

SOMMAIRE

FOLIO DESIGNATION

05	ALIMENTATIONS 05
07	ALIMENTATIONS 07
08	PUISSANCE 08
09	PUISSANCE 09
10	VARIATEUR 10
14	DEVELOPPE 14
16	SECURITE 16
20	CONFIG API 20
21	CONFIG CPU 21
23	CONFIG ET 200 23
24	ALIM 24V ENTREE 24
25	ENTREES 25
26	ENTREES 26
27	ENTREES 27
28	ENTREES 28
29	ENTREES 29
32	ALIM 24V SORTIES 32
33	SORTIES 33
34	SORTIES 34
35	SORTIES 35
36	SORTIES 36
37	SORTIES 37
38	SORTIES 38
39	SORTIES 39
40	DEVELOPPE 40
41	DEVELOPPE 41
43	DEVELOPPE 43
44	DEVELOPPE 44
45	PARAMETRES 45
46	PARAMETRES 46
48	IMPLANTATION ARMOIRE 48
49	IMPLANTATION ARMOIRE 49
50	IMPLANTATION BOUTONNERIE 50
58	CONFIG API 22
59	CONFIG API 23

K				
J				
I				
H				
G				
F				
E				
D				
C				
B				
A				
	MODIFICATION	DATE	PAR	

SPECIFICITE CLIENT :

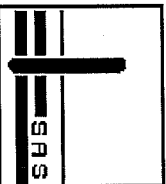
DESSINE LE : 28-04-2011 PAR : F.T Nbre de FOLIOS : 30

MACHINE : NASTRO + ROBOT 6 AXES N° : PA078

CLIENT : SACCHI TENSION : 3X400V+N

NOM PROGRAMME :

PUISSANCE MACHINE : 4KW CONSOMMATION D'AIR :

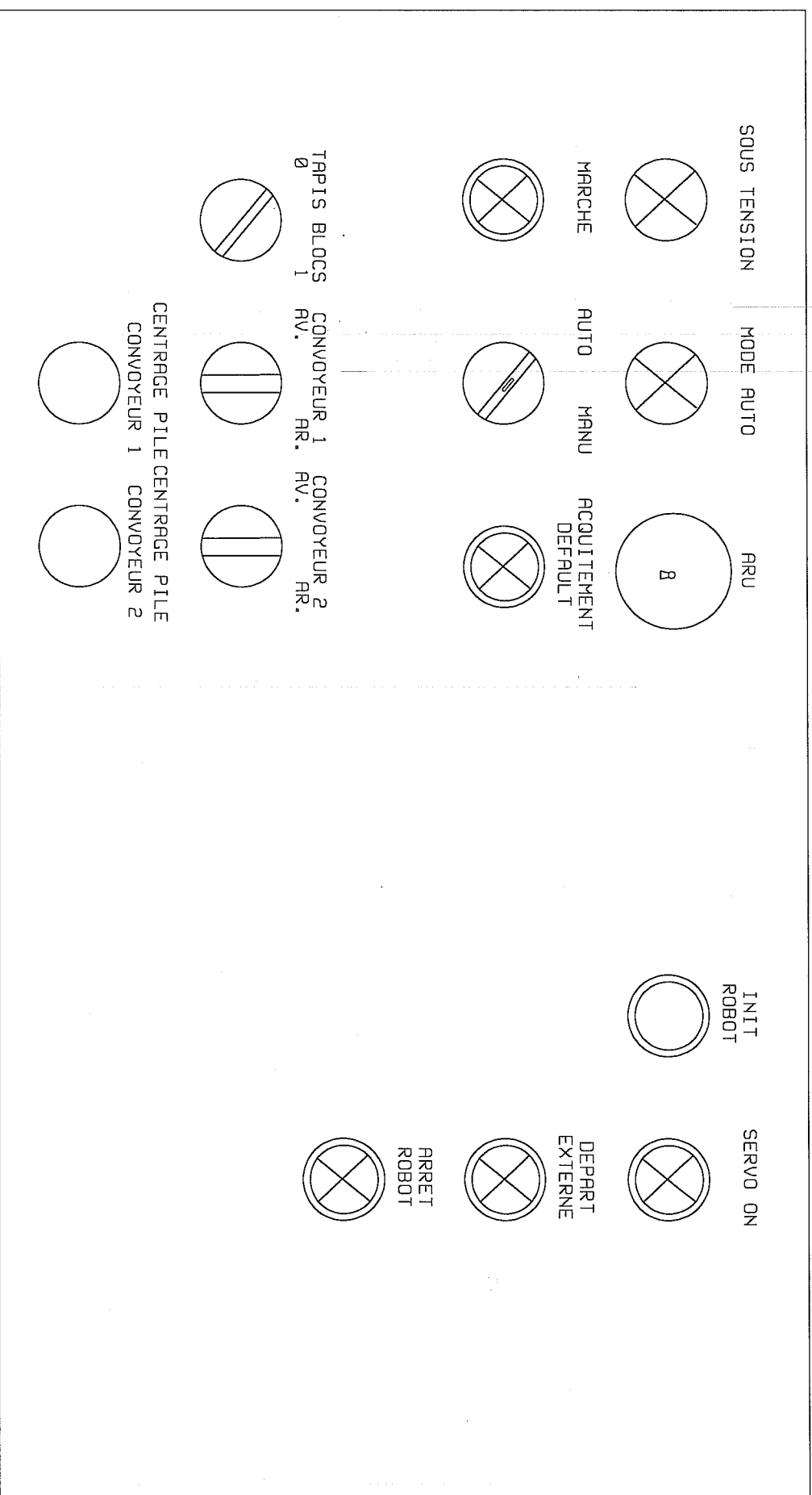


SODEME

SIEGE SOCIAL: Z.I. de la Croix Cadeau 49240 BP 60093 - AVRILLE Tél :02-41-42-35-00 Fax: 02-41-42-30-41

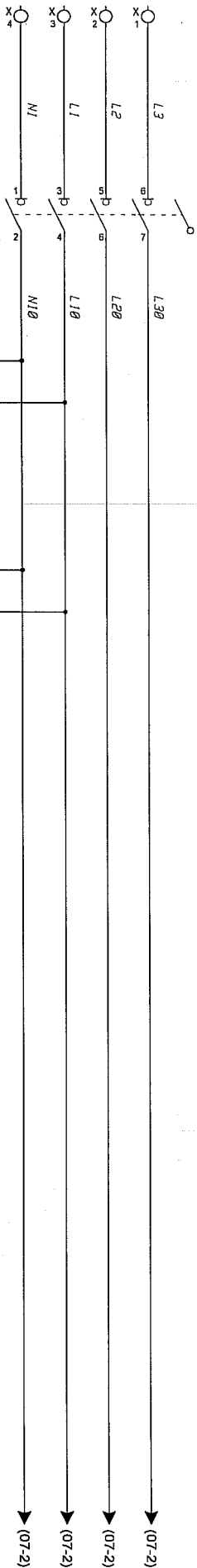
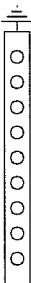
Ce plan est la propriété de S.A.S. SODEME. Il ne pourra sans son autorisation écrite, être utilisé ou communiqué à des tiers.
Toutes précautions utiles devront être prises pour en éviter la divulgation. (Loi du 11/03/1902.)

IMPLANTATION BOUTONNERIE PUPITRE (vue de FACE)



ALIMENTATION
3x400V 50Hz

BARRETTE DE RACCORDEMENT
DE TOUTES LES TERRES EN
ETOILE



05QS1
25A

05FU1
1AgG

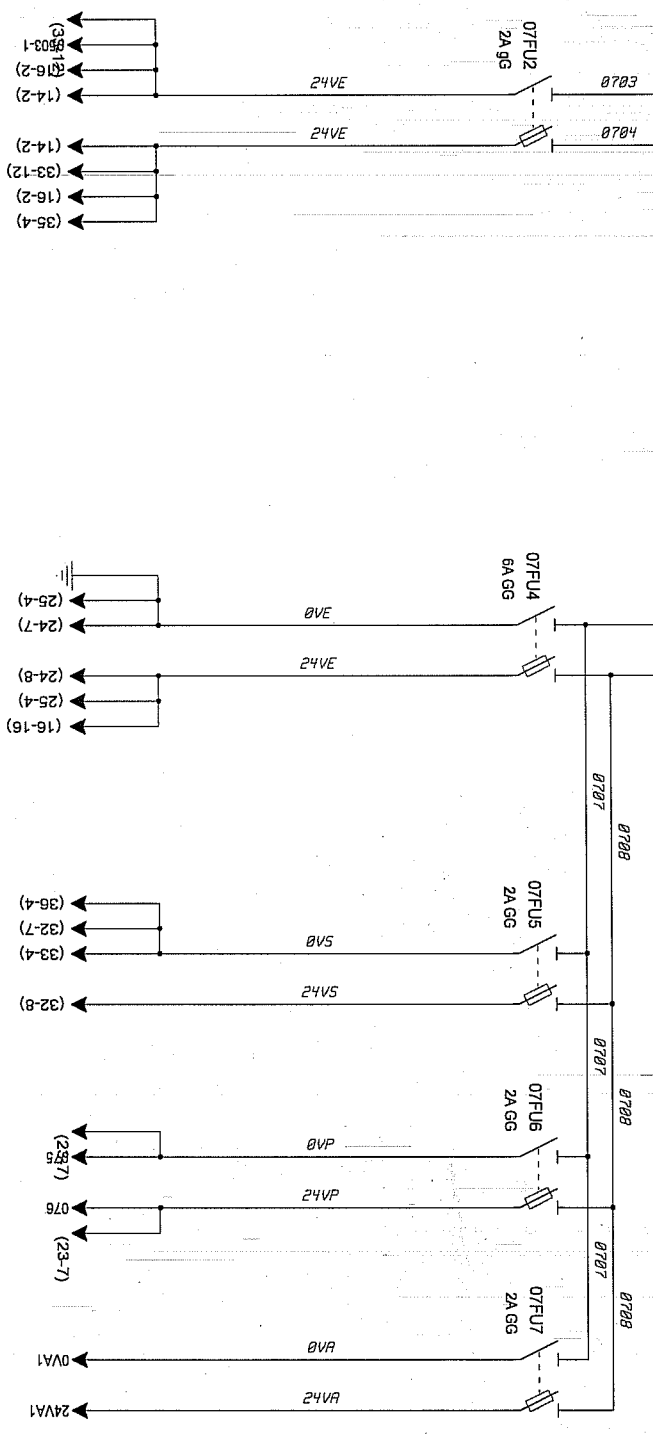
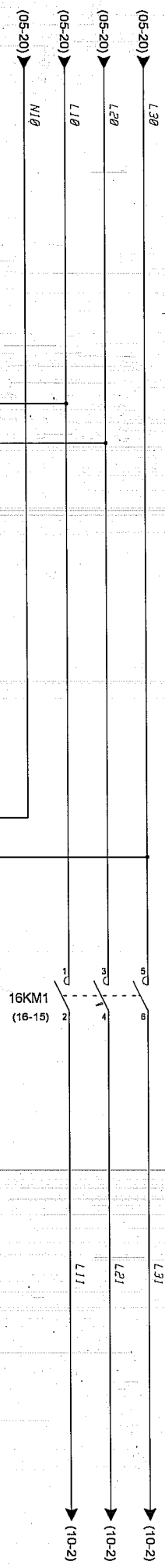
05QF1
10A
30mA

