals

English Man.No.	Japanese Man.No.	Model	Manual name
1586	SBCE-377	R88M-1□/R88D-1SN□-ECT	AC Servomotors/Servo Drives 1S-Series with EtherCAT Communications User's Manual
W535	SBCA-418	NX701-□□□	NX-series CPU Unit User's Manual (Hardware)
W500	SBCA-358	NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ-series CPU Unit User's Manual (Hardware)
W501	SBCA-359	NX701-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ-series / NX-series CPU Unit User's Manual (Software)
W507	SBCE-363	NX701-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ-series / NX-series CPU Unit User's Manual (Motion Control)
Z930	SGFM-710	NX-SLOOO NX-SIOOO NX-SOOOOO	NX-series Safety Control Unit User's Manual
W504	SBCA-362	SYSMAC-SE2□□□	Sysmac Studio Version 1 Operation Manual
1589	SBCE-401	SYSMAC-SE2□□□	Sysmac Studio Drive Function Operation Manual
Z922	SJLB-306	G9SP-N10S G9SP-N10D G9SP-N20S	G9SP Series Safety Controller Operation Manual

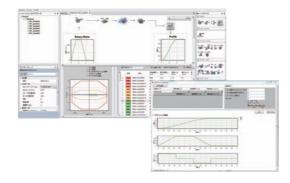
Mechatronics Sizing Tool for AC Servo Motors

AC Servo motors selection for the entire machine

- User can size all axes in one project with the corresponded Sysmac controller.
- Pre-defined system can be used for common applications.
- Selection of optimized drive, motor and gearbox combination.
- Multiple views are not required: design, adjust and validate at a glance.
- Import sizing file directly to Sysmac Studio for reducing the machine development time.

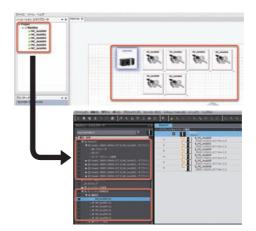
Quick sizing and selection of AC servo motors

- · High variety of mechanical system
- Import CAM from Sysmac Studio
- Kinematics chain architecture includes motor, reducer, loads and motion profile.
- Adjustments can be done in one view and results autorefreshed.



Re-use work done during design phase

- Export sizing file result.
- Import sizing file result in Sysmac Studio.
- EtherCAT configuration, axes settings and drives parameters will be created automatically



Compatible models

1S series	EtherCAT Communications	R88D-1SN□-ECT
G5 series	EtherCAT Communications for Position Control	R88D-KN□-ECT(-R)
G5 series	EtherCAT Communications (Linear Motor Type)	R88D-KN□-ECT-L
G5 series	MECHATROLINK-II Communications	R88D-KN□-ML2
G5 series	General-purpose Pulse Train or Analog Inputs	R88D-KT
G series	MECHATROLINK-II Communications	R88D-GN□-ML2
G series	General-purpose Pulse Train or Analog Inputs	R88D-GT
Smart Step 2	General-purpose Pulse Train	R7D-BP

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OMRON Corporation Industrial Automation Company

Kyoto, JAPAN

Contact: www.ia.omron.com

Regional Headquarters OMRON EUROPE B.V.

Wegalaan 67-69, 2132 JD Hoofddorp The Netherlands Tel: (31)2356-81-300/Fax: (31)2356-81-388

OMRON ASIA PACIFIC PTE. LTD.

No. 438A Alexandra Road # 05-05/08 (Lobby 2), Alexandra Technopark, Singapore 119967 Tel: (65) 6835-3011/Fax: (65) 6835-2711

OMRON ELECTRONICS LLC

OMHON ELECTHONICS LLC 2895 Greenspoint Parkway, Suite 200 Hoffman Estates, IL 60169 U.S.A. Tel: (1) 847-843-7900/Fax: (1) 847-843-7787

OMRON (CHINA) CO., LTD.

Room 2211, Bank of China Tower, 200 Yin Cheng Zhong Road, PuDong New Area, Shanghai, 200120, China Tel: (86) 21-5037-2222/Fax: (86) 21-5037-2200

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