05EV1

05XS1

VENTILATEURS
ARMOIRES

PRISE DE COURANT
ARMOIRE



ALIMENTATION 110VAC
SORTIES

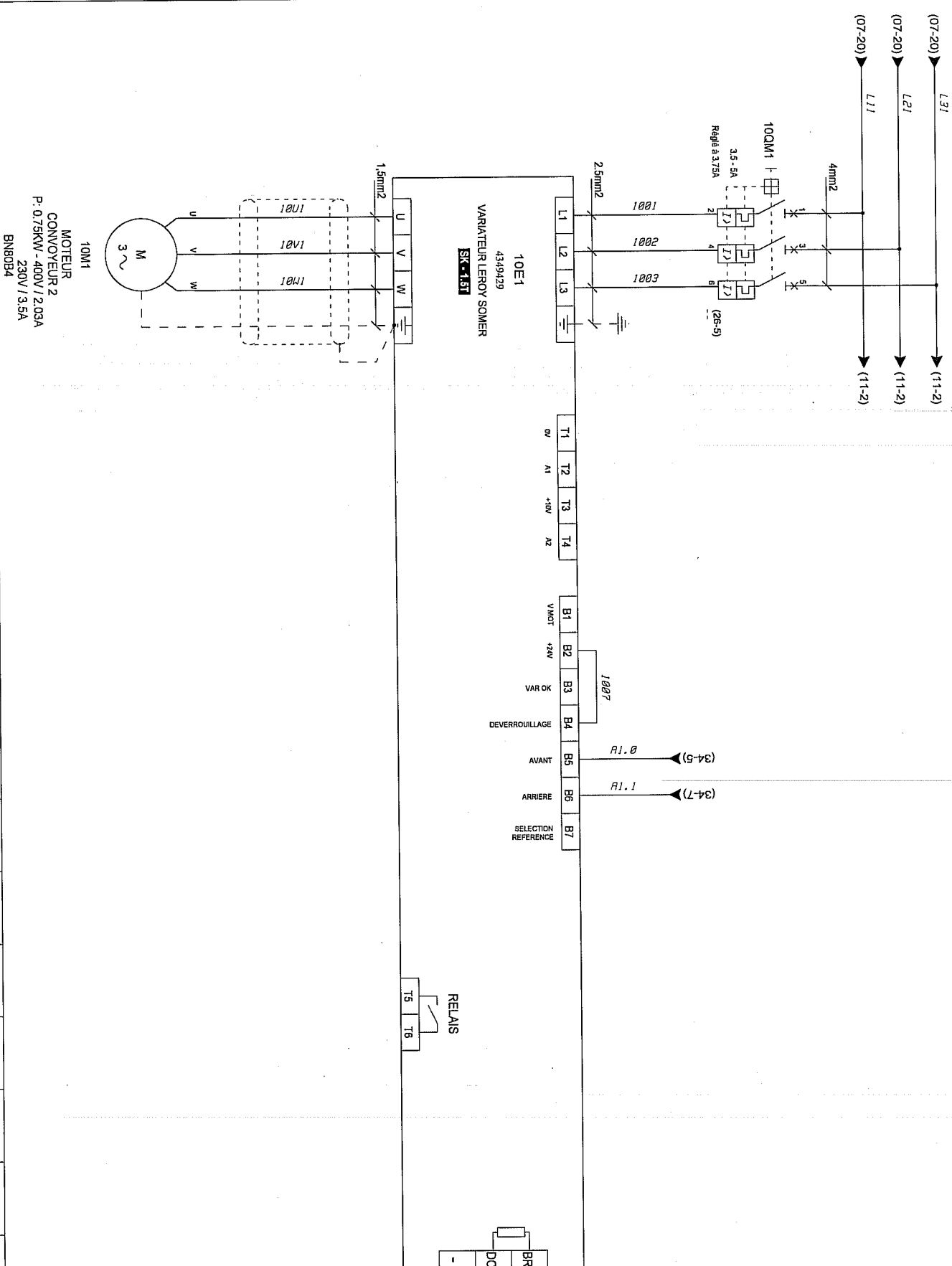
ALIMENTATION 24VDC

ALIMENTATION 24VDC
SORTIE

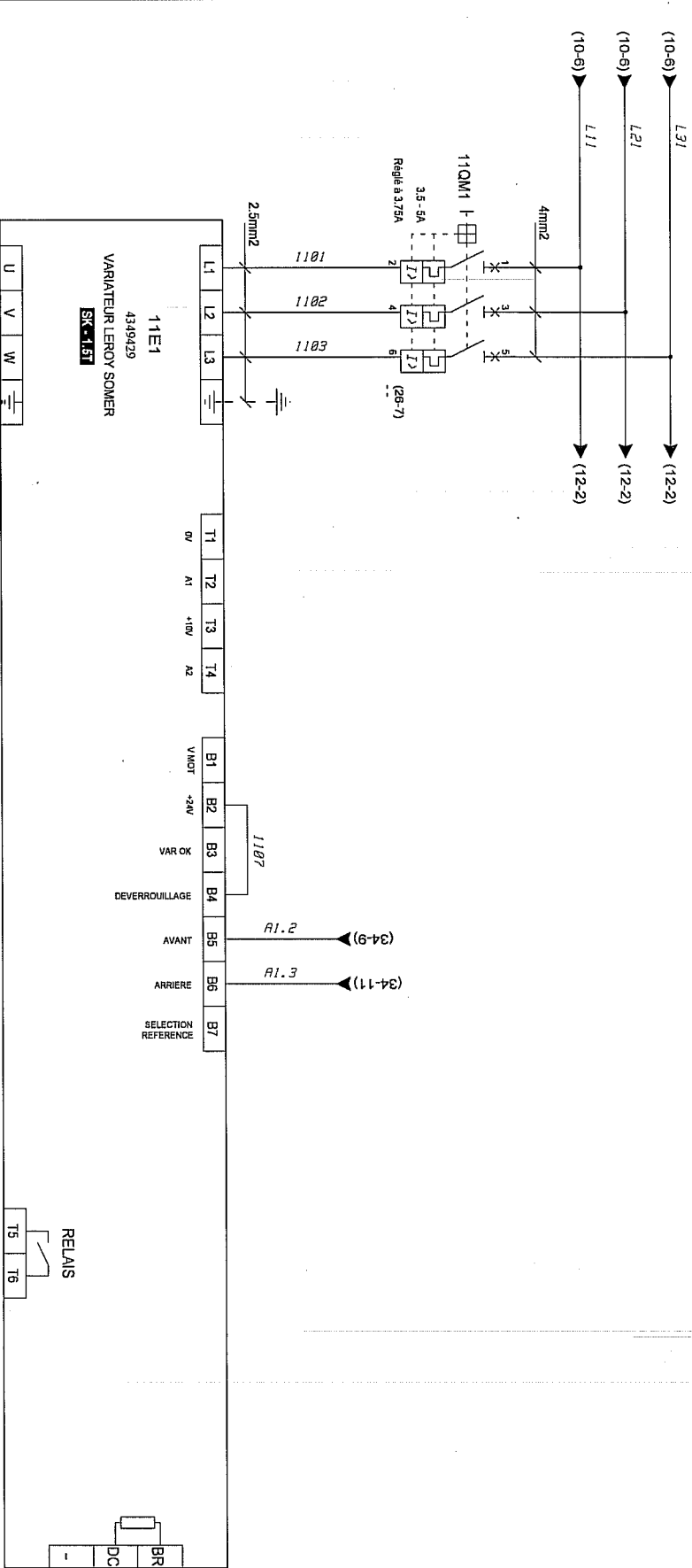
ALIMENTATION 24VDC
AUTOMATE

ALIMENTATION 24VDC
ROBOT MOTOMAN

VITESSE·CONVOYEUR 2

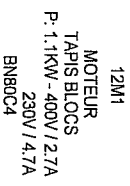


VITESSE CONVOYEUR 1



[illegible]

RELAIS	
T5	T6

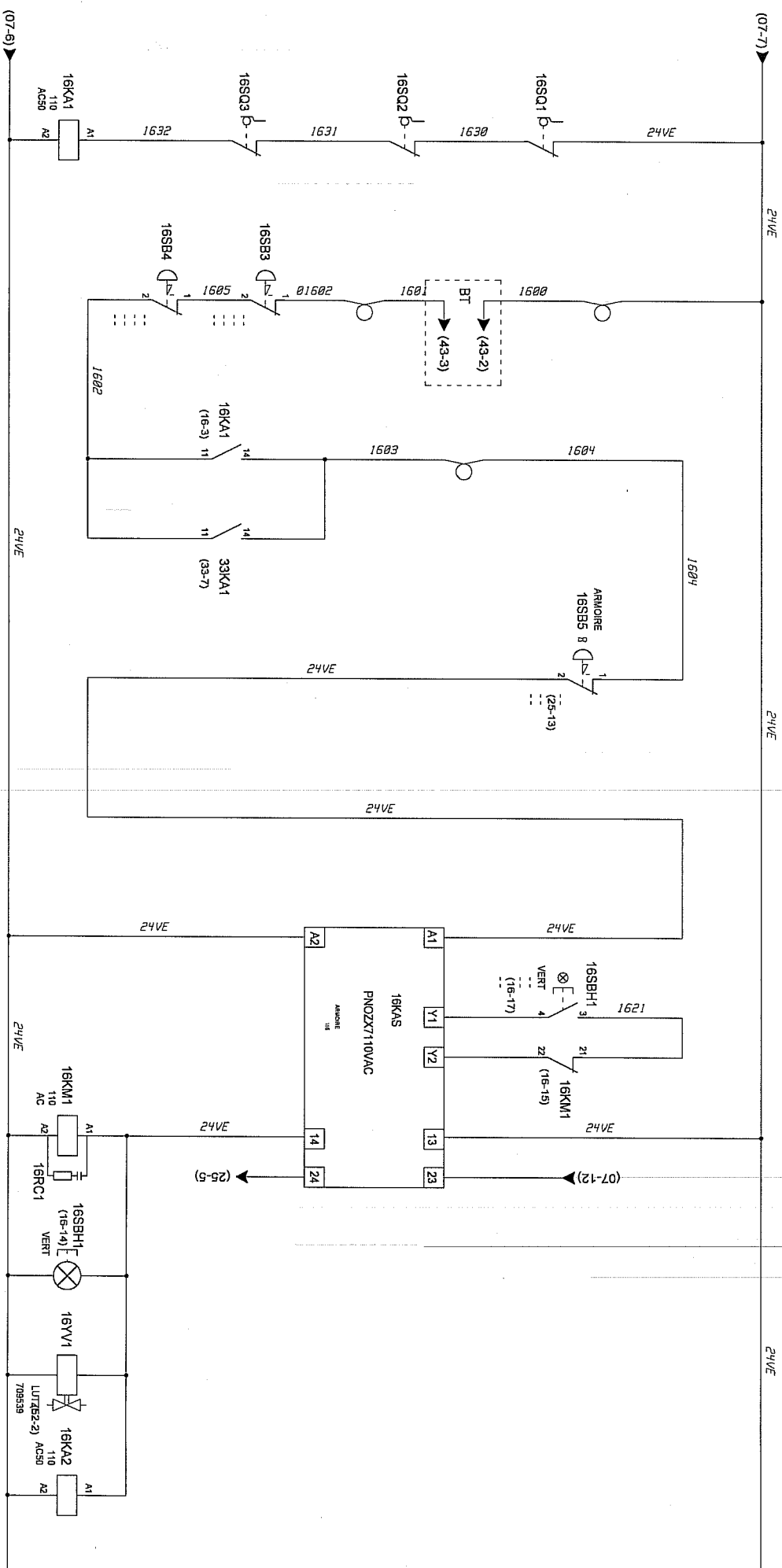


(07-6) 24VE

24VE

ARMOIRE X1
14HL1
BLANC X2
VOYANT

(07-6) 24VE
Sous
Tension



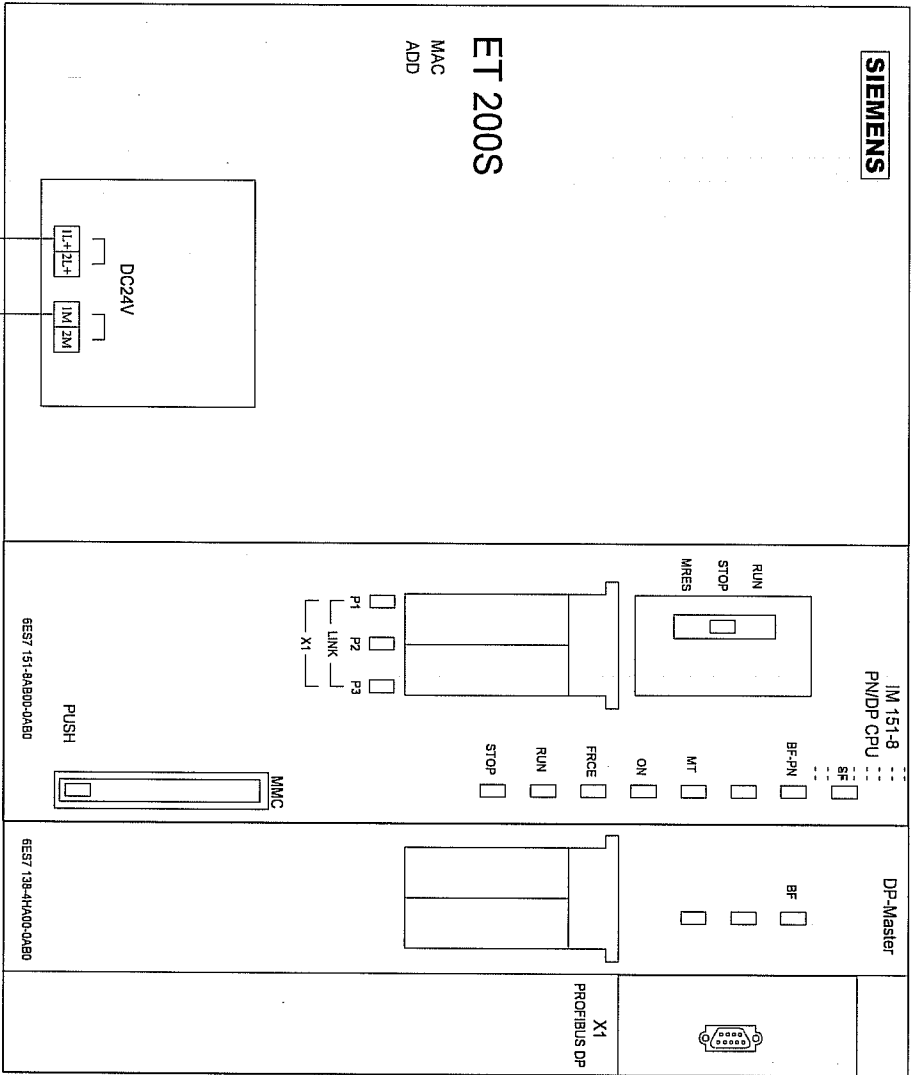
CPU

Diagram illustrating the IM151 Standard module. The top view shows the Siemens logo and the text "IM 151 STANDARD". The side view shows the module's profile with a DIN rail connector. The bottom view shows the 16-pin connector with pins numbered 1 to 16.

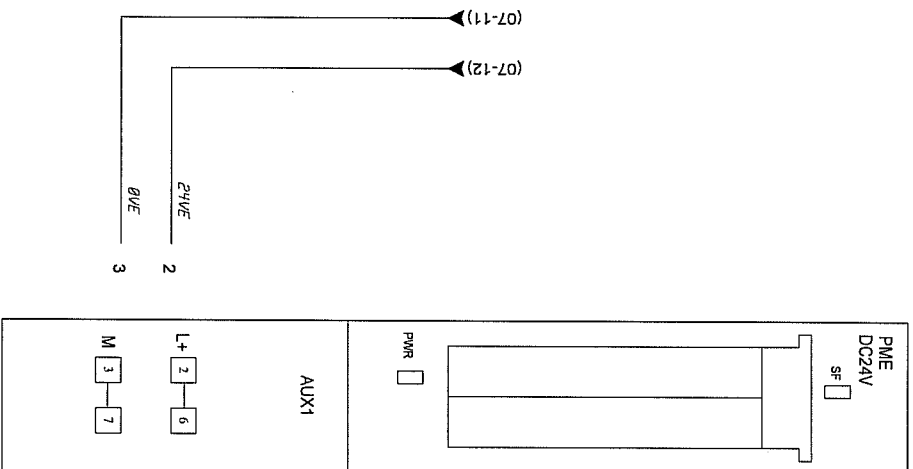
IP: 192.168.10.110

23E2

6ES7 151-8AB00-0AB0

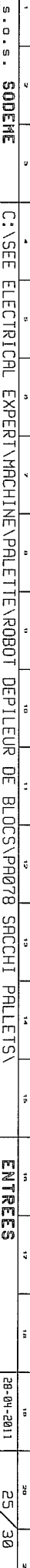


24E1
6ES7 138-4CA01-0AA0
6ES7 193-4CC20-0AA0

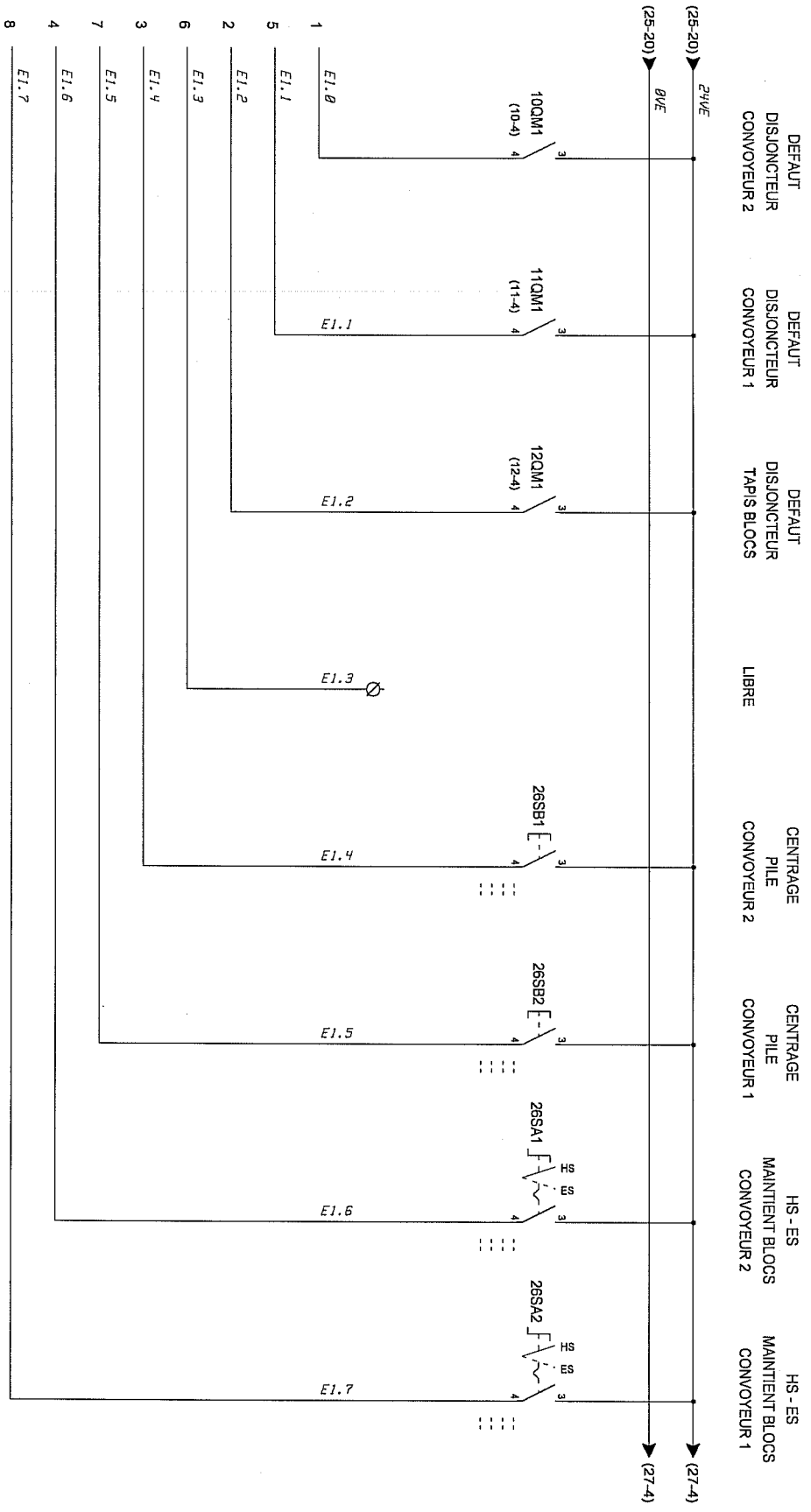
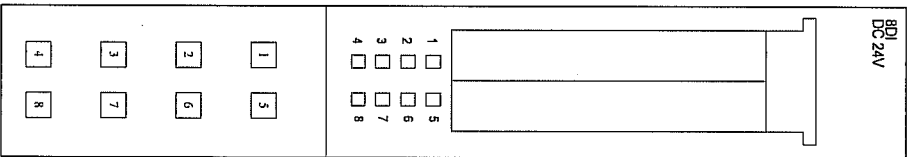


6ES7 193-4CB20-0AA0/U

6ES7 132-4BD00-0AA0



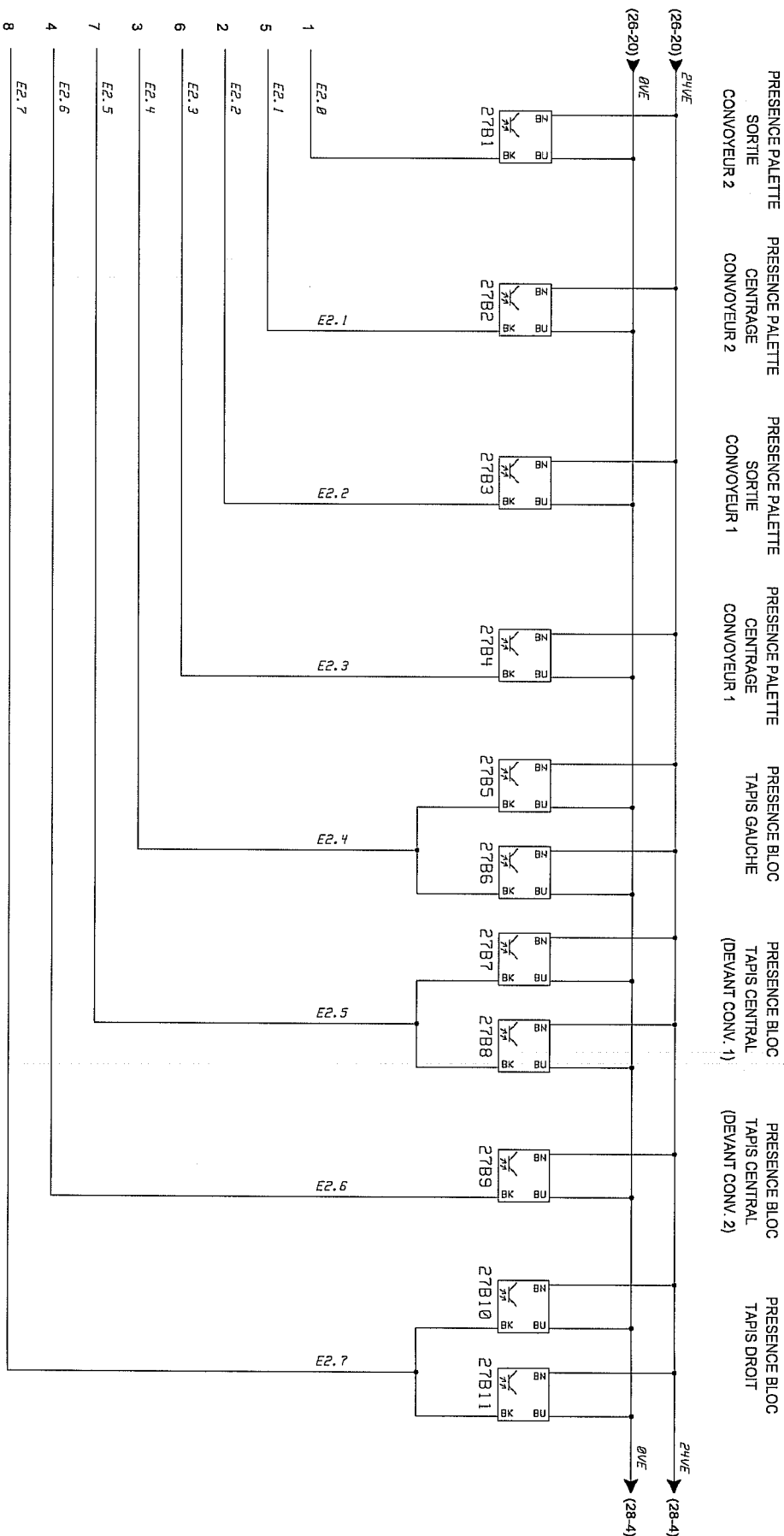
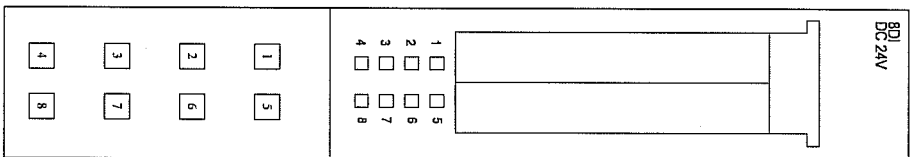
26E2
6ES7 193-4CB20-0AA0U
6ES7 132-4BD00-0AA0



27E2

6ES7 193-4CB20-0AA0/U

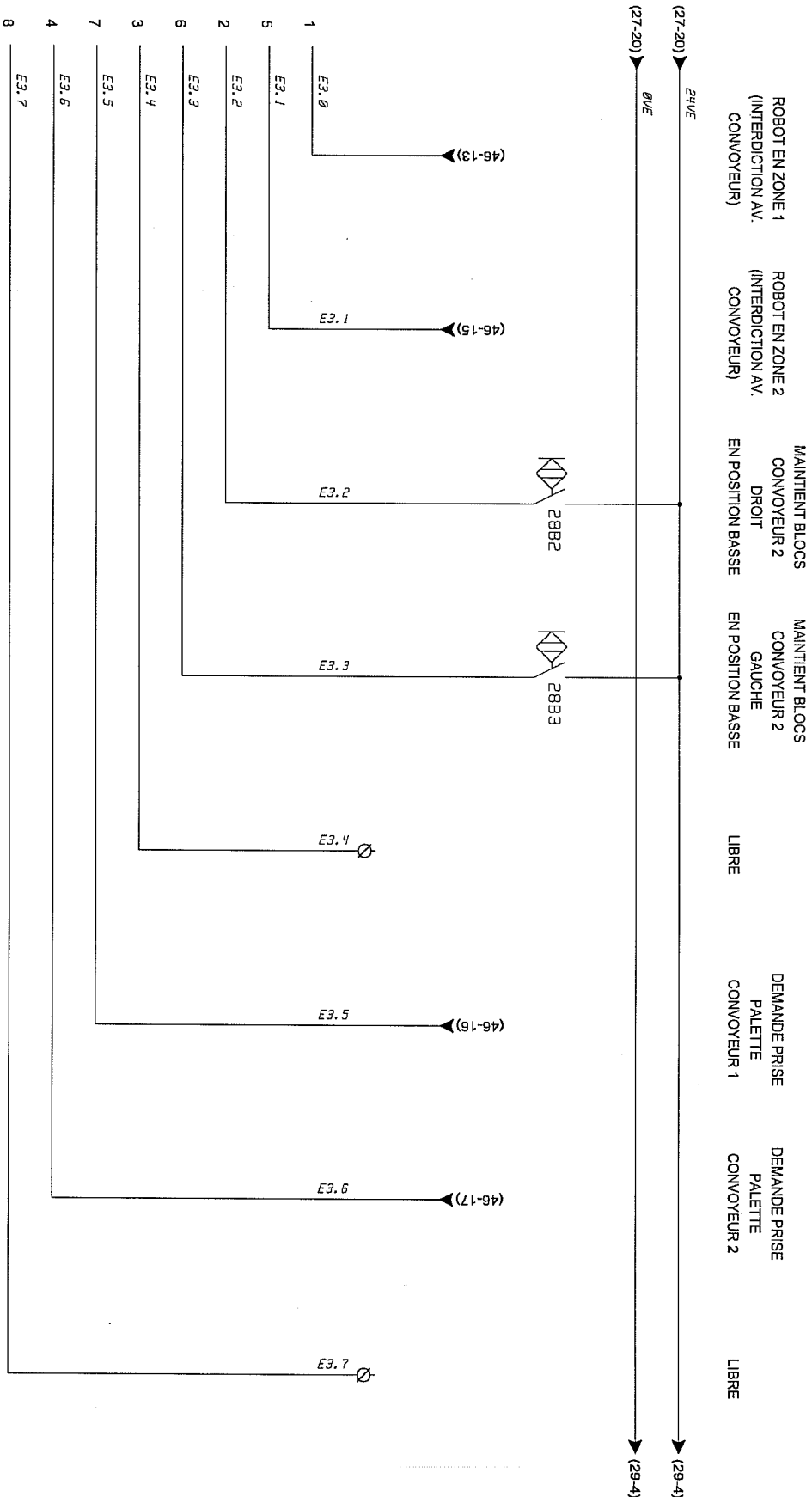
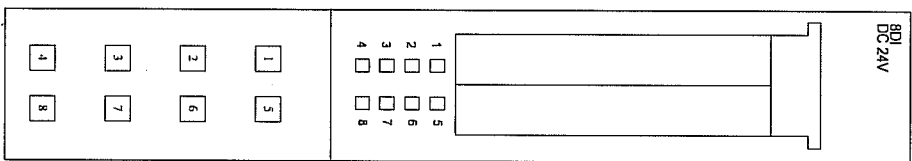
6ES7 132-4BD00-0AA0



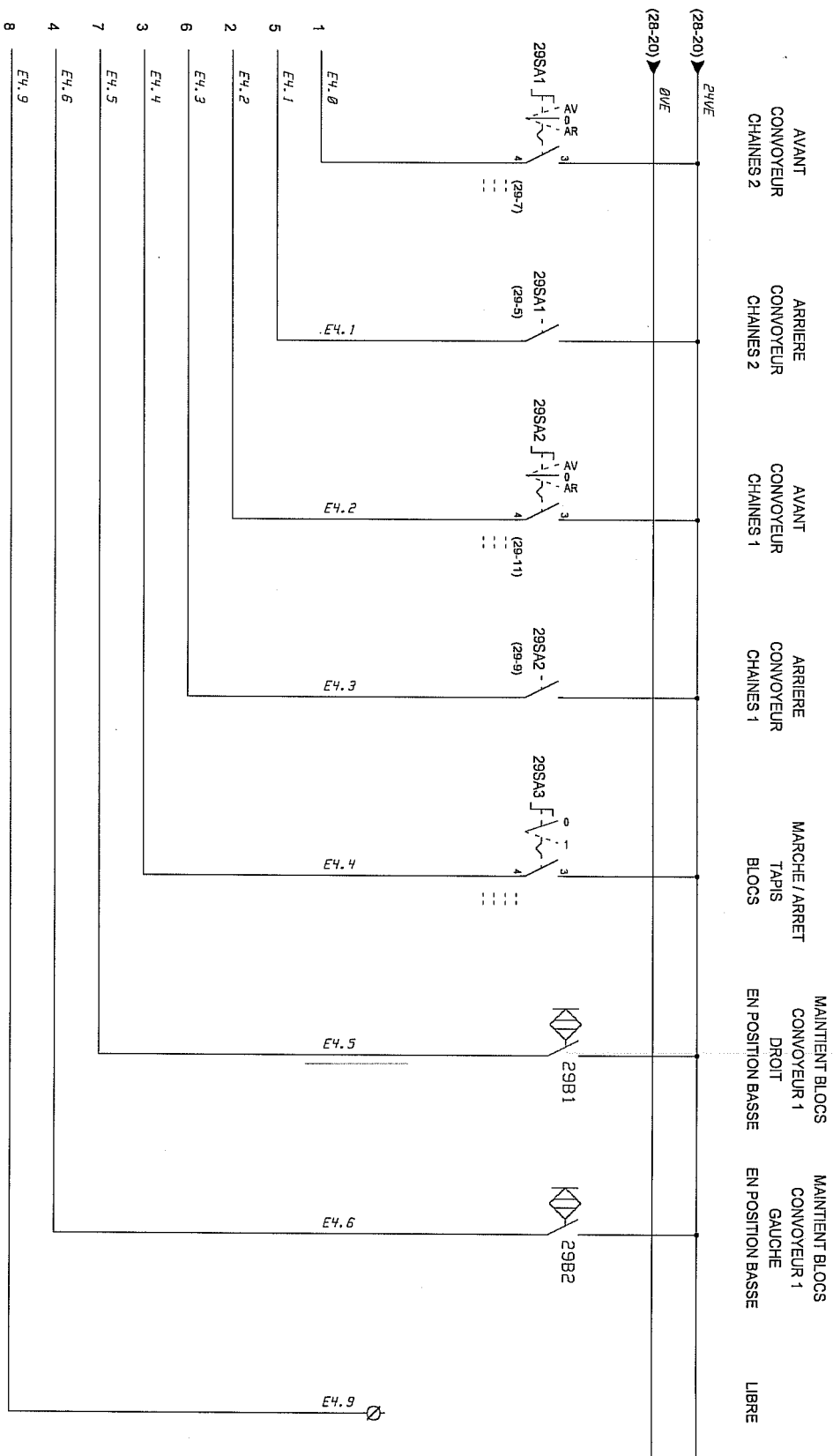
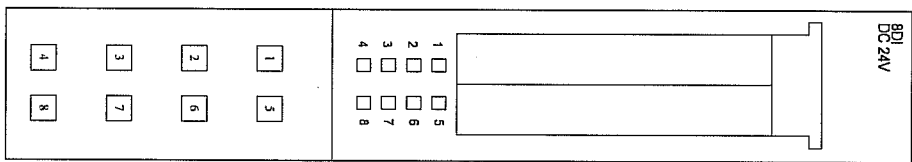
28E2

6ES7 193-1CB20-0AA0U

6ES7 132-1BD00-0AA0



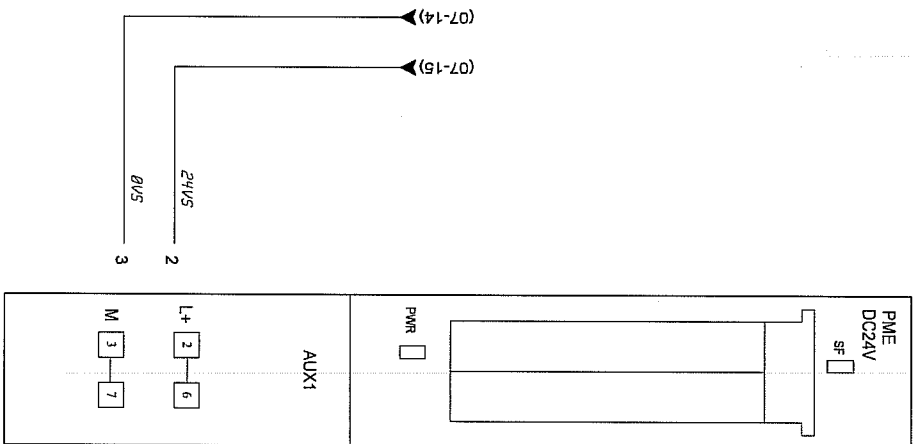
29E2
6ES7 193-1CB20-0AA0/U
6ES7 132-4BD00-0AA0



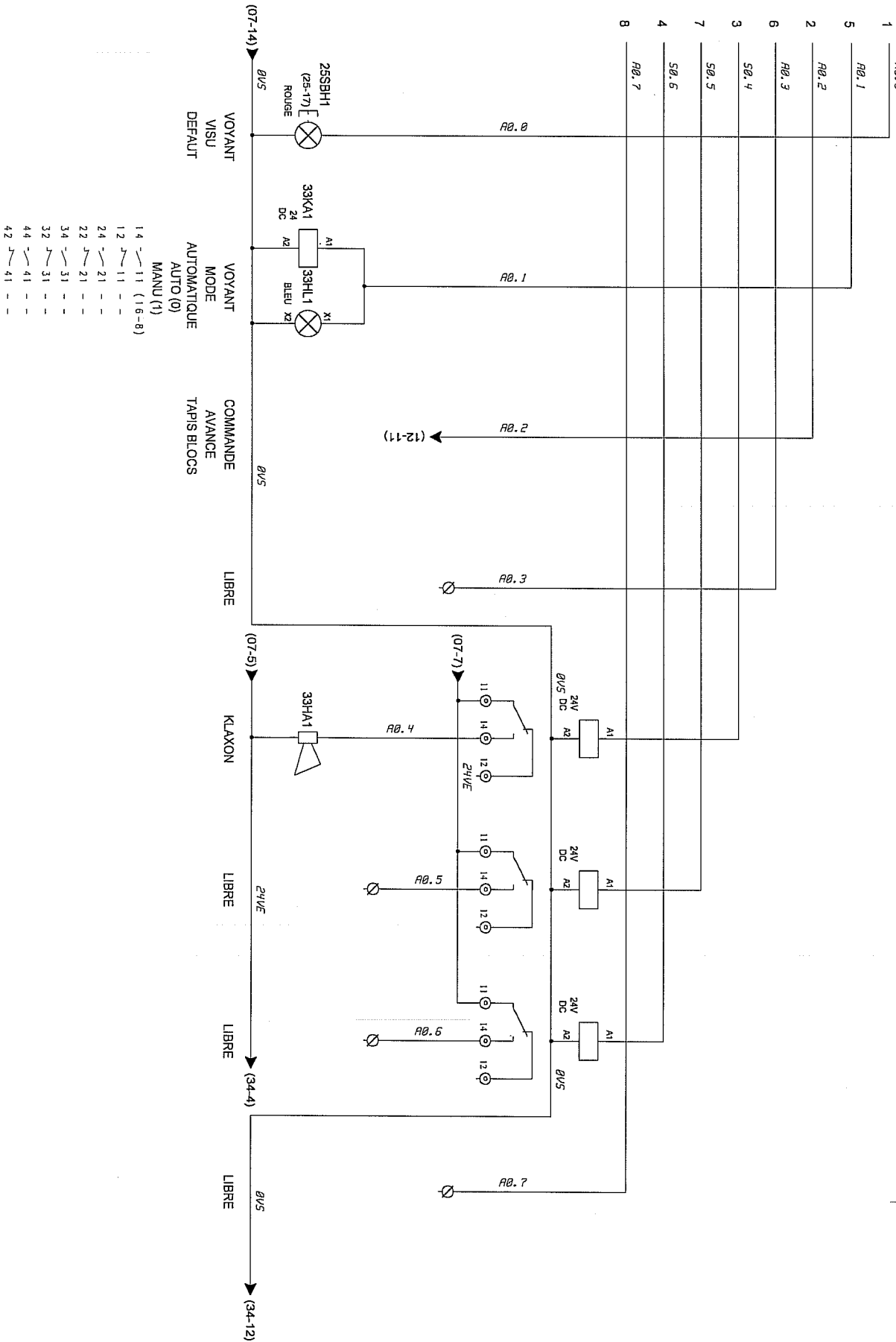
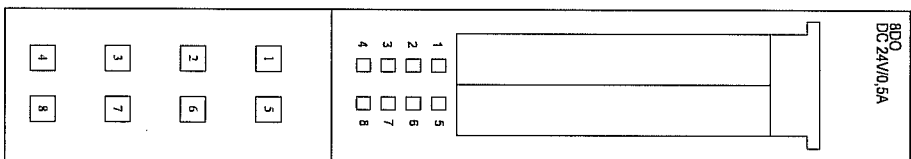
32E1

6ES7 138-4CA01-0AA0

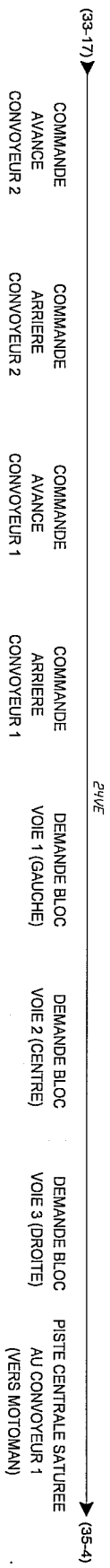
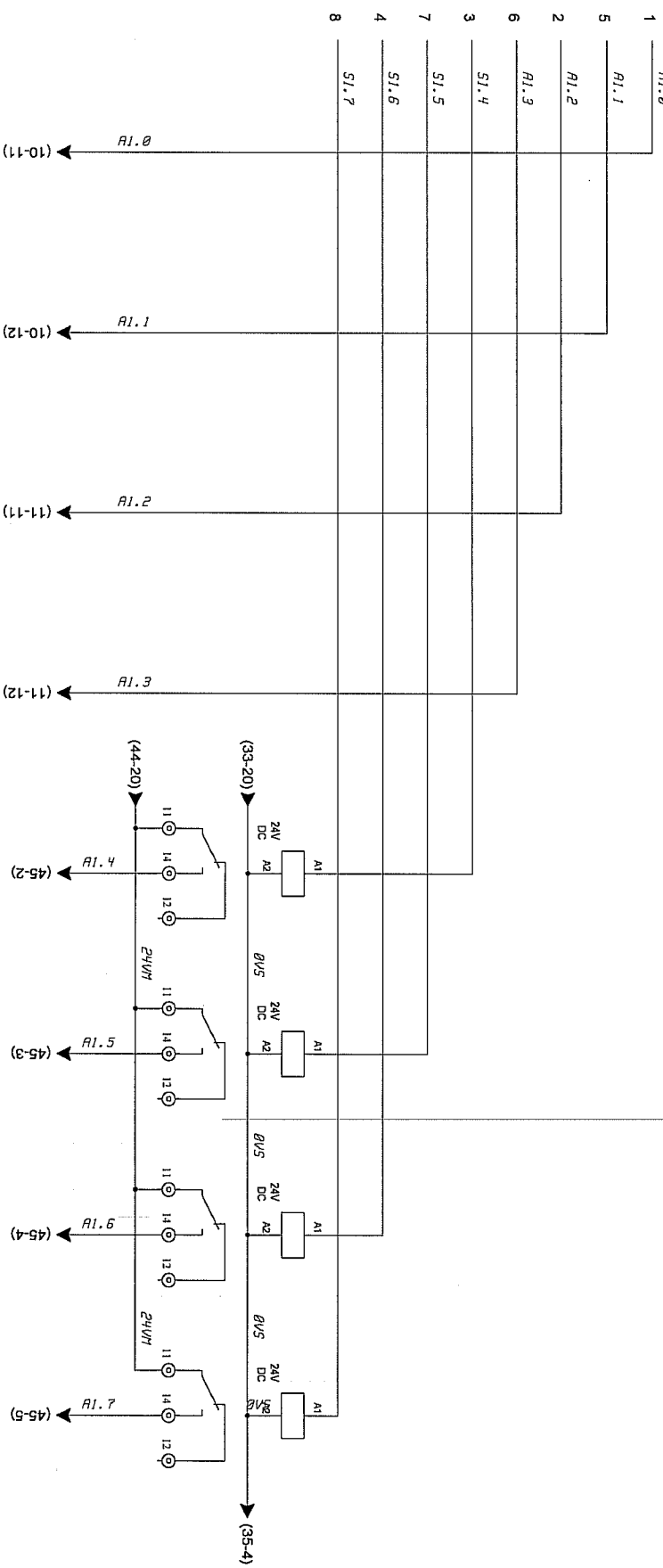
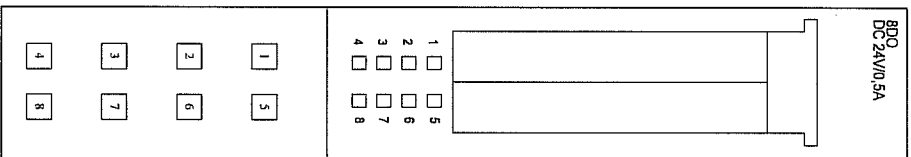
6ES7 193-4CC20-0AA0



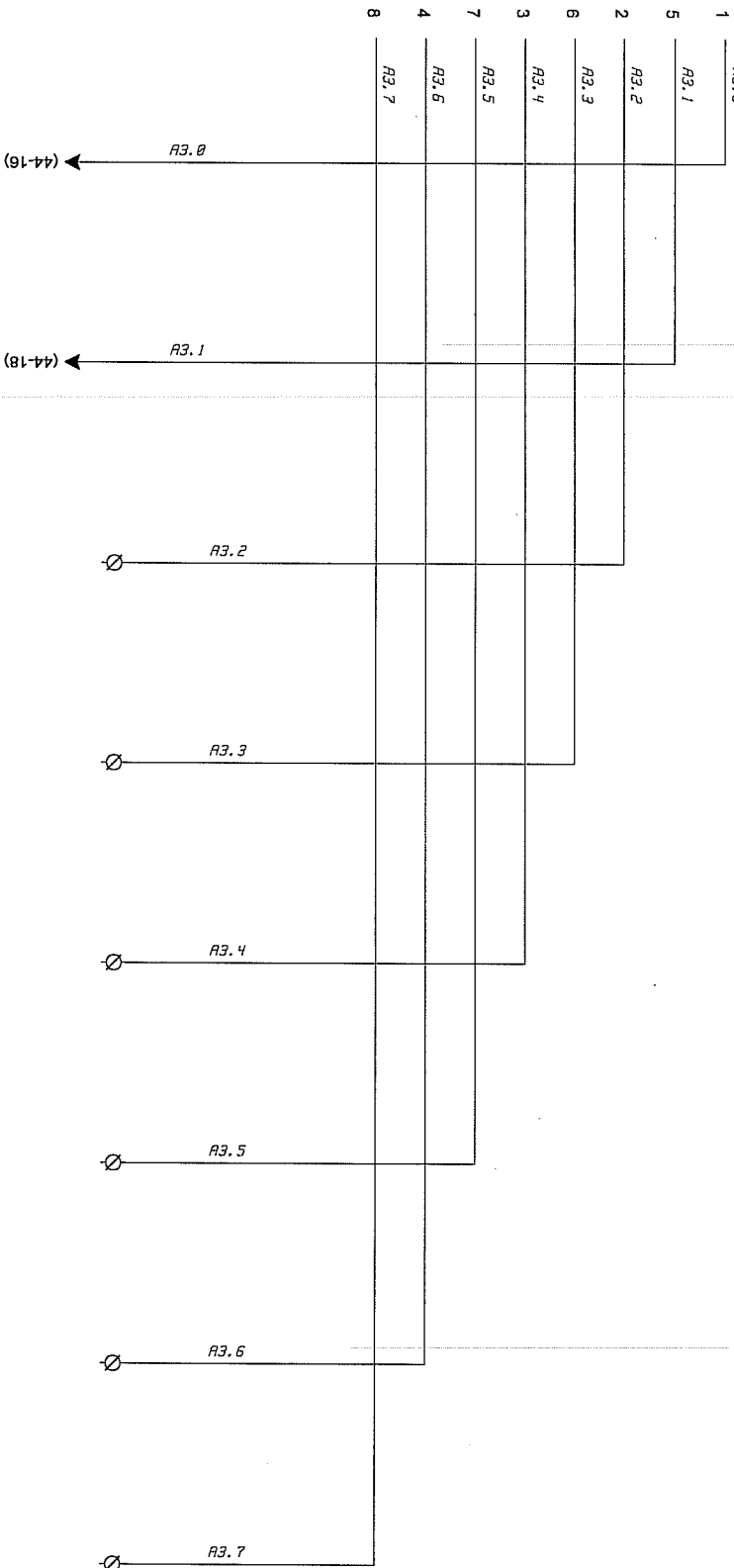
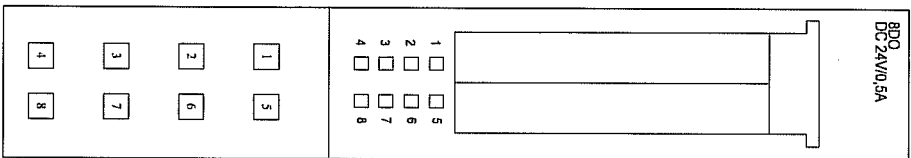
33E1
6ES7 193-4CB20-0AA0U
6ES7 132-4BD00-0AA0



34E1
6ES7 193-4CB20-0AA0U
6ES7 132-4BD00-0AA0



36E1
6ES7 193-1CB20-0AA0/U
6ES7 132-4BD00-0AA0



(07-14) →

AUTORISATION PRISE PALETTE CONVOYEUR 1	AUTORISATION PRISE PALETTE CONVOYEUR 2	LIBRE	LIBRE	LIBRE	LIBRE	LIBRE	LIBRE

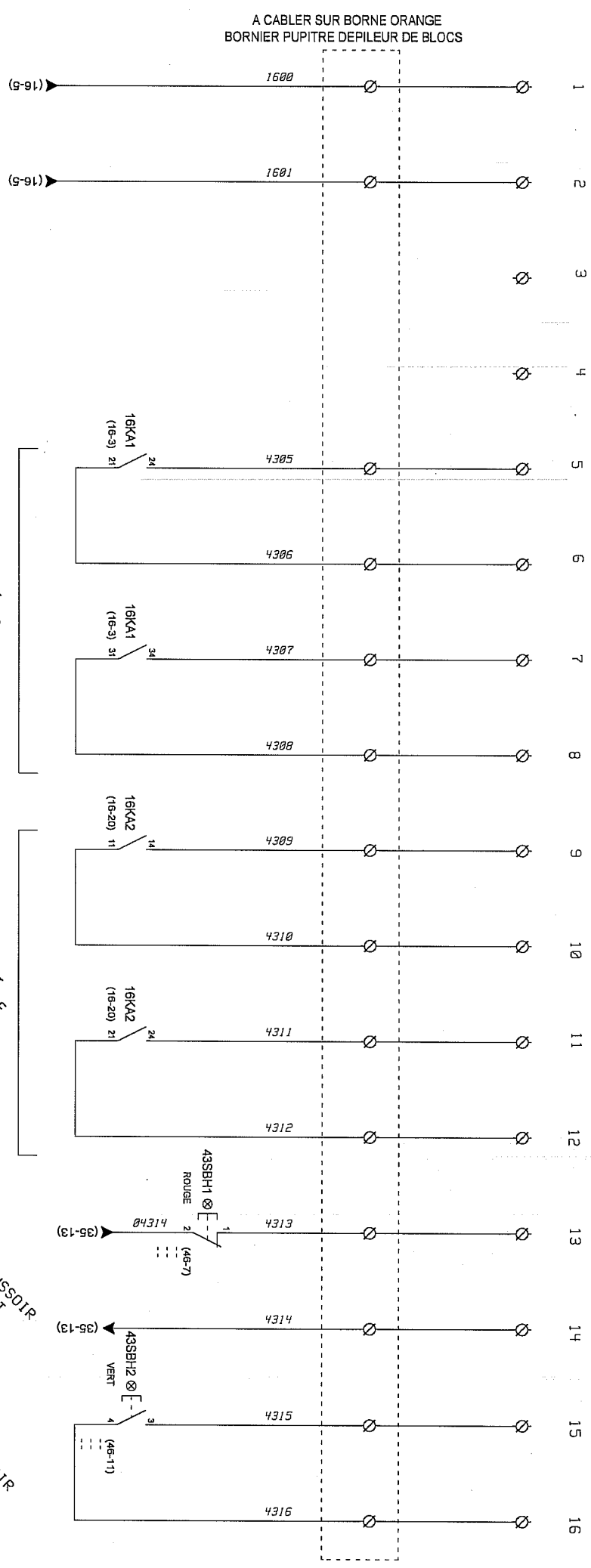
0V5

MOTOMAN X10

connecteur harting

de X10 vers X18

X5.1 X5.2 X5.23 X5.24



SECURITE
GRILLES

ARRET
D'URGENCE

BOUTON POUSSOIR
ARRET ROBOT

BOUTON POUSSOIR
SERVO ON

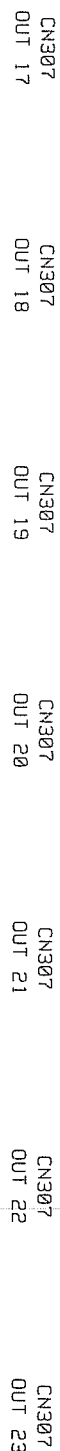
A CABLER SUR BORNE ORANGE
BORNIER PUPITRE DEPILEUR DE BLOCS

BT
ARRET D'URGENCE
TELECOMMANDE ROBOT MOTOMAN

X12-A



CN306	CN306	CN306	CN306
-------	-------	-------	-------

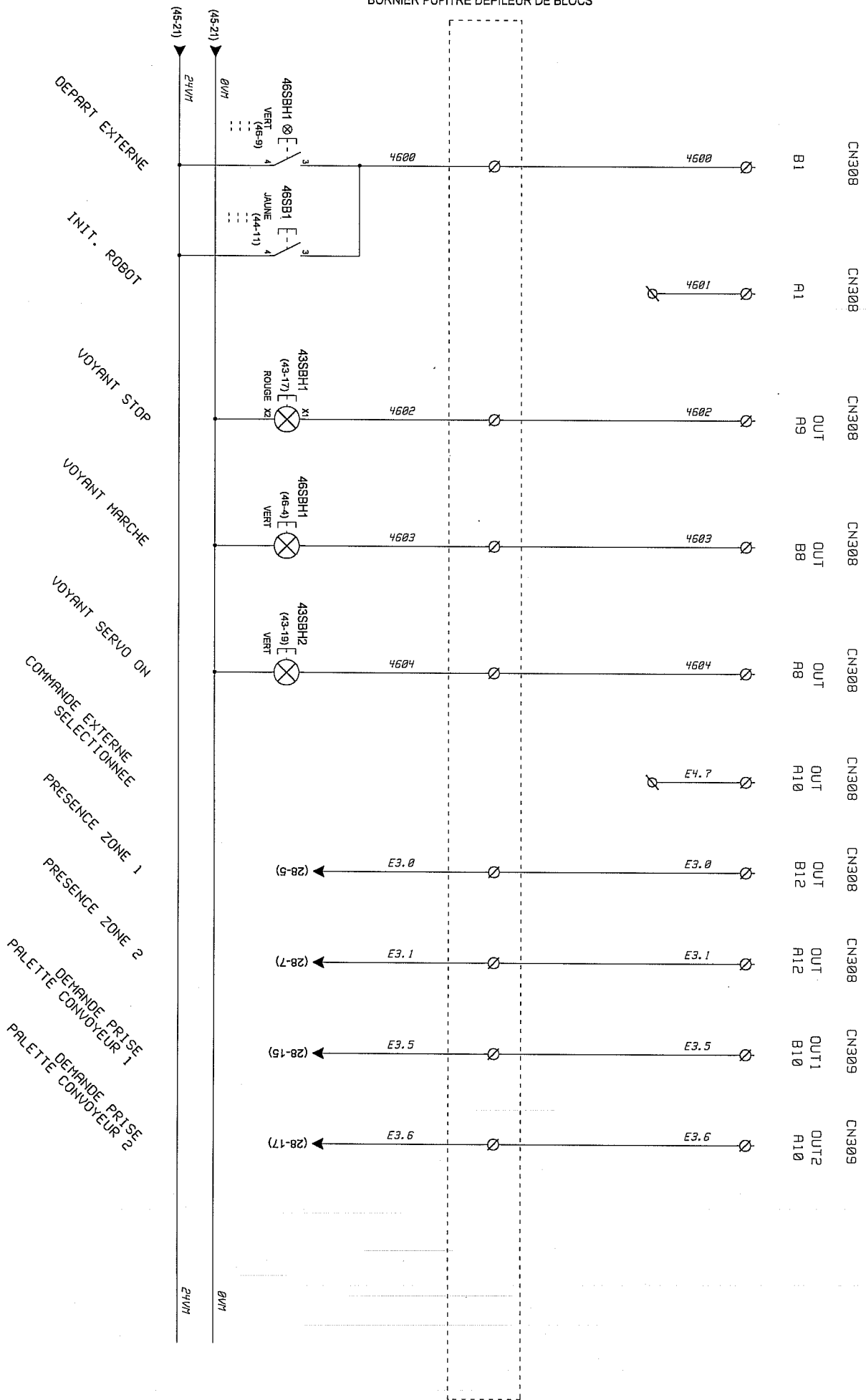


0005	SOEENE			45 / 30
C:\SEE ELECTRICAL EXPER\MACHINE\PALETTE\ROBOT DEPIEUR DE BLOCS\PA078 SACCHI PALETS\IATONS				28-04-2011

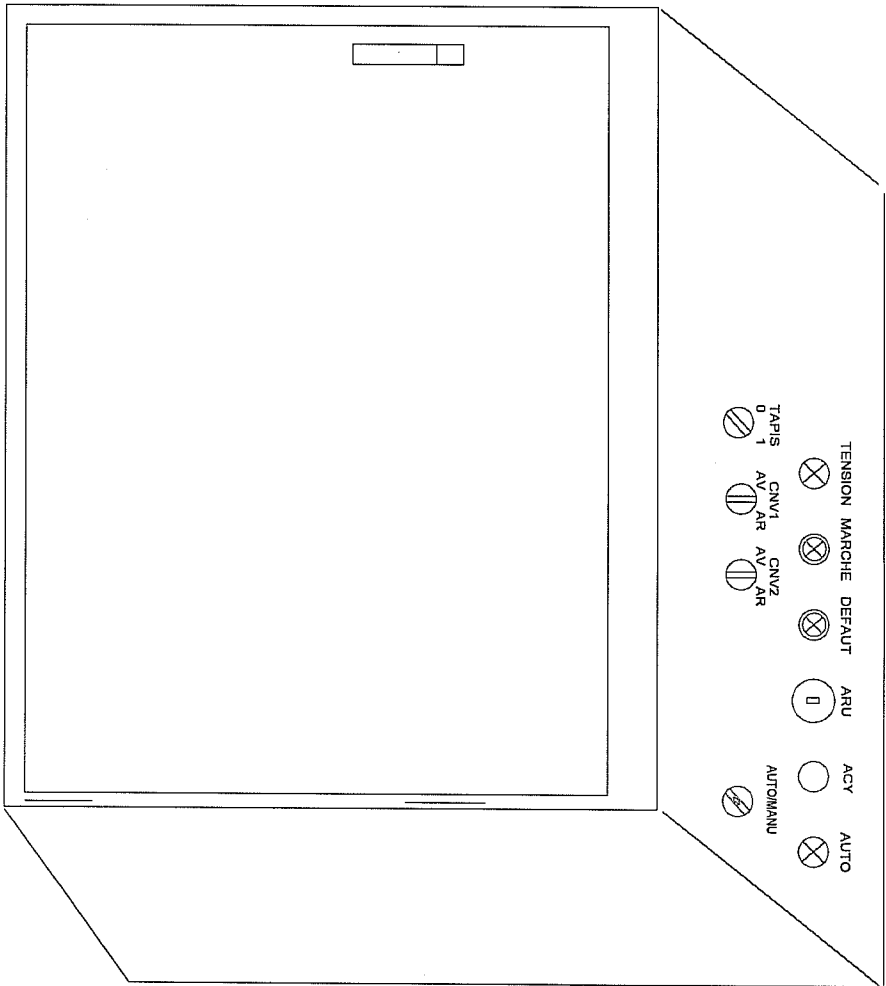
28-04-2011	45	30
------------	----	----

MOTOMAN

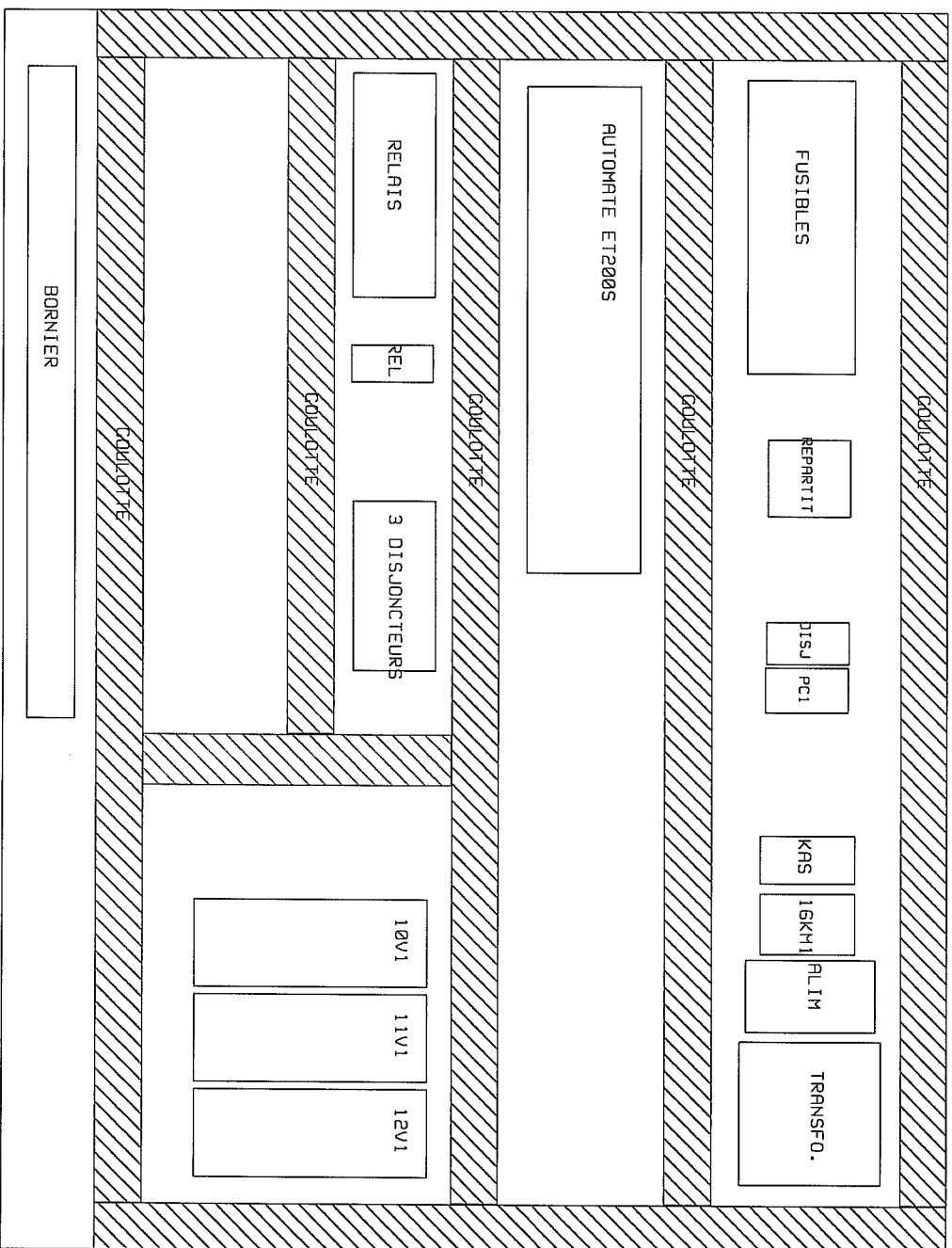
A CABLER SUR BORNES ORANGE
BORNIER PUPITRE DEPILEUR DE BLOCS



IMPLANTATION ARMOIRE



IMPLANTATION ARMOIRE



PARAMETRES DU VARIATEUR 10V1
VITESSE CONVOYEUR 1 SK - 2T

PARAMETRES	VALEUR	PARAMETRES	VALEUR
01	0.0	25	0
02	50HZ	27	0
03	0.5	28	no
04	0.5	29	no
05	A1-RU	30	1
06	2.70	31	1
07	1500 tr/min	32	OFF
08	400	33	0
09	0.85	34	d19
10	L2	35	n=0
11	0	36	FR
12	d15	37	3
15	1.5	38	0
16	4-20mA	39	50HZ
17	OFF	40	AUTO
18	0.0	41	U-1
19	0.0	42	3.0
20	0.0	43	19.2
21	0.0	44	1
22	LD	45	1.08
23	FR	55	VV
24	1.00	56	notr

PARAMETRES DU VARIATEUR 11V1
VITESSE CONVOYEUR 2 SK - 2T

PARAMETRES	VALEUR	PARAMETRES	VALEUR
01	0.0	25	0
02	50HZ	27	0
03	0.5	28	no
04	0.5	29	no
05	A1-RU	30	1
06	2.70	31	1
07	1500 tr/min	32	OFF
08	400	33	0
09	0.85	34	d19
10	L2	35	n=0
11	0	36	FR
12	d15	37	3
15	1.5	38	0
16	4-20mA	39	50HZ
17	OFF	40	AUTO
18	0.0	41	U-1
19	0.0	42	3.0
20	0.0	43	19.2
21	0.0	44	1
22	LD	45	1.08
23	FR	55	VV
24	1.00	56	notr

PARAMETRES DU VARIATEUR 12V1
VITESSE TAPIS BLOCS SK - 2T

PARAMETRES	VALEUR	PARAMETRES	VALEUR
01	0.0	25	0
02	50HZ	27	0
03	0.5	28	no
04	0.5	29	no
05	A1-RU	30	1
06	2.70	31	1
07	1500 tr/min	32	OFF
08	400	33	0
09	0.85	34	d19
10	L2	35	n=0
11	0	36	FR
12	d15	37	3
15	1.5	38	0
16	4-20mA	39	50HZ
17	OFF	40	AUTO
18	0.0	41	U-1
19	0.0	42	3.0
20	0.0	43	19.2
21	0.0	44	1
22	LD	45	1.08
23	FR	55	VV
24	1.00	56	notr

PNEUMATIQUE ZONE ROBOT 6 AXES

